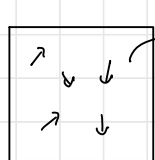


Introduction

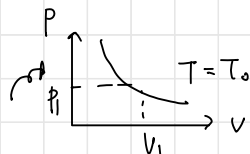
Thermodynamics: Transformations between heat and work relationships between macroscopic properties of a macroscopic system.



$$\begin{cases} \dot{g}_i = \frac{\partial H}{\partial p_i} \\ \dot{p}_i = -\frac{\partial H}{\partial g_i} \end{cases}$$

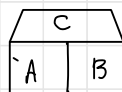
$$N \gg 1$$

Thermodynamic System: Large numbers of particles



⇒ It obeys Thermodynamic Laws

0th Law: Thermal equilibrium → Definition of temperature



1st Law: Conservation of Energy → Form of a transition

$$T_A = T_C \Rightarrow T_A = T_B$$

$$T_B = T_C$$

$$\Delta U = Q + W \quad \text{with } W = \pm p dV \text{ (work done by a system)}$$

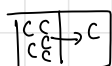
$$Q = \text{Heat observed by a system}$$

2nd Law: Entropy $\Delta S \geq 0$ for an isolated system

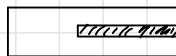
$$\Delta S = \frac{\Delta Q}{T} \quad \text{열의 평형 } T.$$

(*) Historical Development.

- 1824, Carnot heat engine: Engine Limitation of Performance
- Misconcept of theory: Heat Particle, Caloric (열소)의 fluid론 이해.



→ Thompson's Cannon Drilling



- 1842, Mayer: Heat & work thm
- 1850, Clausius, kelvin: classical thermodynamics
- Atomic approach: Desire to explain in microscopic scale
 - 1859, Maxwell
 - 1872, Boltzmann ... $\approx 10^{23}$

Gibbs
Boltzmann
] → Probabilistic approach
→ Statistical mech.

→ kinetic theory

I. Preliminary Probability Theory

1. Definition and Simple Properties

Let $X \rightarrow S = \{x_1, x_2, \dots, x_n\}$ and $E \subset S$ ($E = \text{events}$) ↗ S 의 카이집합

Then, Probability of the event $P(E)$ can be defined as

- Objective (Experimental) way : $P(A) = \lim_{N \rightarrow \infty} \frac{NA}{N}$
- Subjective (Theoretical) way : Lack of information (Uncertainty)
→ Theoretical Estimate.

집합이론에 의거, 다음 성질들이 성립한다.

$$P(A \cup B) = P(A) + P(B) - P(A \cap B) \xrightarrow{\text{mutually exclusive}} P(A) + P(B)$$

$$P(B|A) = \frac{P(A, B)}{P(A)} \longrightarrow P(A \cap B) = P(A)P(B) \quad (\text{independence})$$

아가 일어났을 때
B가 일어날 확률

$$\Rightarrow P(A|B) = \frac{P(A)}{P(B)} P(B|A)$$

$$\Rightarrow P(B) = \sum_{i=1}^n P(A_i) P(B|A_i) \quad (\text{When } A_i \text{ are mutually exclusive})$$

$$\cdot \text{Permutation (Order-dependence)} = {}_n P_k = \frac{n!}{(n-k)!}$$

↗ Binomial Coefficient

$$\cdot \text{Combination (Order-Independence)} = {}_n C_k = \binom{n}{k} = \frac{n!}{(n-k)! k!}$$

(*) Sort of Probability

① Discrete Probability Distribution

$X \rightarrow x_i$ with P_i

$$\begin{cases} \sum_i P_i = 1 \\ \langle X \rangle = \sum x_i P_i \\ \langle f(X) \rangle = \sum f(x_i) P_i \end{cases} \quad (\text{Mean, Expectation, Average})$$

② Continuous Prob Distributions

$$\underbrace{P(x)dx}_{\text{density}} = \text{Prob s.t. } E \in [x, x+dx] \quad \begin{cases} \int P(x) dx = 1 \\ \langle x \rangle = \int dx \cdot x P(x) \\ \langle f(x) \rangle = \int dx \cdot f(x) P(x) \end{cases}$$

(*) Variance (Dispersion, mean-squared deviation)

$x - \langle x \rangle \equiv$ Deviation from the mean value.

$$\Rightarrow \langle x - \langle x \rangle \rangle = \langle x \rangle - \langle x \rangle = 0 \quad (\because \text{Positive \& negative deviation cancel})$$

$$\therefore \sigma_x^2 \equiv \langle (x - \langle x \rangle)^2 \rangle = \langle x^2 - 2x\langle x \rangle + \langle x \rangle^2 \rangle = \langle x^2 \rangle - \langle x \rangle^2$$

$$\rightarrow \sigma_x \equiv \sqrt{\langle (x - \langle x \rangle)^2 \rangle} \quad (\text{Standard Deviation, RMS})$$

(*) Definition of n th moment

$$\mu_n \equiv \langle x^n \rangle = \int dx \cdot x^n P(x)$$

$$\hookrightarrow \sigma^2 = \begin{cases} \sum_j (x_j - \langle x \rangle)^2 P_j \\ \int_{-\infty}^{\infty} (x - \langle x \rangle)^2 P(x) dx \end{cases}$$

(*) Linear Transform

$$\text{if } y = ax + b \quad (a, b = \text{const})$$

$$\textcircled{1} \langle y \rangle = a \cdot \langle x \rangle + b.$$

$$\textcircled{2} \langle y^2 \rangle = \langle a^2 x^2 + 2abx + b^2 \rangle = a^2 \langle x^2 \rangle + 2ab \langle x \rangle + b^2.$$

$$\langle y \rangle^2 = a^2 \langle x \rangle^2 + 2ab \langle x \rangle + b^2$$

$$\Rightarrow \sigma_y^2 = \langle y^2 \rangle - \langle y \rangle^2 = a^2 \cdot (\langle x^2 \rangle - \langle x \rangle^2) = a^2 \cdot \sigma_x^2 \quad \sigma_y = a \sigma_x$$

$$\begin{aligned} \text{for continuous variable, } \langle y \rangle &= \int_{-\infty}^{\infty} y \underbrace{g(y)}_{\text{Same}} dy = \int_{-\infty}^{\infty} (ax+b) \underbrace{f(x)}_{\text{Same}} dx \\ &= a \cdot \langle x \rangle + b. \quad \sigma_y^2 = \int_{-\infty}^{\infty} [y - (a\langle x \rangle + b)]^2 g(y) dy = a^2 \sigma_x^2. \end{aligned}$$

$$\text{cf) Chebyshev inequality} \quad P(|x - \langle x \rangle| \geq k\sigma) \leq \frac{1}{k^2}$$

2. Binomial Distribution

Prob distbn of getting k heads of N independent Bernoulli trials

$$P_N(k) = \binom{N}{k} p^k q^{N-k} = \binom{N}{k} p^k (1-p)^{N-k} \quad (\text{Repeated Individual})$$

$\Rightarrow$ By binomial expansion, $(x+y)^N = \sum_{k=0}^N \binom{N}{k} x^k y^{N-k}$ or all $x=p, y=q$ ($p+q=1$)

$$= \sum P_N(k) = 1 \quad (\text{makes sense})$$

① Mean $\langle k \rangle = \sum_{k=0}^N k \cdot P_N(k) = \sum_{k=0}^N \binom{N}{k} k \cdot p^k \cdot q^{N-k}$

$$= p \cdot \frac{\partial}{\partial p} \sum_{k=0}^N \binom{N}{k} p^k q^{N-k} = \left(p \cdot \frac{\partial}{\partial p} \right) p^N$$

$$= p \cdot \frac{\partial}{\partial p} (p+q)^N = p \cdot N \cdot (p+q)^{N-1} = NP \quad \therefore \langle k \rangle = NP$$

② Variance : $\sigma_k^2 = \langle k^2 \rangle - \langle k \rangle^2$

$$\langle k^2 \rangle = \sum_{k=0}^N k^2 \cdot P_N(k) = \sum_{k=0}^N \binom{N}{k} k^2 p^k q^{N-k} = \left(p^2 \frac{\partial^2}{\partial p^2} + p \frac{\partial}{\partial p} \right) (p+q)^N$$

$$= \left(p^2 \cdot \frac{\partial^2}{\partial p^2} + p \frac{\partial}{\partial p} \right) p^N$$

$$= N(N-1)p^2 + NP = N^2 p^2 - Np^2 + NP = N^2 p^2 + NP(1-p)$$

$$\Rightarrow \sigma_k^2 = N^2 p^2 + NP(1-p) - N^2 p^2 = NPq \quad \sigma_k = \sqrt{NPq}$$

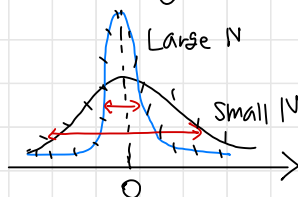
③ Relative width $\equiv \frac{\sigma_k}{\langle k \rangle} = \frac{\sqrt{NPq}}{NP} \sim \frac{1}{\sqrt{N}} \xrightarrow{N \gg 1} 0$

(*) Sterling's Approximation for very large N ($\sim 10^{23}$)

$$n! = \int_0^\infty x^n e^{-x} dx \quad (\text{Gamma function})$$

$$e^{f(x)} = e^{n \ln x - x} \quad f(x) = n \cdot \ln x - x$$

(분포의 극한 증명)



Sharp Peaks

to determine x^* , $f'(x) \Big|_{x^*} = \left(\frac{n}{x} - 1 \right) \Big|_{x^*} = 0 \therefore x^* = n$.

and, $f''(x) = -\frac{n}{x^2}$ or $f''(x^*) = -\frac{1}{n} < 0$.

Taylor expand, $f(x) \cong f(x^*) + f'(x^*)(x-x^*) + \frac{f''(x^*)}{2!}(x-x^*)^2$
 $= (n \cdot \ln n - n) + 0 \cdot (x-n) - \frac{1}{2n} \cdot (x-n)^2 \quad (\because x^* = n) \quad (\text{up to 2nd order})$

$\Rightarrow n! \cong \int_0^\infty e^{n \ln n - n - \frac{(x-n)^2}{2n}} dx = e^{n \ln n - n} \int_{-\infty}^\infty e^{-\frac{(x-n)^2}{2n}} dx$

$\therefore n! \cong \sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n$ for large n . $= \sqrt{2\pi n}$, Gaussian

$\Leftrightarrow \ln n! = n \cdot \ln n - n + \frac{1}{2} \ln(2\pi n) \cong \boxed{n \cdot \ln n - n}$ Integration

(*) From Binomial to Gaussian

$P_N(k)$ for large enough N , $\ln P_N(k) = \ln N! - \ln(N-k)! + k \ln p - (N-k) \ln q$.
 $-\ln k!$

By using Stirling approximation,

$\ln P_N(k) \cong (N \cdot \ln N - N) - [(N-k) \ln(N-k) - (N-k)] + k \ln p + (N-k) \ln q - k \ln k + k$
 $\rightarrow$ $\frac{1}{2} \ln(2\pi k)$ 을 기리는 k^* 값을 근대보자

$\frac{\partial}{\partial k} \ln P(k) \Big|_{k^*} = -\ln k - 1 + \ln(N-k) + 1 + \ln p - \ln q \Big|_{k^*} = 0$

$\therefore (N-k^*)p = k^*q \quad k^*(p+q) = NP = \langle k \rangle \quad \langle k \rangle = k^*$

then, $\frac{\partial^2}{\partial k^2} \ln P(k) \Big|_{k^*} = -\frac{1}{k} - \frac{1}{N-k} \Big|_{k^* = \langle k \rangle} = -\frac{N-k+k}{k(N-k)}$
 $= \frac{-N}{NP(N-Np)} = \frac{-1}{NP(1-p)} = \frac{-1}{NPq} = -\frac{1}{6k^2}$

$\xrightarrow{\text{Taylor expansion}} \ln P(k) \cong \ln P(k^*) + 0 \cdot (k-k^*) + \frac{1}{2!} \left(-\frac{1}{6k^2} \right) (k-k^*)^2$

∴ $P_N(k) \approx C_1 \cdot e^{-\frac{1}{2\sigma^2} \cdot (k - \langle k \rangle)^2}$ 확률 분포론에 의해 C를 구하면

$$\sum P_N(k) \rightarrow \int_0^\infty dk \cdot P(k) = \int_0^\infty dk P(k) = \int_{-\infty}^\infty dk \cdot C \cdot e^{-\frac{(k - \langle k \rangle)^2}{2\sigma^2}} = 1$$

$$\therefore C = \frac{1}{\sqrt{2\pi\sigma^2}}$$

→ Gaussian Int. = $\sqrt{2\pi\sigma^2}$

$$P_N(k) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(k - \langle k \rangle)^2}{2\sigma^2}} : \text{for large } N, \text{ 이항 분포를 가우스 분포로 근사 가능하다.}$$

<Summary>

$P(x)dx$: Probability of events

$\langle x \rangle$: Expectation value

$$\sigma^2 \equiv \langle (x - \langle x \rangle)^2 \rangle = \langle x^2 \rangle - \langle x \rangle^2$$

Binomial Distribution $\xrightarrow{N \gg 1}$ Gaussian Distrib

$$\Rightarrow P_N(k) = \binom{N}{k} p^k q^{N-k}$$

$$P(k) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(k - \langle k \rangle)^2}{2\sigma^2}}$$

ex) Coin toss HTTH

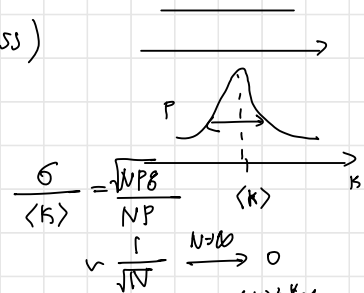
as $\bar{k} = \mu = NP$

$$P_4(2) = \binom{4}{2} \left(\frac{1}{2}\right)^4$$

$$\sigma^2 = NPq$$

$\Rightarrow$ for sequence $p^k \cdot q^{N-k} = p^N$ for "unbiased" events (Randomness)

$\Rightarrow$ for Given composition (ex: $k=2$) neglecting "sequence" events can be predictable



So, $\langle k \rangle$ 에서 sharp 해지니 다른 event 무시 가능.

3. Moments & Cumulants

By definition, n th moment of variable x from the origin is $\mu_n = \langle x^n \rangle = \int dx \cdot x^n P(x)$

But, Integration is complex... Let's introduce convenient skill

(*) Characteristic function ~~and~~ moment generating function cf) $\tilde{P}(k) =$

Def) $\tilde{P}(k) = \langle e^{-ikx} \rangle = \int dx \cdot e^{-ikx} \cdot P(x)$ (2) $e^{(-ikx)} = 1 + \sum \frac{(-ikx)^n}{n!}$

$$= \int dx \cdot \sum_{n=0}^{\infty} \frac{(-ik)^n}{n!} x^n P(x)$$

$$= \sum_{n=0}^{\infty} \frac{(-ik)^n}{n!} \cdot \underbrace{\int dx \cdot x^n P(x)}_{\mu_n}$$

$$\Rightarrow \left. \frac{\partial \tilde{P}(k)}{\partial k^n} \right|_{k=0} = (-i)^n \cdot \mu_n$$

$\therefore \mu_n = i^n \cdot \left. \frac{\partial^n \tilde{P}(k)}{\partial k^n} \right|_{k=0}$

 $\left(\because \frac{1}{(-i)^n} = \frac{i^n}{i^{2n}} \right)$

$$\hookrightarrow = \left(-\frac{\partial}{\partial k} \right)^n \tilde{P}(k) \Big|_{k=0}$$

(*) Cumulant generating function

Def) $\ln \tilde{P}(k) = \ln \langle e^{-ikx} \rangle = \sum_{n=1}^{\infty} \frac{(-ik)^n}{n} \cdot \langle x^n \rangle_c \equiv \text{cumulant} \langle x^n \rangle_c$

then, 특성함수의 정리에 의해 $\langle x^n \rangle_c = (-i)^n \cdot \left. \frac{\partial^n}{\partial k^n} [\ln \tilde{P}(k)] \right|_{k=0}$ 가 된다.

$$\textcircled{1} \langle x \rangle_c = i \cdot \frac{\partial}{\partial k} \cdot \ln \tilde{P}(k) \Big|_{k=0} = i \cdot \frac{1}{\tilde{P}(k)} \cdot \frac{\partial \tilde{P}}{\partial k} \Big|_{k=0}$$

$$= \frac{1}{\tilde{P}(0)} \cdot \mu_1 = \mu_1 = \langle x \rangle \quad \therefore \langle x \rangle_c = \langle x \rangle$$

Mean

$$(\because \tilde{P}(0) = \langle e^0 \rangle = \langle 1 \rangle = 1)$$

$$\textcircled{2} \langle x^2 \rangle_c = i^2 \cdot \frac{\partial^2}{\partial k^2} \cdot \ln \tilde{P}(k) \Big|_{k=0} = i^2 \left[\frac{1}{\tilde{P}(k)} \frac{\partial^2 \tilde{P}(k)}{\partial k^2} - \frac{1}{(\tilde{P}(k))^2} \left(\frac{\partial \tilde{P}}{\partial k} \right)^2 \right]_{k=0}$$

$$= \mu_2 - \mu_1^2 = \langle x^2 \rangle - \langle x \rangle^2 = \sigma^2 \quad \therefore \langle x^2 \rangle_c = \sigma^2$$

Variance

$$\textcircled{3} \langle x^3 \rangle_c = \tilde{z}^3 \cdot \frac{\partial^3}{\partial k^3} \ln \tilde{p}(k) \Big|_{k=0}$$

$$= \tilde{z}^3 \left[\frac{1}{\tilde{p}(k)} \cdot \frac{\partial^3 \tilde{p}(k)}{\partial k^3} - \frac{1}{(\tilde{p}(k))^2} \left(\frac{\partial \tilde{p}}{\partial k} \right) \left(\frac{\partial^2 \tilde{p}}{\partial k^2} \right) + \frac{2}{(\tilde{p}(k))^3} \left(\frac{\partial \tilde{p}}{\partial k} \right)^2 \right. \\ \left. - \frac{1}{(\tilde{p}(k))^2} \cdot 2 \left(\frac{\partial \tilde{p}}{\partial k} \right) \left(\frac{\partial^2 \tilde{p}}{\partial k^2} \right) \right] \Big|_{k=0} \quad \begin{matrix} -144 \\ -244 \end{matrix}$$

($\tilde{z}^3$ 을 각 미분항에 붙여줘야 함)

$$= \mu_3 - 3 \cdot \mu_1 \mu_2 + 2 \mu_1^3 = \langle x^3 \rangle - 3 \langle x \rangle \langle x^2 \rangle + 2 \langle x \rangle^3$$

Skewness

(Useful skill, Diagrammatic representation)

nth Cumulant $\langle x^n \rangle_c$: Cluster connected among n points

nth moment $\langle x^n \rangle$: All possible ways of distributing n points into smaller clusters

(ex)

(n=1) $\cdot \quad \langle x^1 \rangle = \langle x^1 \rangle_c$ ↙ diagram $\Rightarrow \langle x^2 \rangle_c = \langle x^2 \rangle - \langle x \rangle^2$

(n=2) $\text{---} \cdot + \cdot \cdot \Rightarrow \langle x^2 \rangle = \langle x^2 \rangle_c + \langle x^1 \rangle_c \langle x^1 \rangle_c$

(n=3) $\triangle + \left(\begin{array}{c} \text{---} \cdot \\ | \\ \text{---} \cdot \\ | \\ \text{---} \cdot \end{array} \right) + \cdot \cdot \Rightarrow \langle x^3 \rangle = \langle x^3 \rangle_c + 3 \cdot \langle x^2 \rangle_c \langle x^1 \rangle_c + \langle x^1 \rangle_c^3$
 $= \langle x^3 \rangle_c + 3 \cdot [\langle x^2 \rangle - \langle x \rangle^2] \langle x \rangle + \langle x \rangle^3$
 $\therefore \langle x^3 \rangle_c = \langle x^3 \rangle - 3 \langle x^2 \rangle \langle x \rangle + 2 \langle x \rangle^3$

After $n=4, 5, 6, \dots$ go on. $\langle x^4 \rangle = \langle x^4 \rangle_c + 4 \cdot \langle x^3 \rangle_c \langle x^1 \rangle_c + 6 \cdot \langle x^2 \rangle_c \langle x^1 \rangle_c^2 + \langle x^1 \rangle_c^4 + 6 \cdot \langle x^2 \rangle_c^2$

$\square \quad \text{---} \cdot \quad | \quad : \quad : \quad : \Rightarrow \langle x^4 \rangle_c = \langle x^4 \rangle - 4 [\langle x^3 \rangle - 3 \langle x^2 \rangle \langle x \rangle + 2 \langle x \rangle^3] \langle x \rangle$
 $- 6 \cdot (\langle x^2 \rangle - \langle x \rangle^2) \langle x \rangle^2 - \langle x \rangle^4 - 3 (\langle x^2 \rangle - \langle x \rangle^2)^2$
 $= \langle x^4 \rangle - 4 \langle x^3 \rangle \langle x \rangle + 12 \langle x^2 \rangle \langle x \rangle^2 - 8 \langle x \rangle^4$
 $- 6 \cdot \langle x^2 \rangle \langle x \rangle^2 + 6 \langle x \rangle^4 - \langle x \rangle^4 - 3 \langle x^2 \rangle^2 + 6 \langle x^2 \rangle \langle x \rangle^2 - 3 \langle x \rangle^4$

①

④

⑥

①

1 1 ③

4. Several Random Variables

(*) Joint Probability Distribution: $P(x_1, x_2, \dots, x_N) dx_1 \dots dx_N = \text{Prob} [E \in [\vec{x}, \vec{x} + d\vec{x}]]$ o.k.

Joint Characteristic function $\equiv \tilde{P}(k_1, k_2, \dots, k_N) = \langle e^{-i(k_1 x_1 + k_2 x_2 + \dots + k_N x_N)} \rangle$

$$= \int \prod_{\alpha=1}^N dx_{\alpha} e^{-i k_{\alpha} x_{\alpha}} \cdot P(x_1, x_2, \dots, x_N)$$

$$\textcircled{1} \text{ Joint moment } \langle x_1^{m_1} x_2^{m_2} \dots x_N^{m_N} \rangle = \int \prod_{\alpha=1}^N dx_{\alpha} \cdot x_{\alpha}^{m_{\alpha}} P(x_1, x_2, \dots, x_N)$$

$$= \left(-\frac{\partial}{\partial (i k_1)} \right)^{m_1} \left(-\frac{\partial}{\partial (i k_2)} \right)^{m_2} \dots \left(-\frac{\partial}{\partial (i k_N)} \right)^{m_N} \tilde{P}(k_1, \dots, k_N) \Big|_{\vec{k}=0}$$

② Joint Cumulant by symmetry,

$$\langle x_1^{m_1} x_2^{m_2} \dots x_N^{m_N} \rangle_c = \left(-\frac{\partial}{\partial (i k_1)} \right)^{m_1} \dots \left(-\frac{\partial}{\partial (i k_N)} \right)^{m_N} \ln \tilde{P}(k_1, \dots, k_N) \Big|_{\vec{k}=0}$$

(*) Statistical Independency

$$\text{Def) } P_N(x_1, x_2, \dots, x_N) = P_1(x_1) P_2(x_2) \dots P_N(x_N)$$

$$\begin{aligned} \langle f(x_1) g(x_2) \rangle &= \int dx_1 dx_2 f(x_1) g(x_2) P(x_1, x_2) \quad \text{only, if } x_1, x_2 \text{ is statistically independent,} \\ &= \int dx_1 dx_2 f(x_1) P(x_1) g(x_2) P(x_2) = \langle f(x_1) \rangle \langle g(x_2) \rangle \end{aligned}$$

So, under the same condition, the characteristic function becomes

$$\begin{aligned} \Rightarrow \tilde{P}(k_1, \dots, k_N) &= \int \prod_{\alpha=1}^N dx_{\alpha} e^{-i k_{\alpha} x_{\alpha}} \underbrace{P(x_1, \dots, x_N)}_{= \prod_{\alpha=1}^N P_{\alpha}(x_{\alpha})} \\ &= \prod_{\alpha=1}^N \int dx_{\alpha} e^{-i k_{\alpha} x_{\alpha}} P_{\alpha}(x_{\alpha}) \\ &= \prod_{\alpha=1}^N \tilde{P}_{\alpha}(k_{\alpha}) \end{aligned}$$

$$\text{Similarly, } \langle x_1^{m_1} x_2^{m_2} \dots x_N^{m_N} \rangle = \langle x_1^{m_1} \rangle \langle x_2^{m_2} \rangle \dots \langle x_N^{m_N} \rangle$$

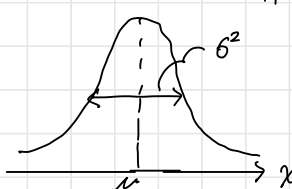
But, Cumulant became little bit different.

$$\langle x_1^{m_1} x_2^{m_2} \dots x_N^{m_N} \rangle_c = \left(-\frac{\partial}{\partial i k_1} \right)^{m_1} \dots \left(-\frac{\partial}{\partial i k_N} \right)^{m_N} \sum_{\alpha=1}^N \ln \tilde{P}_\alpha(k_\alpha)$$

$$= 0 \text{ for any } m_i \cdot m_j \neq 0. \quad (\because \ln P_1 P_2 \dots P_N = \ln P_1 + \ln P_2 + \dots)$$

(*) Moments / Cumulants of Gaussian distribution

(P.D.F) $P(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{(x-\mu)^2}{2\sigma^2}}$



(Characteristic Function) $\tilde{P}(k) = \langle e^{-ikx} \rangle = \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{\infty} dx e^{-ikx - \frac{(x-\mu)^2}{2\sigma^2}} \quad (x-\mu = y)$

$$= \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{\infty} dy e^{-\frac{y^2}{2\sigma^2} - ik y - ik\mu} \left(\int_{-\infty}^{\infty} dy e^{-\frac{1}{2\sigma^2} (y + \sigma^2 ik)^2} = 1 \text{ or } \sqrt{2\pi\sigma^2} \right)$$

$$= e^{-ik\mu - \frac{\sigma^2 k^2}{2}}$$

$\therefore \ln \tilde{P}(k) = -ik\mu - \frac{\sigma^2 k^2}{2}$ 이다. 즉, 이 Cumulant generating function은 μ 와 σ^2

$$\langle x^1 \rangle_c = -\frac{\partial}{\partial (ik)} \ln \tilde{P}(k) \Big|_{k=0} = \mu = \langle x^1 \rangle$$

$$\langle x^2 \rangle_c = \frac{\partial^2}{\partial k^2} \left(\frac{\sigma^2 k^2}{2} \right) = \sigma^2. \quad \text{이(2), } \ln \tilde{P}(k) \text{의 } k \text{에 대한 2차항이 2이므로}$$

$$= \langle x^2 \rangle - \langle x \rangle^2. \quad (\because \text{cumulant-moment relation})$$

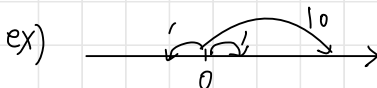
$$\langle x^n \rangle_c = 0 \text{ for } n > 2. \quad \therefore \text{Mean} = \mu, \text{ Variance} = \sigma^2 \text{ 인 distribution 이 된다.}$$

→ Gaussian distribution의 중요한 성질. | - | mapping으로 이 성질을 가진 분포를 대응시킬 것.

(*) for arbitrary Gaussian, $\int_{-\infty}^{\infty} e^{-a(x+b)^2} dx = \sqrt{\frac{\pi}{a}}$

5. Probability Distribution for Large N: Central limit theorem

(*) $X = \sum_i^N x_i$ variable



after N step, final displacement?

$P(X) = \int \dots \int P(x_1, \dots, x_N) dx_1 \dots dx_N$

$X = \sum x_i \rightarrow$ constraint

cf) $\int_{-\infty}^{\infty} \delta(x) dx = 1$

$$\int P(X) \delta(X - \sum x_i) dX = \int \dots \int_{X=-\infty}^{X=+\infty} dx_1 \dots dx_N \cdot \underbrace{P(x_1, x_2, \dots, x_N)}_{\text{Independence}} \cdot \underbrace{\delta(X - \sum x_i)}_{= \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ik(X - \sum x_i)}} dX$$

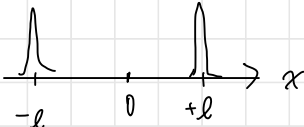
$P(X)$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikX} \cdot \int \dots \int (dx_1 e^{-ikx_1} P(x_1)) (dx_2 e^{-ikx_2} P(x_2)) \dots \text{(up to N-term)}$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikX} \cdot (\tilde{P}_1(k) \tilde{P}_2(k) \dots \tilde{P}_N(k)) = (\tilde{P}(k))^N$$

이때 $\tilde{P}(k)$ 의 형태 보면

(ea) 여러 상황의 Probability Distribution을 구해봅시다. (P for +l, g for -l after N step, distribution!)

(P.D.F) $p(x) = p \cdot \delta(x-l) + g \delta(x+l)$ 이다. 

($\because P(+l-\epsilon, +l+\epsilon) = \int_{l-\epsilon}^{l+\epsilon} P(x) dx = P.$)

Then, $(\tilde{P}(k))^N = \langle e^{-ikx} \rangle^N = (e^{-ikl} \cdot p + e^{ikl} \cdot g)^N \rightarrow \text{Binomial Polynomial}$

$$= \sum_{n=0}^{\infty} \binom{N}{n} p^n g^{N-n} e^{-n \cdot ikl + (N-n) \cdot ikl} = (N-2n) \cdot ikl$$

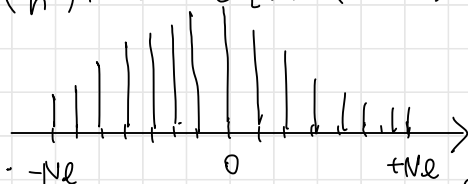
$$P(X) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikX} \cdot \sum_{n=0}^{\infty} \binom{N}{n} p^n g^{N-n} e^{-(2n-N)ikl}$$

$$= \frac{1}{2\pi} \sum_{n=0}^{\infty} \binom{N}{n} p^n g^{N-n} \int_{-\infty}^{\infty} dk e^{+ik[X - (2n-N)l]} = \delta[X - (2n-N)l]$$

$$\therefore P(X) dX = \sum_{n=0}^{\infty} \binom{N}{n} p^n q^{N-n} \cdot \delta[X - (2n-N)l] dX$$

$$n=0 \quad X = -Nl$$

$$n=N \quad X = Nl$$



$$\Rightarrow X = (2n'-N)l \text{ 이 될 확률 } P(X = (2n'-N)l) = \int_{X=(n'-N)l-\varepsilon}^{X=(2n'-N)l+\varepsilon} P(X) dX$$

$$= \binom{N}{n'} p^{n'} q^{N-n'} \quad (n': \text{Dummy index})$$

$$\therefore P((2n-N)l) = \binom{N}{n} p^n q^{N-n} \quad \text{for otherwise, } P = 0.$$

(ex: $X = (2n-N)l + \frac{l}{2}$)

(*) Central Limit Theorem ($N \gg \gg$)

Consider $X = \sum_{i=1}^N x_i$, then, for random variable X , characteristic function

$$\tilde{P}_X(k) = \langle e^{-ikX} \rangle = \langle e^{-ik \sum_i x_i} \rangle = \langle e^{-ikx_1} \cdot e^{-ikx_2} \cdots e^{-ikx_N} \rangle$$

$$= \sum_{n=0}^{\infty} \frac{(-ik)^n}{n!} \langle X^n \rangle$$

$$\ln \tilde{P}_X(k) = \sum_{n=0}^{\infty} \frac{(-ik)^n}{n!} \langle X^n \rangle_c = \sum_{n=0}^{\infty} \frac{(-ik)^n}{n!} \langle (x_1 + x_2 + \cdots + x_N)^n \rangle_c$$

Let's assume that x_i are statistically independent. Then,

in the cumulant formula, cross terms should disappear (why?)

$$\langle X^n \rangle_c = \langle x_1^n \rangle_c + \langle x_2^n \rangle_c + \cdots + \langle x_N^n \rangle_c = \sum_{i=1}^N \langle x_i^n \rangle_c$$

$\Rightarrow$ (Sum of random variables)의 Cumulant = (random variable)의 Cumulant의 Sum

$\Rightarrow$ 여기에, $x_1, \dots, x_N$ 이 Identical distribution을 가진다고 하자. Independent and Identical distribution

$\Rightarrow$ 이 경우엔 Statistically Independent 조건을 통해서 함께 I.I.D 라고 부른다.

Then, $\langle X^n \rangle_c = N \cdot \langle x^n \rangle_c$ 일 것이다.

$$P(x_1, \dots, x_n) = p(x_1) p(x_2) \dots p(x_n) \\ = P(x_1) P(x_2) \dots P(x_n)$$

Now, Let's introduce $y = \frac{X - \langle X \rangle_c}{\sqrt{N}} = \frac{X - N \langle x \rangle_c}{\sqrt{N}} = \frac{X - N \cdot \langle x \rangle}{\sqrt{N}}$.

It is the Linear transformation of variable X . so, if we calculate Cumulant of y ,

$$\langle y^1 \rangle_c = \frac{\langle X^1 \rangle_c - \langle X^1 \rangle_c}{\sqrt{N}} = 0 \dots \textcircled{1}$$

$$\langle x^3 \rangle_c = \frac{\langle x^3 \rangle_c - \frac{3 \langle x \rangle \langle x^2 \rangle_c + N \langle x \rangle^3}{N^2 \langle x \rangle^2}}{\langle x \rangle} = 0 ?$$

$$\langle y^2 \rangle_c = \frac{\langle X^2 \rangle_c}{N} = \frac{N \langle x^2 \rangle_c}{N} = \langle x^2 \rangle_c \rightarrow \sigma^2 \dots \textcircled{2}$$

? : $\rightarrow$ Intuition : Linear transform 이니, 뒤따라주지 가능. 계산해도 상관없다.

$$\langle y^m \rangle_c = \frac{\langle X^m \rangle_c}{N^{\frac{m}{2}}} = \frac{N \cdot \langle x^m \rangle_c}{N^{\frac{m}{2}}} \sim N^{1 - \frac{m}{2}} \rightarrow 0$$

$$\approx, N \gg 1 \rightarrow \infty \text{ 일 때, } m > 2 \text{ 일 } \begin{cases} \langle y^m \rangle_c = 0 \\ \langle y^1 \rangle_c = 0 \\ \langle y^2 \rangle_c = \sigma^2 \end{cases} \quad \left(\begin{array}{l} \text{for } m > 2 \\ N \rightarrow \infty \end{array} \right)$$

이므로

이 과정에서 y 의 확률분포는 $N(0, \langle x^2 \rangle_c)$ 인 Gaussian distribution이다.

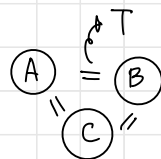
$$P(y) = \frac{1}{\sqrt{2\pi \sigma^2}} e^{-\frac{y^2}{2 \langle x^2 \rangle_c}} \rightarrow N \text{과 관계 } X.$$

따라서, $P(x)$ 가 무엇이든지, $N \rightarrow \infty$ 이면 single variable gaussian으로 변환 가능하다.

$\therefore (N \gg 1)$ $\Rightarrow N$ 의 정확판 값은 몰라도 통계적 분석 가능하다.

II. Classical Thermodynamics

1. The 0th & 1st Law of Thermodynamics



1) 0th Law: The abstract definition of temperature

⇒ If two systems are in thermal equilibrium with a third, the two systems should be in thermal equilibrium each other

definition

⇒ Thermal Contact for a sufficiently long time, and no "net energy" transfer in the stationary state. Then they should have the same physical quantity, specially named: Temperature

definition of thermal contact.

⇒ When the two systems are able to exchange energy while keeping external parameters, they are said to be in thermal contact. $\left(\begin{matrix} T_A = T_C \\ T_B = T_C \end{matrix} \Rightarrow T_A = T_B \right)$

→ The definition of temperature: Ambiguity

Q. How can we define temperature "rigorously"?



2) Statistical Definition of Temperature.

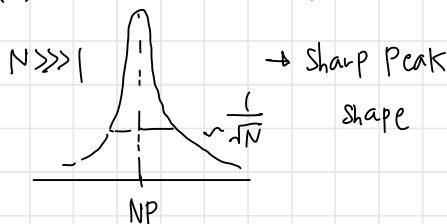
• We will define the temperature through Ω , the number of microstates.

(*) Microscopic states (μ -states)

$N = 100$

H T H H T T ... H T
:
T H H T T H ... H H } Sequences

(*) Macroscopic states (M-states)



Interested in k = number of H = composition

$$\Rightarrow P_N(k) = \binom{N}{k} \cdot p^k \cdot q^{N-k}$$

$= \Omega_N(k)$ = Multiplicity = Density of state

For unbiased, equally Probable

Number of possible configuration = $2^{100} \sim 10^{30}$

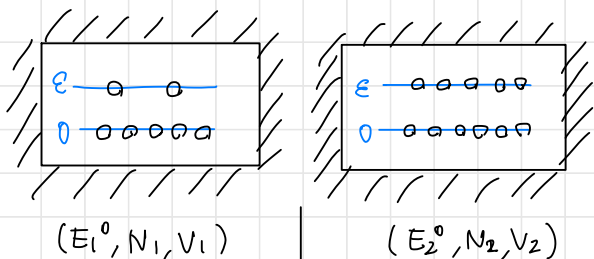
All possible μ -states are equally likely.

(ex) $\frac{P_{1000}(400)}{P_{1000}(500)} \sim 10^{-9}$: Huge difference because of Ω

⇒ From this, we can get the following (Powerful) Postulate, which is true from now on.

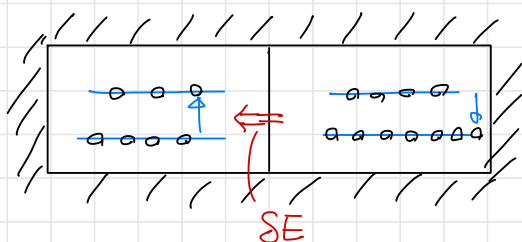
- For a system of **large N** , there is a strong tendency that the system tends to be in Macroscopic state that **maximizes the number of microstates** ($= \Omega$) belonging to that macrostate in **thermal equilibrium**

(*) 이제, 간단한 상황을 통해 Ω 의 성질을 파악하고, 이를 통해 온도를 엄밀하게 정의하자.



- Two M-State systems initially isolated
- For simplicity, only 2-energy level available

make these two thermal contact for sufficiently long time
⇒ Thermal equilibrium



- What value is E_1 ?
- ⇒ We should know $E = k \cdot \epsilon$.

where k = number of particles in the excited state.

- Then, the multiplicity of the system

$$\Omega_N(k) \xrightarrow{\text{Macrovariable}} \Omega_N(E, \cancel{V}, \cancel{N})$$

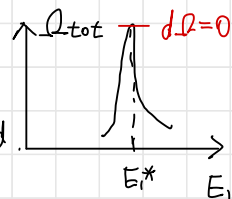
N, V fixed

$$= \Omega(E) \text{ where } E_{\text{tot}} = E_1^0 + E_2^0 = E_1 + E_2 = \text{const.}$$

⇒ By the postulate we have seen, $\Omega_{\text{tot}}(E_{\text{tot}})$ should be maximized.

$$\Rightarrow \Omega_{\text{tot}}(E_{\text{tot}}) = \Omega_1(E_1) \times \Omega_2(E_2) \quad (\because \text{Two independent system, think about the multiplicity: composition})$$

$$= \Omega_1(E_1) \times \Omega_2(E_{\text{tot}} - E_1)$$



Now, we are to find E_1^* , where $d\Omega_{\text{tot}} = 0$

$$\Rightarrow d\Omega_{\text{tot}} = \Omega_2(E_2) \times \frac{\partial \Omega_1(E_1)}{\partial E_1} \cdot dE_1 + \Omega_1(E_1) \times \frac{\partial \Omega_2(E_2)}{\partial E_2} \cdot dE_2$$

$$= \Omega_1(E_1) \cdot \Omega_2(E_2) \cdot \left(\frac{1}{\Omega_1} \cdot \frac{\partial \Omega_1}{\partial E_1} \Big|_{E_1=E_1^*} - \frac{1}{\Omega_2} \cdot \frac{\partial \Omega_2}{\partial E_2} \Big|_{E_2=E_2^*} \right) dE_1 = 0.$$

So, 임의의 E_1 에 대해 항상 이식이 성립하기 위해서

$$(\because dE_1 + dE_2 = 0)$$

$$\therefore \frac{1}{\Omega_1} \cdot \frac{\partial \Omega_1}{\partial E_1} \Big|_{E_1=E_1^*} = \frac{1}{\Omega_2} \cdot \frac{\partial \Omega_2}{\partial E_2} \Big|_{E_2=E_2^*}$$

식은 $\ln$ 의 미분형으로 표현하면,

$$\frac{\partial}{\partial E_1} \cdot \ln \Omega_1(E_1) \Big|_{E=E_1^*} = \frac{\partial}{\partial E_2} \cdot \ln \Omega_2(E_2) \Big|_{E=E_2^*}$$

이다. 이는 간단하지만 강력한, 위의
기초에서 유도된 식이다.

Condition of thermal equilibrium

$\Rightarrow$ 이 때, 이 조건식의 차원을 살펴보자. $\ln \Omega$ 는 number이고, E 에 대해 미분하니 $[E^{-1}]$ 의 차원을 가진다. 또한, 0th Law를 보면 이 열평형 조건에서 온도가 정의된다는 사실을 알 수 있다. 따라서, 적절한 상수를 통해 아래와 같이 정리식을 만들다.

$$\frac{1}{k_B \cdot T} = \frac{\partial}{\partial E} \cdot \ln \Omega(E)$$

k_B : Boltzmann constant $[J/K]$

$\Rightarrow$ 이는, "macrostate observable T "의 statistical (probability) origin을 관계짓는 관계식이다!

$\Rightarrow$ 따라서, 제리 엔트로피 (Entropy) S 를 $S = k_B \cdot \ln \Omega(E)$ 로 정리한다면,
이래의 같은 관계식을 얻고, 이는 fundamental definition of temperature 이다.
(absolute temperature)

$$\frac{1}{T} = \frac{\partial}{\partial E} \cdot k_B \cdot \ln \Omega(E) = \frac{\partial S(E)}{\partial E}$$

$\Rightarrow$ Thus, by using this equation, condition of thermal equilibrium is,

$$\frac{1}{T_1} = \frac{1}{T_2}$$

(*) 이제, 열평형 조건식과, 이를 통해 온도를 엄밀하게 정의했으니, Direction of heat flows를 알아보도록 하자. 주어진 조건에서,

$$(E_1^0, E_2^0) \xrightarrow{\text{equilibrium}} (E_1^*, E_2^*) \text{ 이다.}$$

이 때, 평형을 이루는 지점에서 Ω_{tot} 가 최대이므로, 아래 식은 옳다.

$$\Omega_1(E_1^*) \Omega_2(E_2^*) \geq \Omega_1(E_1^0) \Omega_2(E_2^0) \quad \text{양변에 } \ln \text{를 취하고 정리하면 } (\because \ln \text{증가함})$$

$$\Rightarrow \ln \Omega_1(E_1^*) + \ln \Omega_2(E_2^*) \geq \ln \Omega_1(E_1^0) + \ln \Omega_2(E_2^0) \quad \text{kb 풀어서 정리}$$

$$\Rightarrow S_1(E_1^*) + S_2(E_2^*) \geq S_1(E_1^0) + S_2(E_2^0)$$

$\therefore \Delta S_{tot} = \Delta S_1 + \Delta S_2 \geq 0$: For isolated system, total entropy should be increased

Clausius's Statement of 2nd Law

For small $\delta S = S_1(E_1^*) - S_1(E_1^0) + S_2(E_2^*) - S_2(E_2^0)$, Energy of system can be described as

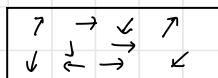
$$\begin{aligned} \begin{cases} E_1^* = E_1^0 + \delta E_1 \\ E_2^* = E_2^0 + \delta E_2 \end{cases} & \quad \text{And, by upper statement, } \delta S = \left(\frac{\partial S}{\partial E_1} \cdot \delta E_1 + \frac{\partial S}{\partial E_2} \cdot \delta E_2 \right) \\ & = \left(\frac{\partial S}{\partial E_1} \bigg|_{E_1^0} - \frac{\partial S}{\partial E_2} \bigg|_{E_2^0} \right) \delta E_1 \\ & = \left(\frac{1}{T_1^0} - \frac{1}{T_2^0} \right) \delta E_1 \geq 0. \end{aligned}$$

$\Rightarrow$ This means if $T_2^0 > T_1^0$, $\delta E_1 > 0$. Energy flows from high temperature to low temperature.

3) The first Law of Thermodynamics

< Micro States >

- $6N$ Variables $\{ \vec{p}_i, \vec{q}_i \}$



< Macro states >

- A few macroscopic observables (Variables)

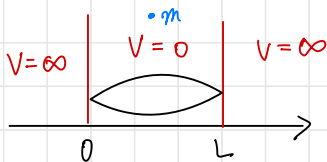
ex) $E, N, V, T, P, \dots$

$\Rightarrow$ In thermal equilibrium, the macroscopic properties of system are characterized by a set of functions of states (state variables, 상태함수)

$\Rightarrow$ Macroscopic observables do not change (fixed value) under time evolution or previous history, because they are "functions of states"

$\hookrightarrow$ If not, 0th Law 위반한다.

(Ex) 약간의 양자역학이 개입된, Infinite Potential Well을 고려해보자. (1-D)



$$\hat{H} \cdot \psi(x) = E \cdot \psi(x) \quad \text{for this case, } \hat{H} = -\frac{\hbar^2}{2m} \cdot \frac{d^2}{dx^2}$$

$$\psi \sim e^{ikx} \text{ 이고, } \psi(0) = \psi(L) = 0 \text{ 이므로}$$

$$\therefore \psi(x) = C \cdot \sin kx \quad k_n = \frac{n\pi}{L} \quad \text{이것을 들면}$$

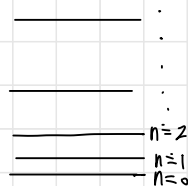
$$E_n = \frac{\hbar^2 \cdot k_n^2}{2m} = \frac{\hbar^2 \pi^2}{2m L^2} n^2 \rightarrow \text{Quantized energy level, discrete value.}$$

$$(n = 0, 1, 2, \dots)$$

$H(x_1, x_2, x_3, \dots)$
Internal parameter.

If $L \rightarrow L + \delta L$, E_n shifted, energy changes (External parameter)

If $n = i \rightarrow j$, Energy changes (Internal parameter)

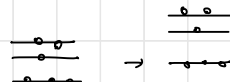


$\Rightarrow$ 이처럼, 계의 에너지에 영향을 주는 변화 인자를 구할 수 있다. 여기서, 아래의 정리가 필요하다.

(i) **Work**: Energy changes induced by variation of **External parameters**

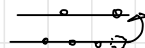
(= due to the changes of energy level)

$$\Delta E = W \quad (\text{Naturally, 계에 가해진 일 개념이다})$$



(ii) **Heat**: Energy changes when all the external parameters **remain fixed**

$$\Delta E = Q. \quad (\text{계에 흡수된 열})$$



(iii) Combine (i) (ii) together $\Rightarrow \Delta E = W + Q \dots$ The 1st Law of Thermodynamics

$\Rightarrow$ Note that ΔE : Energy의 "변화량"

W, Q should be defined only through the process (= Energy in transit)

All of these discussions are valid during thermal equilibrium.



System go through the points that all satisfy thermal equilibrium, at every instant moments, so Ω is maximized

$\Rightarrow$ For infinitesimal process, $dE = \delta Q + \delta W$ (or $\delta Q + \delta W$)

$\hookrightarrow$ Inexact differential, which means path-dependent.

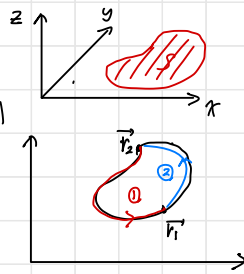
(*) Exact vs Inexact.

• Exact is, for $z = f(x, y)$, $df = f(x+dx, y+dy) - f(x, y) = \left(\frac{\partial f}{\partial x}\right)_y dx + \left(\frac{\partial f}{\partial y}\right)_x dy$

$$\Rightarrow \left[\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x}\right)_y\right]_x = \left[\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y}\right)_x\right]_y = A(x, y) dx + B(x, y) dy$$

In this case, $\int_a^b df = f(b) - f(a)$ (Path independence)

pf) $\vec{F} = (A(x,y), B(x,y))$ then, $\oint_{\partial S} \vec{F} \cdot d\vec{x} = \int_S d\vec{S} \cdot (\nabla \times \vec{F})$ 여기서는 $\hat{z}$ 방향이니
 $(\nabla \times \vec{F})_z = \left(\left(\frac{\partial B}{\partial x} \right)_y - \left(\frac{\partial A}{\partial y} \right)_x \right) \stackrel{df}{=} 0$ 이라면, $= 0$ 이므로



$\left(\int_{r_1}^{r_2} \vec{F} \cdot d\vec{x} \right)_1 + \left(\int_{r_2}^{r_1} \vec{F} \cdot d\vec{x} \right)_2 = 0$. So, $\left(\int_{r_1}^{r_2} \vec{F} \cdot d\vec{x} \right)_1 = \left(\int_{r_1}^{r_2} \vec{F} \cdot d\vec{x} \right)_2$
 $\stackrel{df}{=} df$

즉, 이걸 필요 조건이 df 가 exact differential이다.

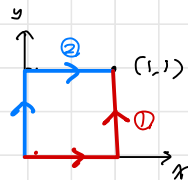
$\Leftrightarrow$ Path Independence

• Inexact differential: naturally, Path-dependent property.

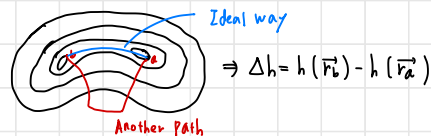
ex) Let $df = xy \cdot dx + x^2 \cdot dy$.

$\int_{(0,0)}^{(1,1)} df = 0 + \int_{y=0}^{y=1} 1^2 \cdot dy = 1$

$\int_{(0,0)}^{(1,1)} df = 0 + \int_0^1 xy \cdot dx = \frac{1}{2}$.



(cf) Contour map



4) Heat Capacity

< 1st Law : $dQ = dE - dW$ >

Question : How much heat should be added to the system, to increase the temperature?

$\Rightarrow$ The answer comes from new definition, Heat Capacity $C \equiv \left(\frac{dQ}{dT} \right)$

이 때, Energy of the system을 T, V 의 함수로 간주하자.

(그런데 이래도 통불려나? 그걸다!) $E = E(T, V)$

$\Rightarrow dE(T, V) = \left(\frac{\partial E}{\partial T} \right)_V dT + \left(\frac{\partial E}{\partial V} \right)_T dV = dQ + dW$.

$\Rightarrow dQ = \left(\frac{\partial E}{\partial T} \right)_V dT + \left(\frac{\partial E}{\partial V} \right)_T dV - dW$.

이 때, System의 Quasi-Static Process (Slowly enough to remain in thermodynamic equilibrium)

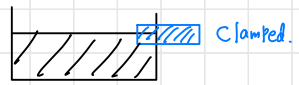
을 따름으로 하면, $dW = -PdV$ 이다.

$\Rightarrow dQ = \left(\frac{\partial E}{\partial T} \right)_V dT + \left[\left(\frac{\partial E}{\partial V} \right)_T + P \right] dV$

이제, 이 식을 이용해 Heat Capacity under certain Condition을 구하자.

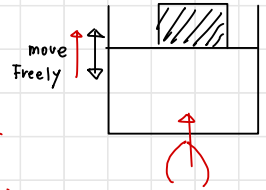
① Constant Volume, $C_v = \left(\frac{\partial Q}{\partial T}\right)_v = \left(\frac{\partial E}{\partial T}\right)_v$
 ($dV = 0$)

⇒ 이 때, (Amount of heat) = (Amount of Internal energy change), 리브에서 가해진 heat가
 전부 energy로 전환된다.



② Constant Pressure. $C_p = \left(\frac{\partial Q}{\partial T}\right)_p = \left(\frac{\partial E}{\partial T}\right)_v + \left[\left(\frac{\partial E}{\partial V}\right)_p + p\right] \left(\frac{\partial V}{\partial T}\right)_p$
 ($dP = 0$)

⇒ $C_p - C_v = \left[\left(\frac{\partial E}{\partial V}\right)_p + p\right] \left(\frac{\partial V}{\partial T}\right)_p$ → extra relation이 더해지면
 정리 가능.
 (like ideal gas etc...)
 ∴ $C_p > C_v$. ⇒ $\gamma \equiv \frac{C_p}{C_v} > 1$ (Adiabatic index)



2. The Ideal Gas

In general, we can say this using entropy.
 ($C_p - C_v = \frac{d^2}{ds} V$)

2.1) The equation of state

(*) The Empirical statement of gas

Boyle's Law : $p \propto \frac{1}{V}$ at constant Temperature

Charles's Law : $V \propto T$ at constant Pressure

$p \propto T$ at constant Volume.
 $p \propto N$

⇒ Empirical Laws combined into one formula:

$PV = Nk_B T$... The equation of state.

⇒ These Laws were found experimentally, so physicists wanted how to explain this theoretically.
 To explain this, they made a few assumptions.

(*) Assumptions

a) No inter-molecular interactions

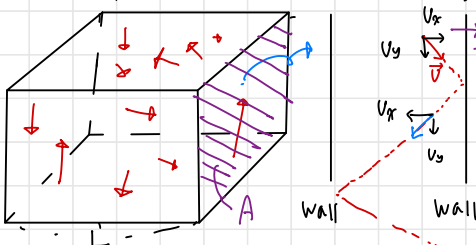
b) Point-like particles

c) Randomly moving.

d) Elastic collisions with the wall: No collisions between particles because of a).

with these assumptions,
 Let's use kinetic theory.

< N particles in Rectangular box >



Before & After the collision of a particle, momentum changes

$\Delta P_i = 2mV_x = mV_x - (-mV_x)$

⇒ $F_i = \frac{\Delta P}{\Delta t} = \frac{mV_x^2}{L}$ (∵ $\Delta t = \frac{2L}{V_x}$, Because no inter-molecular collision)

So, the force acting on the wall by N particles is

$$F = \sum F_i = \frac{m}{L} \cdot \sum (v_{i,x})^2 \Rightarrow P = \frac{F}{A} = \frac{m}{\underbrace{A \cdot L}_V} \sum (v_{i,x})^2$$

$$\Rightarrow P = \frac{m}{V} \cdot N \cdot \langle v_x^2 \rangle = \frac{mN}{3V} \langle v^2 \rangle \quad (\because \text{3 방향 구분 의미 } \times)$$

$$= \frac{2N}{3V} \cdot \left(\frac{1}{2} m \langle v^2 \rangle \right) = \frac{N k_B T}{V} \quad (\because \text{The equation of state})$$

~~$\sum U^2$~~ $\langle v^2 \rangle \cdot XN$
 이때, moment의 정리에 의해,
 $\langle v_x^2 \rangle = \frac{\sum (v_{i,x})^2}{N}$ 이므로,
 $U^2 = v_x^2 + v_y^2 + v_z^2$

$\therefore \langle K \rangle = \frac{1}{2} m \langle v^2 \rangle = \frac{3k_B T}{2} \Rightarrow$ So, we can get the relation between U^2 and T like this.

$\langle \frac{1}{2} m v^2 \rangle$ microscopical Macroscopic
 $\frac{1}{2} m \langle v^2 \rangle$
 (C) $N k_B = n \cdot N_A \cdot k_B = n R \Rightarrow PV = nRT$

2.2) Maxwell-Boltzmann Distribution

• 기체 분자의 속도 분포에 대한 확률밀도 함수를 유도해 보자. 여기서, 우리는 속도의 크기에 대해 분석하고 싶으니 v^2 에 대한 확률밀도 함수 $f(v^2)$ 를 찾고, 이때 $v^2 = v_x^2 + v_y^2 + v_z^2$, where v_x, v_y, v_z are independent 이므로 아래를 쓴다.

$\Rightarrow f(v^2) = f(v_x^2) f(v_y^2) f(v_z^2)$ (In thermal equilibrium, v_x^2, v_y^2, v_z^2 의 확률 분포는 같다)

이것 만족하는 함수는 지수함수이므로, f 를 아래와 같이 표현 가능하다.

$\Rightarrow f(v_x^2) = C \cdot e^{-a v_x^2}$ (사실, Boltzmann distribution $e^{-\beta E}$ 에 비례함 통해 직관적 유추 가능)

$$\Rightarrow \int_{-\infty}^{\infty} dx \cdot f(v_x^2) = \int_{-\infty}^{\infty} dx \cdot e^{-a v_x^2} = 1 \quad (\text{Normalization condition}). \quad C \cdot \sqrt{\frac{\pi}{a}} = 1. \quad \therefore C = \sqrt{\frac{a}{\pi}} \quad \dots \textcircled{1}$$

$\Rightarrow$ Let's use the consequence of the ideal gas: $m \langle v_x^2 \rangle = k_B T$. with probability density $f(v_x^2)$,

$$\Rightarrow m \langle v_x^2 \rangle = m \cdot \int_{-\infty}^{\infty} dv_x \left(v_x^2 \cdot \sqrt{\frac{a}{\pi}} e^{-a v_x^2} \right) = k_B T. \Rightarrow 2m \frac{a}{\sqrt{\pi}} \cdot I = k_B T, \quad I = \int_0^{\infty} dv_x (v_x^2 e^{-a v_x^2})$$

$$I = \int_0^{\infty} \frac{dt}{2a v_x} \cdot v_x^2 \cdot e^{-t} = \frac{1}{2a \sqrt{a}} \int_0^{\infty} \sqrt{t} \cdot e^{-t} dt \quad (\text{To calculate integral, } t = a v_x^2. dt = 2a v_x dv_x)$$

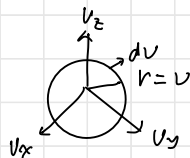
$$= \frac{1}{2a \sqrt{a}} \cdot I\left(\frac{3}{2}\right) = \frac{1}{2a \sqrt{a}} \cdot \frac{1}{2} I\left(\frac{1}{2}\right) = \frac{\sqrt{\pi}}{4a \sqrt{a}} \quad (\because I(n+1) = n I(n), I\left(\frac{1}{2}\right) = \sqrt{\pi})$$

$$\therefore \frac{m}{2a} = k_B T, \quad a = \frac{m}{2k_B T} \quad \dots \textcircled{2}$$

So, in ①, ② we know C, a .

Finally, we can get the result.

$$f(v^2) = f(v_x^2) f(v_y^2) f(v_z^2) = C^3 e^{-a v^2} = \left(\frac{m}{2\pi k_B T} \right)^{\frac{3}{2}} e^{-\frac{m v^2}{2k_B T}}$$



For conventional purpose, we use final representation.

$$f(v) = \left(\frac{m}{2\pi k_B T} \right)^{\frac{3}{2}} e^{-\frac{m v^2}{2k_B T}}$$

$\Rightarrow$ If we want to change this into the familiar form, be careful when you integrate! You need to integrate in d^3v , that is, $d^3v \cdot f(v) = (4\pi v^2 dv) f(v)$. What we know, $4\pi v^2 f(v)$, is very familiar form.

... Maxwell-Boltzmann Distribution.

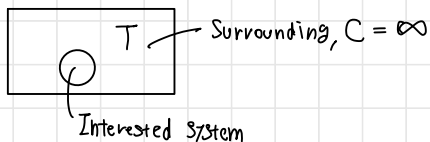
2.3) Equipartition Theorem.

• In the Canonical Ensemble, we can show this statement.

$$P(E) \propto e^{-\beta E}, \quad \beta = \frac{1}{k_B T} \quad \hookrightarrow \text{In this level, we just adopt this is true.}$$

... Boltzmann Distribution

Q) Canonical Ensemble (T fixed ensemble)



Probability theory of Ω , $P \sim W = \frac{N!}{n_1! \dots n_s!} \Rightarrow P \sim e^{-\beta E}$

Then, total energy of the system is the sum of "each degree of freedom energy"

$$E_{tot} = \sum_i E_i(x_i) = E_1(x_1) + E_2(x_2) + \dots + E_n(x_n) \quad \text{일치. } \alpha \geq 1, 4,$$

$$\text{Where, } \langle E_i \rangle = \int dx_1 dx_2 \dots dx_n \cdot E_i \cdot P(E) = \int dx_1 dx_2 \dots dx_n \cdot E_i \cdot e^{-\beta(E_1 + E_2 + \dots + E_n)}$$

$$= \frac{\left(\int dx_i E_i e^{-\beta E_i} \right) \prod_{j \neq i} \int dx_j e^{-\beta E_j}}{\int dx_1 dx_2 \dots dx_n e^{-\beta(E_1 + E_2 + \dots + E_n)}} \quad \hookrightarrow \text{Normalization}$$

$$= \frac{\int dx_i E_i e^{-\beta E_i}}{\int dx_i e^{-\beta E_i}} = - \frac{\partial}{\partial \beta} \cdot \ln \left[\int_{-\infty}^{\infty} dx_i \cdot e^{-\beta E_i} \right] \quad \Rightarrow \text{여기서, 물리적 직관을 발췌해야 한다.}$$

$$\text{Let } E_i(x_i) = \alpha \cdot x_i^2.$$

$$\Rightarrow \langle E_i \rangle = - \frac{\partial}{\partial \beta} \ln \left[\int_{-\infty}^{\infty} dx_i e^{-\alpha \beta x_i^2} \right] = - \frac{\partial}{\partial \beta} \cdot \frac{1}{2} \ln \left[\frac{\pi}{\alpha \beta} \right] = - \frac{1}{2} \cdot \frac{\partial}{\partial \beta} \left[\ln \pi - \ln \alpha - \ln \beta \right]$$

$$\langle E_i \rangle = \frac{1}{2\beta} = \frac{k_B T}{2}$$

$$(\beta \text{ definition: } \beta = \frac{1}{k_B T} = \frac{\partial \ln \Omega(E)}{\partial E})$$

... Equipartition thm

$\Rightarrow$ Single degree of freedom 에 해당하는 에너지인 $\langle E_i \rangle = \frac{k_B T}{2}$ 이다.

(ex) For $n=3, (x_1, x_2, x_3) \Rightarrow K = \sum_i \langle E_i \rangle = \frac{3k_B T}{2}$... 이는 2.1) 에서 검증한 식이다.

Q. In Quantum mechanics, energy is discrete value... why integral is ok?

$\Rightarrow \Delta E \ll k_B T$, It works well in our region!

2.4) Specific Heats

• We can define specific heat of the system like this :

$$\left[\begin{aligned} C_v &= \frac{C_v}{N} \text{ or } \frac{C_v}{n} \\ C_p &= \frac{C_p}{N} \text{ or } \frac{C_p}{n} \end{aligned} \right] \text{ where large } C \text{ means heat capacity.}$$

• Now, **ideal gas**의 경우에는, $E = \frac{3}{2} N k_B T$ 이므로 다음과 같다. (In monoatomic case)

$$(i) C_v = \frac{1}{N} \left(\frac{dQ}{dT} \right) = \frac{1}{N} \left(\frac{\partial E}{\partial T} \right)_v = \frac{3}{2} k_B; (\because dV=0)$$

(ii) For constant pressure,

$$\begin{aligned} C_p &= \frac{1}{N} \left(\frac{dQ}{dT} \right) = \frac{1}{N} \left[\frac{dE - dW}{dT} \right]_p = \frac{1}{N} \left[\left(\frac{\partial E}{\partial T} \right)_v + \left\{ \left(\frac{\partial E}{\partial V} \right)_T + P \right\} \left(\frac{\partial V}{\partial T} \right)_p \right] \\ &= C_v + \cancel{\frac{P}{N}} \cdot \cancel{\frac{N k_B}{P}} \\ &= C_v + k_B = \frac{5}{2} k_B \quad (\text{For } \text{자유도} = 3). \end{aligned}$$

E는 T만의 함수, 아래에서 보일듯
보이겠다.

For Quasi-static Process [P definable
W = -P dV

$$\boxed{\gamma \equiv \frac{C_p}{C_v} = \frac{5}{3}} \dots \text{adiabatic exponent}$$

(*) E가 ideal gas의 경우, T만의 함수임을 보일것다. 여기서 우리가 필요한 가정은 "quasi-static" 뿐이다.

• Let $E = E(T, V)$ then, $dE(T, V) = \left(\frac{\partial E}{\partial T} \right)_v dT + \left(\frac{\partial E}{\partial V} \right)_T dV = dQ + dW$

• In quasi static, $dW = -P dV$.

$\Rightarrow$ As we will see later, entropy can be related to the heat with temperature: $dQ = T dS$

$\Rightarrow T dS = dE - dW = \left(\frac{\partial E}{\partial T} \right)_v dT + \left(\frac{\partial E}{\partial V} \right)_T dV + P dV$ T를 나눠, 정리해서 dS에 대한 방정식 구하면

$$\Rightarrow dS = \underbrace{\frac{1}{T} \left(\frac{\partial E}{\partial T} \right)_v}_{①} dT + \underbrace{\left[\frac{1}{T} \left(\frac{\partial E}{\partial V} \right)_T + \frac{P}{T} \right]}_{②} dV = \underbrace{\left(\frac{\partial S}{\partial T} \right)_v}_{①'} dT + \underbrace{\left(\frac{\partial S}{\partial V} \right)_T}_{②'} dV$$

$\Rightarrow$ This is true for all condition of (T, V) so we can say ① = ①', ② = ②'

$$\left(\frac{\partial S}{\partial T} \right)_v = \frac{1}{T} \left(\frac{\partial E}{\partial T} \right)_v \dots \textcircled{A}$$

$$\left(\frac{\partial S}{\partial V} \right)_T = \frac{1}{T} \left(\frac{\partial E}{\partial V} \right)_T + \frac{P}{T} \dots \textcircled{B}$$

이제, S는 상태함수이므로 $S_{TV} = S_{VT}$ 이다. 이를 $\frac{\partial}{\partial V} \cdot \textcircled{A} = \frac{\partial}{\partial T} \textcircled{B}$ 로 정리하면

$$\Rightarrow \underbrace{\frac{1}{T} \cdot \frac{\partial^2 E}{\partial V \partial T}}_{①} = - \frac{1}{T^2} \cdot \left(\frac{\partial E}{\partial V} \right)_T + \underbrace{\frac{1}{T} \cdot \frac{\partial^2 E}{\partial T \partial V}}_{①'} + \cancel{\frac{\partial}{\partial T} \left[\frac{N k_B}{V} \right]}$$

$\Rightarrow E$ is state function, $E_{VT} = E_{TV}$ 이다. (미분 순서 상관 X) 즉, $\textcircled{1} = \textcircled{2}$ 이므로 이 식을 정리하면,

$$\frac{1}{T^2} \left(\frac{\partial E}{\partial V} \right)_T = 0 \text{ for all } T. \text{ also,}$$

$$\left(\frac{\partial E}{\partial V} \right)_T = 0$$

E is not the function of V .

$\therefore$ In Ideal gas system, E only depends on the temperature.

3. The 2nd Law

• The only way to tell the direction of time flows.

• Before we go further, let's talk about thermodynamic process.

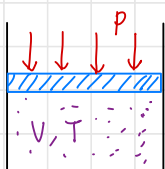
Thermodynamic Process : Transformation, changes of thermodynamic states.

3.1) Quasi-Static Process

$\rightarrow$ So slowly performed that the system is in the thermal equilibrium at every moment. ^{Related} 'Reversible process'

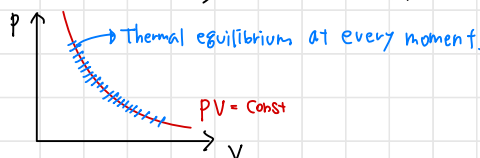
$\rightarrow$ Pressure is measured (definable) at every moment: $\delta W = -P dV$ can be used. Otherwise, you cannot use it.

(ex1)

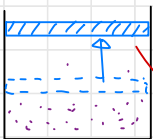


For ideal gas $PV = Nk_B T$, during Quasi-Static Process, we can see that:

$$\begin{aligned} P &\rightarrow P' = P + \delta P \rightarrow P'' \rightarrow \dots \\ V &\rightarrow V' = V + \delta V \rightarrow V'' \rightarrow \dots \\ T &\rightarrow T' = T + \delta T \rightarrow T'' \rightarrow \dots \end{aligned}$$



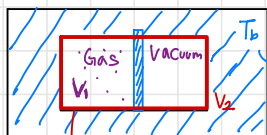
(ex2)



Suddenly expansion for very small time interval

Nearly vacuum, molecules not yet reach, cannot find P .

(*) Isothermal expansion.

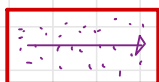


Heat bath (Reservoir) : T_b is fixed, because heat capacity $C \rightarrow \infty$

$\Rightarrow$ In thermal equilibrium, $T_b = T_s$.

System

a) Free expansion : 갑자기 중간 기밀판 제거, Non Quasi-Static Process



• $\Delta T = 0 \Rightarrow \Delta E = 0$ for ideal gas

• $\Delta W = 0 \Rightarrow$ No pushing material, no work!

• $\Delta Q = \Delta E - \Delta W = 0 - 0 = 0$. No heat exchange.

b) Quasi-Static isothermal expansion (Reversible?)

• Pressure can be defined always: $\delta W = -PdV$.

• $\Delta T = 0 \Rightarrow \Delta E = 0$

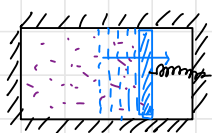
• $\Delta W = \int_1^2 \delta W = - \int_1^2 PdV = - \int_{V_1}^{V_2} \frac{Nk_B T}{V} dV = -Nk_B T \cdot \ln\left(\frac{V_2}{V_1}\right)$

• $\Delta Q = \Delta E - \Delta W = -\Delta W$

$V_2 > V_1$ (Expansion) : $\Delta W < 0$ $\Delta Q > 0$

$V_2 < V_1$ (Compression) : $\Delta W > 0$ $\Delta Q < 0$

(*) Adiabatic expansion: Thermally insulated & Quasi-Static



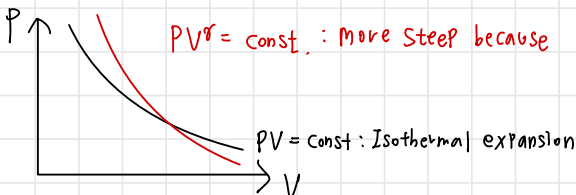
• $\delta Q = 0 = dE - \delta W$ $\left[C_V = \left(\frac{\partial E}{\partial T}\right) = \left(\frac{dE}{dT}\right) \text{ (Ideal gas condition)} \right]$
 $\delta W = -PdV$

$\Rightarrow C_V dT + PdV = 0$ dT 를 P, V 에 대해 정리하면 아래와 같다.

$\Rightarrow C_V \cdot \left[\frac{PdV + VdP}{Nk_B} \right] + PdV = 0 \Rightarrow (C_V + Nk_B)PdV + C_V VdP$ 양변을 $C_V P$ 로 나누고 적분하면 $\gamma - \frac{C_P}{C_V}$ 이므로

$\Rightarrow \int \frac{\gamma}{V} dV + \int \frac{dP}{P} = 0 \Rightarrow \ln PV^\gamma = C. \therefore PV^\gamma = \text{const}$... state equation of adiabatic expansion.

$PV^\gamma = \text{const}$: more steep because $\gamma > 1$



3.2) The Second Law (Statement based on the observation)

Clausius's Statement.

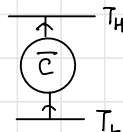
(= No perfect refrigerator)

$\Rightarrow$ No Process is Possible whose Sole effect is the transfer of heat from a colder to hotter body.
 = with no other effect. (머리만 돌아)

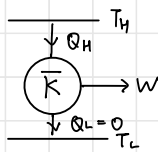
Kelvin's Statement

(= No perfect engine)

$\Rightarrow$ No Process is possible whose sole effect is the complete



< Clausius violator >



< Kelvin violator >

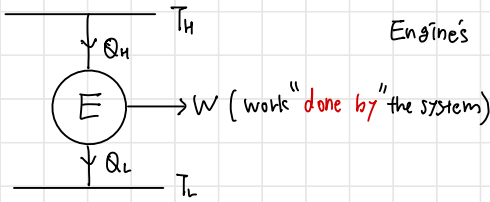
Equivalence! Conversion of heat into work.

Q. How about isothermal expansion? Its $\Delta E = 0$. So,

$\Delta Q + \Delta W = 0$. Isn't it Kelvin violator?

A. No! why?

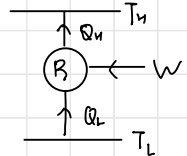
• Engine: A system operating a cyclic process that converts heat into work.



$$\text{Engine's Efficiency } \eta \equiv \frac{W}{Q_H} = \frac{Q_H - Q_L}{Q_H} = 1 - \frac{Q_L}{Q_H} \leq 1$$

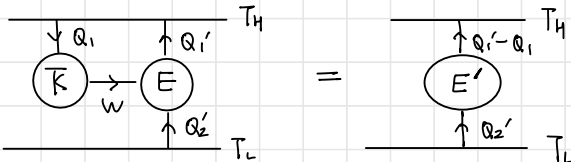
where $Q_H, Q_L > 0$ in this diagram.
(arrow indicate the sign).

cf) Refrigerator



(*) Proof of the equivalence of Kelvin & Clausius's statement.

(i) $K \rightarrow C$: Let's assume we have Kelvin violator $\bar{K}$.

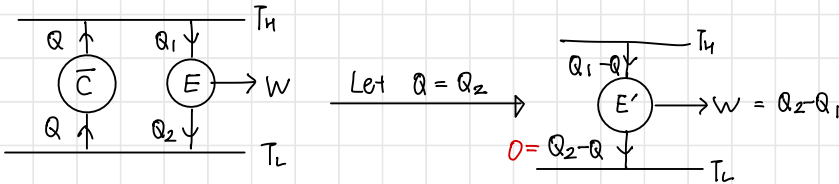


$$\begin{aligned} Q_1' - Q_1 &= W + Q_2' - Q_1 \\ &= Q_2' \quad (\because W = Q_1) \end{aligned}$$

$$\text{So, } (Q_1' - Q_1) = Q_2' \text{ 이므로,}$$

외복에서 온 것이 T_L 에서 T_H 로 Heat transfer가 발생한다. $\Rightarrow E' = \text{Clausius violator } \bar{C}$

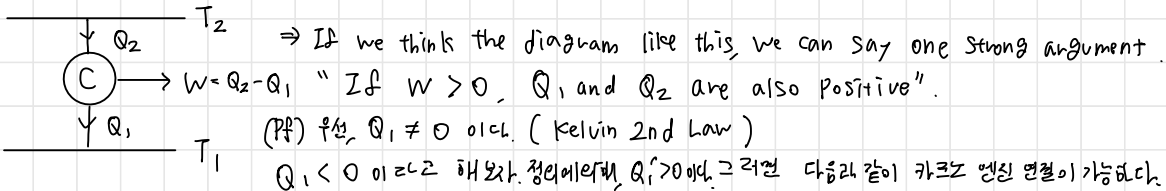
(ii) $C \rightarrow K$: Let's assume we have $\bar{C}$.



$\therefore E' = \text{Kelvin violator } \bar{K}$

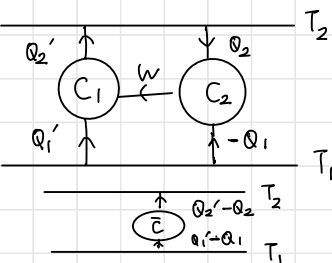
3.3) The Carnot Engine.

Def) Any reversible engine working between two given temperatures. (Based on Carnot's assumption)



(Pf) 우선, $Q_1 \neq 0$ 이다. (Kelvin 2nd Law)

$Q_1 < 0$ 이라고 해보자. 정역이려면 $Q_1' > 0$ 이다. 그러면 다음과 같이 카르노 엔진 연결이 가능하다.



$$\because \text{Reversible engine!} \quad \frac{+}{W} = \frac{+}{Q_2 - Q_1}, \quad Q_2' = W + Q_1' \text{ 이다. } \Rightarrow Q_2' = Q_2 - Q_1 + Q_1'.$$

$\therefore$ 전체 관련에 의해, $W > 0$ 이다. (C_2 로 볼 때) $> Q_2$.

따라서, $Q_2' - Q_2 > 0$ 이고, $Q_1' - Q_1 > 0$ 이다.

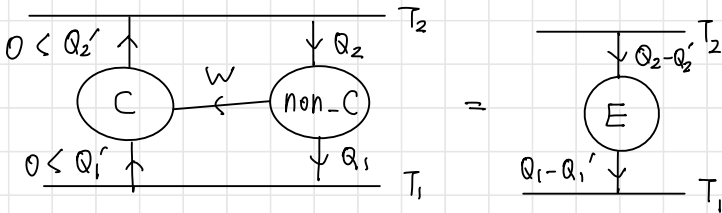
이런, 알짜 열기관이 Clausius violator가 되므로 불가능하다.

따라서, 전체가 돌렸다. $\therefore W > 0$ 이면 $Q_1 > 0$. $Q_2 = Q_1 + W > 0$.

중요한 정리인 카르노 정리를 공부하자.

(*) **Carnot's theorem** : No engine operating between the two temperatures is more efficient than the Carnot engine.

PF) Let's assume the following situation



Clausius's

$$W = Q_2 - Q_1 = Q_2' - Q_1' \Rightarrow Q_2' = (Q_1' - Q_1) + Q_2, \text{ By 2nd Law, } Q_2 \geq Q_2', Q_1 \geq Q_1'.$$

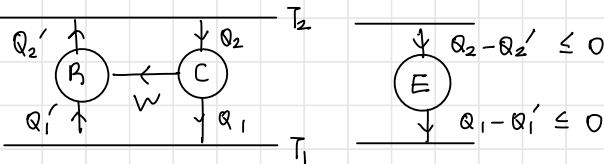
Then, we can now see, $\eta_{nc} = \frac{W}{Q_2}$, $\eta_c = \frac{W}{Q_2'} \Rightarrow \eta_{nc} \leq \eta_c$.

If $\eta_{nc} = \eta_c$, then $Q_2 = Q_2'$, $Q_1 = Q_1'$. So, now non-C is Carnot engine! ■

(*) Corollary

① All reversible engine have the same efficiency.

PF) We know $\eta_R \leq \eta_c \Rightarrow \frac{W}{Q_2'} \leq \frac{W}{Q_2} \Rightarrow Q_2' \geq Q_2$.



Not to violate Clausius's 2nd Law, we have $Q_2 = Q_2'$, $Q_1 = Q_1'$. $\Rightarrow \eta_R = \eta_c$.

$\therefore$ So, any reversible engine has the same efficiency!

$\Rightarrow$ Based on these statements, ($\eta \leq \eta_c$, $\eta_R = \eta_c$) we can think the simplest condition. Let's think reversible, idle-gas working, frictionless idealized engine.

$\Rightarrow$ From reversible, during heat transfer, no Temperature of system change!

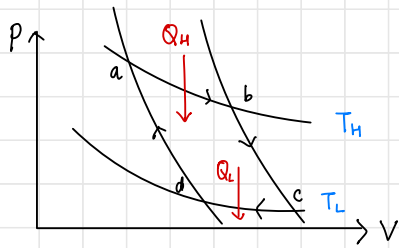
(온도가 바뀌려면; 어느 한방향에서는 열이 낮 $\rightarrow$ 높이가 되어서 클라우지우스 2법칙 위반)

$\Rightarrow T_H, T_L$ 두 온도의 가역기관에서, 각각의 온도를 줄일 때만 heat transfer 가능 (실제로는 불가능)

$\Rightarrow$ Then, Engine이 $T_H \leftrightarrow T_L$ 일 때는 열교환 X: Adiabatic process!

아예...

• 이제 이러한 배경을 바탕으로, 간단한 Carnot cycle 분석하자.



Engine: Cyclic Process, Converts heat into work.

(i) ab (Isothermal Expansion)

$$\Delta T = 0, \Delta E = 0 = \Delta Q_1 + \Delta W_1.$$

$$\Rightarrow \Delta Q_1 = -\Delta W_1 = \int_{V_a}^{V_b} P dV = N k_B T_H \ln \frac{V_b}{V_a} > 0.$$

(ii) bc (Adiabatic Expansion)

$$\text{or } aH, P_a V_a = P_b V_b \text{ or } cL.$$

$$P V^\gamma = \text{const.} \Rightarrow V^{\gamma-1} \cdot T = \text{const.} (\because \text{ideal gas equation})$$

$$\Rightarrow \left(\frac{V_b}{V_c}\right)^{\gamma-1} = \frac{T_L}{T_H} \quad \Delta Q_2 = 0 \text{ or } cL, \Delta W_2 = \Delta E_2 = C_V \Delta T = C_V (T_L - T_H)$$

(iii) cd (Isothermal Compression)

$$\Delta T = 0, \Delta E_3 = 0, \Delta Q_3 = -W_3 = N k_B T_L \ln \left(\frac{V_d}{V_c}\right) < 0$$

(iv) da (Adiabatic Compression)

$$\Delta Q_4 = 0, \left(\frac{V_a}{V_d}\right)^{\gamma-1} = \frac{T_L}{T_H}$$

$$\Delta W_4 = \Delta E_4 = C_V (T_H - T_L).$$

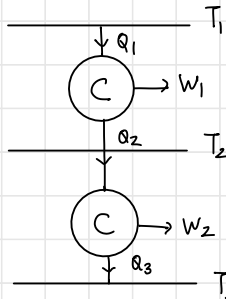
$$\Rightarrow \Delta E_{\text{tot}} = (\Delta E_1 + \Delta E_3) + (\Delta E_2 + \Delta E_4) = 0 \quad \text{Also, } \frac{V_b}{V_c} = \frac{V_a}{V_d} \Leftrightarrow \frac{V_b}{V_a} = \frac{V_c}{V_d}.$$

$$\Rightarrow \frac{Q_L}{Q_H} = \frac{-\Delta Q_3}{\Delta Q_1} = \frac{N k_B T_L \ln \left(\frac{V_c}{V_d}\right)}{N k_B T_H \ln \left(\frac{V_b}{V_a}\right)} = \frac{T_L}{T_H} \text{ or } \Xi \quad \boxed{\eta_c = 1 - \frac{Q_L}{Q_H} = 1 - \frac{T_L}{T_H}}$$

$$\therefore \text{For reversible engine } \eta = \eta_c = 1 - \frac{T_c}{T_H} \text{ or } cL. \quad \underline{\eta(T_L, T_H)}$$

(*) Defining temperature scale using Carnot engine efficiency.

→ Universal way to define temperature scale



$$Q_2 = Q_1 - W_1.$$

$$= Q_1 - \eta Q_1$$

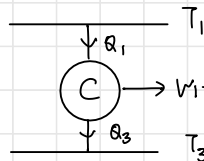
$$= [1 - \eta(T_1, T_2)] Q_1 \rightarrow$$

$$Q_3 = Q_2 - W_2.$$

$$= Q_2 - \eta(T_2, T_3) Q_2$$

$$= Q_2 [1 - \eta(T_2, T_3)]$$

$$= [1 - \eta(T_1, T_2)] [1 - \eta(T_2, T_3)] Q_1.$$



$$\Rightarrow Q_3 = Q_1 [1 - \eta(T_1, T_3)]$$

$$\therefore 1 - \eta(T_1, T_3) = (1 - \eta(T_1, T_2)) (1 - \eta(T_2, T_3))$$

$$\text{Let's guess } 1 - \eta = \frac{f(T_3)}{f(T_1)} = \frac{f_3 \propto T_3}{f_1 \propto T_1} = \frac{T_3}{T_1}.$$

↳ Linear eg

지금은 Temperature = 정의

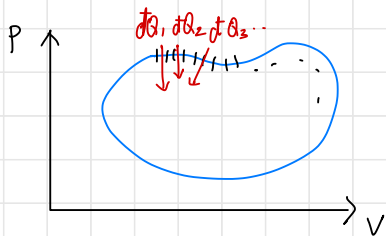
- 0th law → not rigorous

- Ideal gas Law

→ only for ideal gas

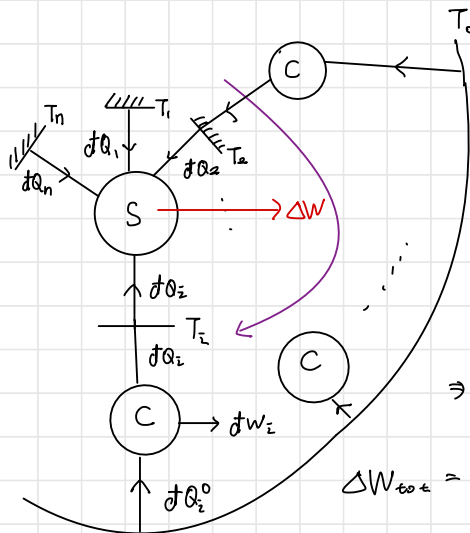
→ gas property dependent

3.4) Clausius's Theorem



⇒ In the real world, cycle is not that simple and beautiful.

(*) Let's think about the situation below.



T_0 (Thermal constant reservoir).

$dQ_i > 0$: System S absorbs heat
 $\Rightarrow \Delta W = \sum_i dQ_i$

Because of the Carnot engine property, we know

$$\left\{ \frac{dQ_i}{dQ_i^0} = \frac{T_i}{T_0} \Rightarrow \frac{dQ_i}{T_i} = \frac{dQ_i^0}{T_0} \right.$$

where $dQ_i^0 = dW_i + dQ_i$

$$\Rightarrow dQ_i^0 = \left(\frac{T_0}{T_i} \right) \cdot dQ_i \quad Q_i^0 = \sum dQ_i^0 = T_0 \cdot \sum \left(\frac{dQ_i}{T_i} \right)$$

$$\Delta W_{\text{tot}} = \Delta W_S + \Delta W_C = \Delta W + \sum_i dW_i$$

$$= \Delta W + \sum_i (dQ_i^0 - dQ_i) = \sum_i dQ_i^0 = T_0 \cdot \sum_i \left(\frac{dQ_i}{T_i} \right) = Q_0$$

If $Q_0 > 0$

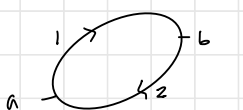
$$\Rightarrow Q_0 \leq 0 \Rightarrow T_0 \cdot \sum_i \left(\frac{dQ_i}{T_i} \right) \leq 0$$

Clausius's Violator!

$$\therefore \sum_i \frac{dQ_i}{T_i} \leq 0 \text{ if } dQ_i \text{ infinitesimal value, } \oint \frac{dQ}{T} \leq 0$$

⇒ For any cycle, $\oint \frac{dQ}{T} \leq 0$. The equality holds for the reversible process.

3.5) Entropy



$$\int_a^b \frac{dQ_{\text{rev}}}{T} \equiv \text{Zustand. For reversible process, } \oint \frac{dQ_{\text{rev}}}{T} = \left[\int_a^b \frac{dQ}{T} \right]_1 + \left[\int_b^a \frac{dQ}{T} \right]_2 = 0$$

$$\Rightarrow \left[\int_a^b \frac{\delta Q_{rev}}{T} \right]_1 = \left[\int_a^b \frac{\delta Q_{rev}}{T} \right]_2$$

$$\therefore \int_A^B \frac{\delta Q_{rev}}{T} = S(B) - S(A) \quad (dS = \frac{\delta Q_{rev}}{T})$$

... Path independence
 ⇔ Exact differential

(*) Property

① For arbitrary process, There is upper bound of heat exchange

$$pf) \oint \frac{\delta Q}{T} = \int_A^B \frac{\delta Q}{T} + \int_B^A \frac{\delta Q_{rev}}{T} \leq 0 \quad \int_A^B \frac{\delta Q}{T} \leq \int_A^B \frac{\delta Q_{rev}}{T} = S(B) - S(A)$$

... upper bound of heat exchange

$$or, \frac{\delta Q}{T} \leq \frac{\delta Q_{rev}}{T} = dS \quad \therefore \delta Q \leq \delta Q_{rev} = TdS$$

② For thermally isolated system, $\delta Q = 0 \Rightarrow T \cdot dS \geq 0$

$$\therefore dS \geq 0$$

⇒ 열적 고립계의 엔트로피는 감소하지 않는다.
 ⇒ 평형상태에서 S가 maximized.

... Another form of 2nd Law of thermodynamics

• For reversible (quasi-static) process, $\delta Q = TdS$, $\delta W = -PdV + \sum_i f_i dx_i$ displacement

$$dE = \delta Q_{rev} + \delta W_{rev} = TdS - PdV + \mu dN + \dots = dE(S, V, N, \dots)$$

$$= \delta Q_{irrev} + \delta W_{irrev} \Rightarrow \delta Q_{irr} \leq \delta Q_{rev} = TdS \quad or, \delta W_{irr} \geq \delta W_{rev} = -PdV$$

(Volume work) generalized force
 (ex) $\mu \cdot dN$
 (chemical potential) x (number of particle)

↪ T, P & generalized force, dS, dV & displacement
 T가 달라지면, dS 가 flow
 = P가 달라지면, dV & flow
 = μ 가 달라지면, dN 이 flow ...

Natural variables (extensive)

ex) Compression $\delta W_{irr} \geq \delta W_{rev} > 0$
 $dV < 0$

expansion $\delta W_{irr} \geq \delta W_{rev}$
 (System 이 팽창) $-\delta W'_{irr} \geq -\delta W'_{rev}$
 $\delta W'_{irr} \leq \delta W'_{rev}$

⇒ 이제, $dE(S, V, N)$ 은 다변량 함수이 표현할 수 있다.

$$dE = TdS - PdV + \mu dN$$

$$= \left(\frac{\partial E}{\partial S} \right)_{V, N} dS + \left(\frac{\partial E}{\partial V} \right)_{S, N} dV + \left(\frac{\partial E}{\partial N} \right)_{S, V} dN \Rightarrow \left(\frac{\partial E}{\partial S} \right)_{V, N} = T, \left(\frac{\partial E}{\partial V} \right)_{S, N} = -P, \left(\frac{\partial E}{\partial N} \right)_{S, V} = \mu$$

$$\Rightarrow \frac{P}{T} = - \frac{\left(\frac{\partial E}{\partial V} \right)_S}{\left(\frac{\partial E}{\partial S} \right)_V} \quad (\text{where } N \text{ is fixed})$$

(*) Mathematical skills of partial derivatives

In $x(y, z)$, $dx = \left(\frac{\partial x}{\partial y} \right)_z dy + \left(\frac{\partial x}{\partial z} \right)_y dz$, where $dz = \left(\frac{\partial z}{\partial x} \right)_y dx + \left(\frac{\partial z}{\partial y} \right)_x dy$

$$\Rightarrow dx = \underbrace{\left(\left(\frac{\partial x}{\partial z} \right)_y \left(\frac{\partial z}{\partial x} \right)_y \right)}_{=1} dx + \underbrace{\left[\left(\frac{\partial x}{\partial z} \right)_y \left(\frac{\partial z}{\partial y} \right)_x + \left(\frac{\partial x}{\partial y} \right)_z \right]}_{=0} dy = 0 \quad \forall x(y, z)$$

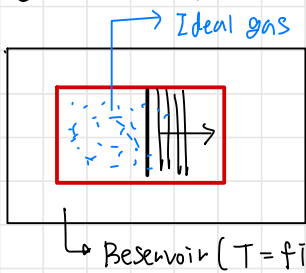
$$\therefore \left(\frac{\partial x}{\partial z} \right)_y = \frac{1}{\left(\frac{\partial z}{\partial x} \right)_y} \quad \text{--- ①} \quad \left(\frac{\partial x}{\partial z} \right)_y \left(\frac{\partial z}{\partial y} \right)_x \left(\frac{\partial y}{\partial x} \right)_z = -1 \quad \text{--- ② 이제, 이를 이용하자.}$$

$$\frac{P}{T} = - \left(\frac{\partial E}{\partial V} \right)_S / \left(\frac{\partial E}{\partial S} \right)_V = - \left(\frac{\partial E}{\partial V} \right)_S \cdot \left(\frac{\partial S}{\partial E} \right)_V \quad (\because ①)$$

$$\Rightarrow \frac{P}{T} \cdot \left(\frac{\partial V}{\partial S} \right)_E = -1 \times -1 = 1 \quad (\because ②) \quad \boxed{\therefore \frac{P}{T} = \left(\frac{\partial S}{\partial V} \right)_E}$$

3.6) Examples

① Reversible isothermal expansion ($\Delta T = 0$)



For ideal gas, we know $E = E(T)$. $\Rightarrow \Delta E = \Delta Q + \Delta W = 0$

$$\Rightarrow \Delta Q = -\Delta W = Nk_B T \cdot \ln \left(\frac{V_2}{V_1} \right)$$

• How about **Entropy**?

$$\Rightarrow \Delta S = \int_1^2 dS = \int_1^2 \frac{dQ_{rev}}{T} = \frac{\Delta Q}{T} \quad (\because T = \text{fixed})$$

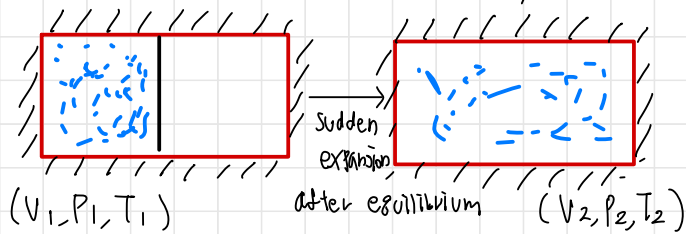
$$(i) (\Delta S)_{sys} = \frac{\Delta Q}{T} = Nk_B \ln \left(\frac{V_2}{V_1} \right) > 0$$

$$(ii) (\Delta S)_{bath} = \frac{-\Delta Q}{T} = -Nk_B \ln \left(\frac{V_2}{V_1} \right) < 0$$

$$(\Delta S)_{tot} = (\Delta S)_{sys} + (\Delta S)_{bath} = \underline{\underline{0}}$$

($\because$ reversible)

② Joule's expansion (Irreversible)



$$\Delta Q = 0 \quad (\because \text{Adiabatic process})$$

$$\Delta W = 0 \quad (\because \text{Free expansion})$$

$$\Rightarrow \Delta E = \Delta Q + \Delta W = 0 = \Delta E(T)$$

$$\therefore T_1 = T_2$$

• How about **Entropy**? $\rightarrow$ It is irreversible, so we cannot say directly " ΔS "

$\Rightarrow$ Instead, Let's consider reversible path from $(V_1, P_1, T_1) \rightarrow (V_2, P_2, T_2)$

($\because$) 가역과정/비가역과정 모두, initial $\rightarrow$ final state가 동일하면, ΔS 가 가역과정을 구해준다.

$\rightarrow$ 엔트로피는 상태함수이기 때문.

(Assume Isothermal reversible process)

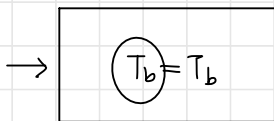
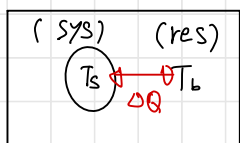
$$\Rightarrow TdS = \cancel{dQ_{rev}} = dE + PdV \Rightarrow N \cdot k_B T \cdot \ln\left(\frac{V_2}{V_1}\right) = \int TdS \quad \therefore \Delta S = N k_B \ln\left(\frac{V_2}{V_1}\right)$$

$$\Rightarrow \therefore (\Delta S)_{sys} = N k_B \ln\left(\frac{V_2}{V_1}\right) > 0.$$

$$\Rightarrow (\Delta S)_{bath} = 0 \quad (\because \text{No heat exchange}) \quad \left. \vphantom{\begin{matrix} \Rightarrow (\Delta S)_{bath} = 0 \\ \Rightarrow (\Delta S)_{sys} = N k_B \ln\left(\frac{V_2}{V_1}\right) > 0 \end{matrix}} \right\} \Delta S_{tot} = N k_B \ln\left(\frac{V_2}{V_1}\right) > 0.$$

($\because$ Irreversible)

(*) How to get $(\Delta S)_{tot}$ only using system variables



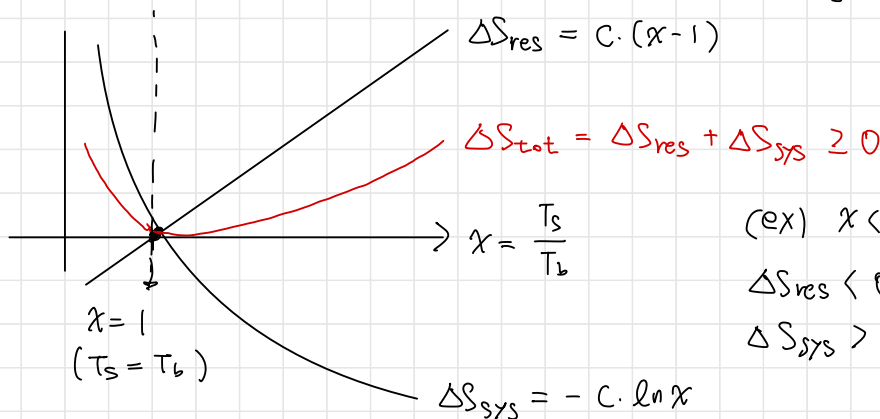
$$\left(\Delta Q = C \cdot (T_b - T_s) \quad (C: \text{비열}) \right)$$

$$(\Delta S)_{res} = \int \frac{dQ}{T} = - \frac{\Delta Q}{T_b}$$

$$\Rightarrow (\Delta S)_{res} = C \cdot \left(\frac{T_s}{T_b} - 1 \right)$$

$$\begin{aligned} (\Delta S)_{sys} &= \int \frac{dQ_{rev}}{T} = \int \frac{C dT}{T} \\ &= C \cdot \ln\left(\frac{T_b}{T_s}\right) \quad (C: \text{constant}) \end{aligned}$$

$$\Rightarrow (\Delta S)_{tot} = (\Delta S)_{sys} + (\Delta S)_{res} = C \cdot \left[-\ln x + x - 1 \right] \geq 0 \quad \left(x = \frac{T_s}{T_b} \right)$$



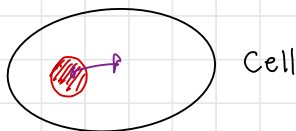
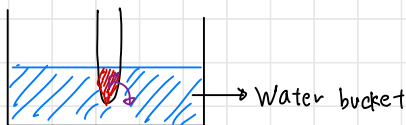
(ex) $x < 1$ ($T_s < T_b$)

$$\left. \begin{matrix} \Delta S_{res} < 0 \\ \Delta S_{sys} > 0 \end{matrix} \right\} \Delta S_{tot} > 0$$

(*) Limitation of $\Delta S \geq 0$

(i) System should be isolated in order to apply $\Delta S \geq 0$

⇒ Example case: Test tube, Cell



⇒ The red area (System) is the region we are interested in, which is interacting with the surrounding. (Non-isolated system)

(ii) Measurable / Controllable : $S(E, V, N)$

4. Thermodynamic Potentials

4.1) Extremum principles

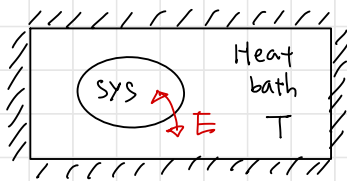
관심있는 system을 바지의 미생물인 heat bath가 둘러싸고 있고 가정.

• $E_{res} \gg \Delta E$: Assume E_{res} is constant (ideal reservoir)

⇒ T of reservoir is constant.

→ Thermal contact with the system long enough time

→ The hole of reservoir : To fix T.



(S)

(S) + (R)

Non-isolated

isolated ⇒ $\Delta S \geq 0$

System temperature → T

• $\Delta S_{tot} = (\Delta S)_{sys} + (\Delta S)_{bath}$ where $(\Delta S)_{bat} = \int \frac{\delta Q_{rev}}{T} = \frac{\Delta Q_{bath}}{T} = - \frac{\Delta Q_{sys}}{T}$

$= \left[(\Delta S)_{sys} - \frac{\Delta E_{sys} - \Delta W_{sys}}{T} \right]$ → 이는 두 system equality 이고, 이제 Reservoir의 detailed information이 필요 없다. "Sys" subscript를 drop하라.

$= \frac{1}{T} \left[T \Delta S - \Delta E + \Delta W \right] \geq 0$

$$\therefore \Delta E - T \Delta S \leq \Delta W$$

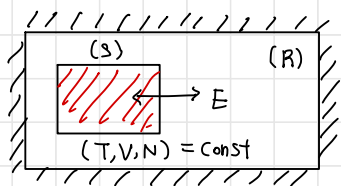
... System information에 관한 식

⇒ T가 충분히 오랜 시간이 지난 뒤 평형에서 System의 온도이고 $\Delta E, \Delta S, \Delta W$ 는 각각

System의 내부에너지 변화 / 엔탈피 변화 / System에 퍼를 일의 변화이다.

• 이제, 이 식을 기반으로 여러 국한 상황에서 계의 Potential을 나타내는 물리량을 정의해보자.

(*) Helmholtz Free energy



- T, V, N 이 일정하게 유지되면서 E 과정이 가능한 System이 주어졌다.
- 이는 isothermal process (?) including no mechanical work.
- ⇒ 위식들 ($\Delta E - T\Delta S \leq \Delta W$) 비교 변위량에 대해 보면,
- ⇒ $d(\underline{E - TS}) \leq \delta W$ ($\because dT = 0$)
- $\equiv F$ (Helmholtz free energy)

⇒ No mechanical work, $dF \leq 0$ → In equilibrium, $dF = 0$, $F \rightarrow F_{min}$.

(i) Described by Itself (System)

(ii) Reservoir only fixes Temperature: Don't need to consider detailed informations

(iii) New Extremum Principle: Upper bound exist.

(iv) "Balance" between $dE \leq 0$ and $dS \geq 0$.

(ex)

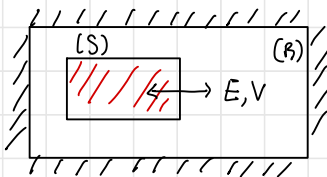
결과물 N개
결합 에너지 -E

회전 에너지 회전된 모든 결과물 X 존재 $\Rightarrow E = -N.E$

→ Impossible!

dE 가 아닌, dF 가 최소. 따라서, 몇몇
보이는 결과물 X. Balance Point에서 평형.

(*) Gibbs Free energy



- 이번에는, E 와 V 가 변할 수 있고 (T, P, N) 이 constant.
- (P 가 일정하니 V 가 변할)
- Isothermal and isobaric involving mechanical work.
- $\delta W = -PdV + \delta W_{other}$
- Volume Work

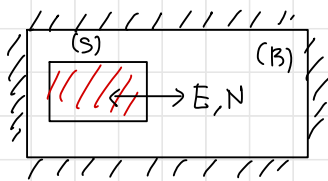
$$\Rightarrow dE - TdS + PdV = d(\underline{E - TS + PV}) \leq \delta W_{other}$$

$$\equiv G \text{ (Gibbs Free energy)}$$

⇒ If No other work ($\Leftrightarrow \delta W_{other} = 0$), $dG \leq 0$. → In equilibrium, $dG = 0$, $G \rightarrow G_{min}$

(*) Grand Potential

• 이번에는 E & N 이 교환 가능하2, (T, V, μ) 가 constant.



$\Rightarrow dW = \underbrace{\mu dN}_{\text{Chemical work}} + \delta W_{\text{other}}$ ↗ Potential ↘ 이변, 미분가능 방위

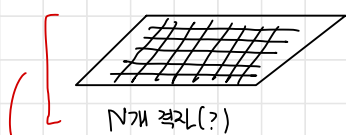
$\Rightarrow d(E - TS - \mu N) \leq \delta W_{\text{other}}$
 $\equiv \Phi$ (Grand Potential)

$\Rightarrow$ If no other work ($\delta W_{\text{other}} = 0$), $d\Phi \leq 0$ $\rightarrow$ In equilibrium, $d\Phi = 0$, $\Phi \rightarrow \Phi_{\min}$

$\Rightarrow$ 이 3가지 상공에서 정의된 계의 Potential이온, 계를 무엇으로 잡느냐에 따라 사용해야 하는데 달라진다.

(Ex) $\dots \rightarrow N$ 개 분자

(T, V, N) 일정, E 만 변함 $\Rightarrow dF = 0$.



$\Rightarrow$ Depending on the picture, different potential

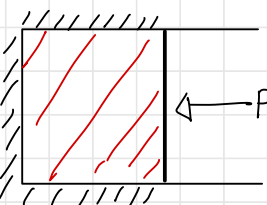
$\Rightarrow$ But, answer must be same!

N, E 변함. T, V, μ 일정
 $\Rightarrow d\Phi = 0$

(*) Entalpy

+ Isobaric

• A diabatic involving mechanical work.



$\Rightarrow \delta Q = 0$. $dE = \cancel{\delta Q} + \delta W^{\text{rev}} = -PdV + \delta W_{\text{other}}^{\text{rev}}$

$\Rightarrow (dE + PdV) = d(E + PV) = \delta W_{\text{other}}^{\text{rev}} \leq \delta W_{\text{other}}^{\text{irr}}$
 $\equiv H$ (Entalpy)

$\Rightarrow$ If no other work ($\delta W_{\text{other}} = 0$), $dH \leq 0$ $\rightarrow$ In equilibrium, $dH = 0$, $H \rightarrow H_{\min}$

(*) What kind of Constraint Condition is given in the Problem?

문제 풀기 전
 Check point.

4.2) Legendre Transformation

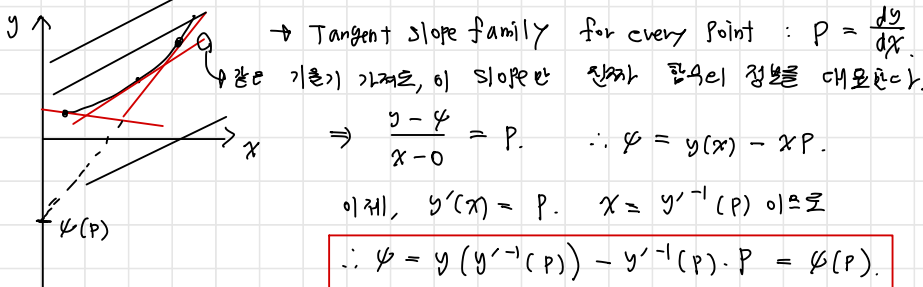
$$dE = TdS - PdV + \underbrace{\mu}_{\text{Particle exchange}} dN = dE(S, V, N) \longrightarrow S(E, V, N)$$

External Parameter: S, V, N
 $\uparrow \downarrow \uparrow \downarrow$
 Internal Parameter: T, P, μ

more easy to Control / Measure.

$$\Rightarrow \text{Let } y = y(x_1, x_2, \dots, x_n) \text{ then } p_i \equiv \frac{\partial y}{\partial x_i} \quad y \text{ is } p_i \text{의 function 으로 표현하자.}$$

(i) $y = y(x)$



Now, we have $y = y(x) \Leftrightarrow \varphi = \varphi(p).$

$$dy = p dx \longleftrightarrow d\varphi = -x dp$$

$$d\varphi(p) = \underbrace{dy - p dx}_{=0} - x dp = -x dp$$

① Entalpy: we now use ($V \rightarrow P$)

$$H \equiv E + PV \Rightarrow dH = dE + d(PV) = TdS - PdV + \cancel{\mu dN} + PdV + VdP = TdS + VdP$$

$$\Rightarrow dH(S, P) = TdS + VdP = \left(\frac{\partial H}{\partial S} \right)_P dS + \left(\frac{\partial H}{\partial P} \right)_S dP$$

$$\therefore \left(\frac{\partial H}{\partial S} \right)_P = T, \quad \left(\frac{\partial H}{\partial P} \right)_S = V$$

② Helmholtz Free Energy ($S \rightarrow T$)

$$F = E - TS$$

$$= \left(\frac{\partial F}{\partial T} \right)_V dT + \left(\frac{\partial F}{\partial V} \right)_T dV$$

$$\Rightarrow dF = dE - d(TS) = TdS - PdV - TdS - SdT = -(PdV + SdT)$$

$$\therefore S = - \left(\frac{\partial F}{\partial T} \right)_V, \quad P = - \left(\frac{\partial F}{\partial V} \right)_T.$$

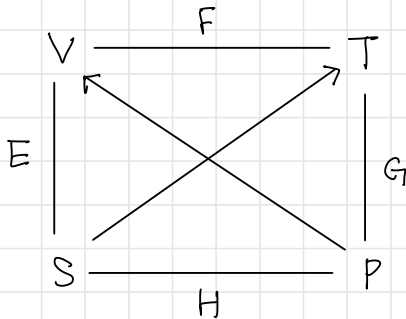
② Gibbs Free Energy ($S \rightarrow T, V \rightarrow P$)

$$G = E - TS + PV$$

$$\Rightarrow dG = dE - d(TS) + d(PV) = -SdT + VdP = \left(\frac{\partial G}{\partial T}\right)_P dT + \left(\frac{\partial G}{\partial P}\right)_T dP$$

$$\therefore S = -\left(\frac{\partial G}{\partial T}\right)_P, \quad V = \left(\frac{\partial G}{\partial P}\right)_T$$

(*) Thermodynamic Rectangle.



(T, S) (P, V) conjugate.

• Arrow 방향은 + sign.

$$\text{ex) } \left(\frac{\partial E}{\partial V}\right)_S = -P.$$

$$\left(\frac{\partial F}{\partial T}\right)_V = -S$$

$$\left(\frac{\partial G}{\partial P}\right)_T = V$$

4.3) Maxwell's relation

• $dE = TdS - PdV \rightarrow$ 4가지의 각각 독립 변수, 연관된 나왔음. $dE(S, V)$

$$\Rightarrow \underbrace{\left(\frac{\partial}{\partial V}\right)_S}_{=T} \left(\frac{\partial E}{\partial S}\right)_V = \underbrace{\left(\frac{\partial}{\partial S}\right)_V}_{=-P} \left(\frac{\partial E}{\partial V}\right)_S \Rightarrow \left(\frac{\partial T}{\partial V}\right)_S = -\left(\frac{\partial P}{\partial S}\right)_V$$

• $dH(S, P)$ 에?

$$\Rightarrow \left(\frac{\partial}{\partial P}\right)_S \left(\frac{\partial H}{\partial S}\right)_P = \left(\frac{\partial}{\partial S}\right)_P \left(\frac{\partial H}{\partial P}\right)_S \Rightarrow \left(\frac{\partial T}{\partial P}\right)_S = \left(\frac{\partial V}{\partial S}\right)_P$$

• $dF(T, V)$ 에?

$$\Rightarrow \left(\frac{\partial}{\partial V}\right)_T \left(\frac{\partial F}{\partial T}\right)_V = \left(\frac{\partial}{\partial T}\right)_V \left(\frac{\partial F}{\partial V}\right)_T \Rightarrow \left(\frac{\partial S}{\partial V}\right)_T = \left(\frac{\partial P}{\partial T}\right)_V$$

• $dG(T, P)$ 에?

$$\left(\frac{\partial}{\partial P}\right)_T \left(\frac{\partial G}{\partial T}\right)_P = \left(\frac{\partial}{\partial T}\right)_P \left(\frac{\partial G}{\partial P}\right)_T \Rightarrow -\left(\frac{\partial S}{\partial P}\right)_T = \left(\frac{\partial V}{\partial T}\right)_P.$$

위 rectangle
한번 가능.

(*) General relationship between C_v and C_p . through Maxwell relation

$$\cdot dE = \delta Q + \delta W = TdS - PdV$$

$$\cdot \delta Q|_v = TdS = C_v dT \quad (dv=0)$$

$$\cdot \delta Q|_p = dE + PdV = d(E + PV) = dH|_p = C_p dT \quad (dp=0)$$

$$\begin{cases} C_p = T \left(\frac{\partial S}{\partial T} \right)_p \\ C_v = T \left(\frac{\partial S}{\partial T} \right)_v \end{cases} \Rightarrow \delta Q = TdS(T, P) = \underbrace{T \left(\frac{\partial S}{\partial T} \right)_p}_{C_p} dT + \underbrace{T \left(\frac{\partial S}{\partial P} \right)_T}_{= \left(\frac{\partial P}{\partial T} \right)_v^{-1} dT + \left(\frac{\partial P}{\partial V} \right)_T^{-1} dV} dP(T, v)$$

$$\therefore \delta Q = \left[C_p + T \cdot \left(\frac{\partial S}{\partial P} \right)_T \left(\frac{\partial P}{\partial T} \right)_v \right] dT + T \cdot \left(\frac{\partial S}{\partial P} \right)_T \left(\frac{\partial P}{\partial V} \right)_T dV$$

$$\text{if } dV = 0, \delta Q = C_v dT. \Rightarrow C_v = C_p + T \left(\frac{\partial S}{\partial P} \right)_T \left(\frac{\partial P}{\partial T} \right)_v$$

→ But, $\frac{\partial S}{\partial P}$ 같은 항은 다뤄야 하므로, Maxwell relation 이용하자.

$$\text{we know, } \left(\frac{\partial S}{\partial P} \right)_T = - \left(\frac{\partial V}{\partial T} \right)_P = -\alpha V. \quad \alpha \equiv \frac{1}{V} \cdot \left(\frac{\partial V}{\partial T} \right)_P \dots \text{Isobaric expansion coefficient}$$

$$\left(\frac{\partial P}{\partial T} \right)_v \text{ 등, } T \text{가 늘어남에 따라 } P \text{가 증가, 즉 } \alpha \text{가 양수. (꼭 그런 실린거 가릴!)}$$

$$\text{지금 조건에서, } dV = 0 = \left(\frac{\partial V}{\partial T} \right)_P dT + \left(\frac{\partial V}{\partial P} \right)_T dP$$

$$\Rightarrow \left(\frac{\partial P}{\partial T} \right)_v = - \frac{\left(\frac{\partial V}{\partial T} \right)_P}{\left(\frac{\partial V}{\partial P} \right)_T} = \frac{-\alpha V}{-kV} = \frac{\alpha}{k}. \quad k \equiv - \frac{1}{V} \cdot \left(\frac{\partial V}{\partial P} \right)_T \dots \text{Isothermal compressibility}$$

$$\therefore C_p - C_v = VT \cdot \frac{\alpha^2}{k} \quad \left(\because T \cdot -\alpha V \cdot \frac{\alpha}{k} \right)$$

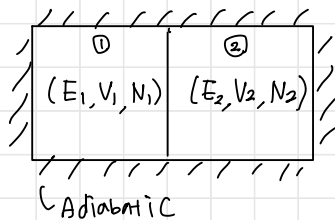
→ For any material

$$(eg) PV = Nk_B T \text{ (Ideal gas)}, V = \frac{Nk_B T}{P} \text{ 이므로 } \alpha \equiv \frac{1}{V} \cdot \left(\frac{\partial V}{\partial T} \right)_P = \frac{Nk_B}{PV} = \frac{1}{T}$$

$$\Rightarrow C_p - C_v = VT \left[\left(\frac{1}{P} \right) \times \frac{1}{T^2} \right] = \frac{PV}{T} = Nk_B \quad k \equiv - \frac{1}{V} \left(\frac{\partial V}{\partial P} \right)_T = \frac{1}{V} \cdot \frac{Nk_B T}{P^2} = \frac{1}{P}$$

$$\therefore C_p - C_v = Nk_B$$

4.4) Equilibrium Conditions



• 총 각자 분리된 평형에서, Partition 통해 E, V, N 변화.

• In Final, equilibrium,

$$\delta S_{\text{tot}} = \delta S_1 + \delta S_2(E_2, V_2, N_2)$$

$$= \left(\frac{\partial S_1}{\partial E_1} \delta E_1 + \frac{\partial S_1}{\partial V_1} \delta V_1 + \frac{\partial S_1}{\partial N_1} \delta N_1 \right) + \left(\frac{\partial S_2}{\partial E_2} \delta E_2 + \frac{\partial S_2}{\partial V_2} \delta V_2 + \frac{\partial S_2}{\partial N_2} \delta N_2 \right)$$

where $\delta S_1 = -\delta S_2$, $\delta V_1 = -\delta V_2$, $\delta N_1 = -\delta N_2$

대입해서 $\delta E_1, \delta V_1, \delta N_1$ 모두 정리하면

$$\Rightarrow \left(\frac{1}{T_1} - \frac{1}{T_2} \right) \delta E_1 + \left(\frac{P_1}{T_1} - \frac{P_2}{T_2} \right) \delta V_1 - \left(\frac{\mu_1}{T_1} - \frac{\mu_2}{T_2} \right) \delta N_1 \geq 0.$$

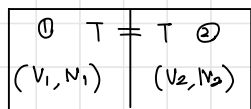
• If $T_1 > T_2$, $\delta E_1 < 0 \Rightarrow T_1 = T_2 \dots$ Thermal equilibrium

• If $P_1 > P_2$, $\delta V_1 > 0 \Rightarrow P_1 = P_2 \dots$ mechanical equilibrium

• If $\mu_1 > \mu_2$, $\delta N_1 < 0 \Rightarrow \mu_1 = \mu_2 \dots$ Chemical equilibrium

(*) Helmholtz energy는 eq condition Zylinder.

$\Rightarrow$ Isothermal Condition.



Heat bath

$$\delta F_{\text{tot}} = \delta F_1 + \delta F_2$$

$$= \left(\frac{\partial F_1}{\partial V_1} \delta V_1 + \frac{\partial F_2}{\partial V_2} \delta V_2 \right) = -(P_1 - P_2) \delta V_1 \leq 0.$$

If $P_1 > P_2$, $\delta V_1 > 0 \rightarrow P_1 = P_2$

4.5) Euler's equation

• $dE = TdS - PdV + \mu dN \rightarrow E(S, V, N)$

if we change the size of the system: $E(\alpha S, \alpha V, \alpha N) = \alpha E$.

$$\Rightarrow E((1+\epsilon)S, (1+\epsilon)V, (1+\epsilon)N) = E(S, V, N) + \frac{\partial E}{\partial S} \epsilon S + \frac{\partial E}{\partial V} \epsilon V + \frac{\partial E}{\partial N} \epsilon N$$

$$= E(S, V, N) + \epsilon(TS - PV + \mu N) = (1+\epsilon)E.$$

$$\therefore E = TS - PV + \mu N$$

... Euler's equation

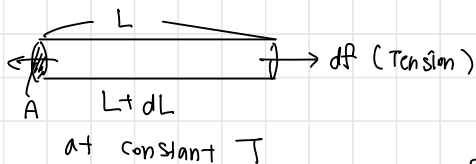
derivative $\rightarrow dE = TdS + SdT - PdV - VdP + \mu dN + Nd\mu$

So, $SdT - VdP + Nd\mu = 0$... Gibbs' Duhem relation (?)

→ Not independent, somehow related (?)

4.6) Examples

#1. Elastic rod



• Young's modulus

$$\gamma = \frac{\sigma}{\epsilon} = \frac{\frac{df}{A}}{\frac{dL}{L}} = \frac{L}{A} \left(\frac{\partial f}{\partial L} \right)_T$$

• We know α (expansion coefficient at constant f)

$$\alpha_f = \frac{1}{L} \left(\frac{\partial L}{\partial T} \right)_f \quad \updownarrow \quad P$$

→ Isothermal expansion $\Leftrightarrow$ 분자해방.

• $dE = TdS + \underbrace{fdL}_{dW_{other}} \rightarrow dW_{other}$

• Isothermal work $dF = d(E - TS) \Rightarrow dF(T, L) = -SdT + f dL$

$$= \left(\frac{\partial F}{\partial T} \right)_L dT + \left(\frac{\partial F}{\partial L} \right)_T dL$$

$$\therefore S = - \left(\frac{\partial F}{\partial T} \right)_L \quad f = \left(\frac{\partial F}{\partial L} \right)_T$$

Maxwell relation $\rightarrow \left(\frac{\partial S}{\partial L} \right)_T = - \left(\frac{\partial f}{\partial T} \right)_L = \left(\frac{\partial f}{\partial L} \right)_T \left(\frac{\partial L}{\partial T} \right)_f = \left(\frac{\gamma A}{L} \right) (L \alpha_f) = \gamma A \alpha_f$

So, $\Delta Q = T \Delta S = T \cdot \gamma A \alpha_f (\Delta L) > 0$ if $\alpha_f > 0$.

→ Polymer: $\rightarrow$ reduce. < 0 if $\alpha_f < 0$

#2 Paramagnetism

(Independent magnetic moment)

$$dE = TdS - MdH \quad (M = \text{total magnetic moment} \approx nV)$$

$$\chi \equiv \lim_{H \rightarrow 0} \frac{M}{H} \quad (\text{magnetic susceptibility}) \rightarrow m = \chi \cdot H \quad (\text{small volume})$$

• Isothermal magnetization. ($H \uparrow$)

$$\Rightarrow dF = d(E - TS) = -SdT - MdH = \left(\frac{\partial F}{\partial T} \right)_H dT + \left(\frac{\partial F}{\partial H} \right)_T dH$$

$$\therefore S = - \left(\frac{\partial F}{\partial T} \right)_H \quad M = - \left(\frac{\partial F}{\partial H} \right)_T \quad \text{Constant (V, \epsilon, \mu, \text{etc.})}$$

$$\longrightarrow \left(\frac{\partial S}{\partial H} \right)_T = \left(\frac{\partial M}{\partial T} \right)_H = \left(\frac{\partial \chi H V}{\partial T} \right)_H = H \cdot V \left(\frac{\partial \chi}{\partial T} \right)_H$$

$$\text{From Curie's Law, } \chi \propto \frac{1}{T} \Rightarrow \left(\frac{\partial S}{\partial H} \right)_T = H V \cdot \underbrace{\left(\frac{\partial \chi}{\partial T} \right)_H}_{(-) \text{ abh.}} < 0.$$

$$\Rightarrow \Delta Q = T \Delta S = H V \cdot \left(\frac{\partial \chi}{\partial T} \right)_H \cdot \Delta H < 0 \quad (-) \text{ abh.}$$

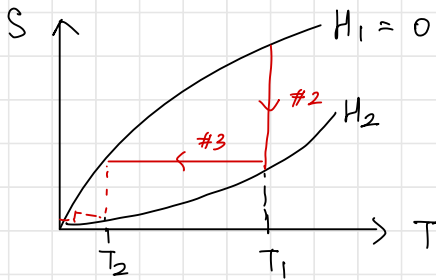
#3. Adiabatic demagnetization

$$\text{From \#2, } dS(T, H) = \left(\frac{\partial S}{\partial T} \right)_H dT + \left(\frac{\partial S}{\partial H} \right)_T dH = 0. \quad (\text{Adiabatic})$$

$$\left(\frac{\partial T}{\partial H} \right)_S = \frac{- \left(\frac{\partial S}{\partial H} \right)_T}{\left(\frac{\partial S}{\partial T} \right)_H} = \frac{- H V \left(\frac{\partial \chi}{\partial T} \right)_H}{\frac{C_H}{T}} = - \frac{T H V}{C_H} \left(\frac{\partial \chi}{\partial T} \right)_H > 0$$

$$(\because C_H \equiv \left(\frac{dQ}{dT} \right)_H = T \left(\frac{\partial S}{\partial T} \right)_H)$$

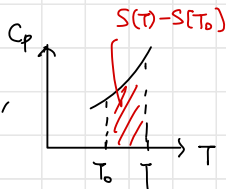
$\Rightarrow$ Demagnetization $\longrightarrow$ cooling



~ Midterm

4.7) The Third Law

One notices $C_p = T \cdot \left(\frac{\partial S}{\partial T} \right)_p \Rightarrow S(T) - S(T_0) = \int_{T_0}^T \frac{C_p(T')}{T'} dT'$



Q. What is reference value? $\rightarrow$ Third law: $S(T=0)$ as ref.

$(S = k_B \cdot \ln \Omega(E))$
 $(E \rightarrow E_0 : \underline{\Omega(E_0) = 1} \Leftrightarrow \text{Non-degenerate ground state})$ (Quantum mechanics only $E \leq E_1$)
 $\rightarrow$ What about degeneracy?

$\Rightarrow$ As $T \rightarrow 0$, $S \rightarrow 0$

... The Third Law

$$(cf) \quad \Delta G = \Delta H - T \Delta S$$

Plank: $T \rightarrow 0; S \rightarrow 0 \quad \frac{S}{T} = \frac{1}{T}$
In internal equilibrium

(반론) Nuclear spins : Crystal $\frac{h^2}{8\pi^2 I}$ $\langle T \sim T_0 \rangle$

$I \rightarrow 2I+1$
 $\Rightarrow \frac{1}{2} \rightarrow 2 \cdot \frac{1}{2} + 1 = 2$

very weak spin-spin interaction

 $\Omega = 2^N, S_0 = N \cdot k_B \ln 2$

$\hookrightarrow T \rightarrow 0$ 이면 $\uparrow - \uparrow - \uparrow - \uparrow$
 $(T \ll T_0)$

Interaction each other가 강한 영향

$$\Rightarrow A \rightarrow T \rightarrow 0, S \rightarrow S_0 \text{ (가장 낮은 aspect)} \\ = 0$$

(*) Classical system

$$\Omega = \frac{1}{h_0^N} \int d\vec{p}_1 d\vec{p}_2 \dots d\vec{p}_N \int d\vec{g}_1 d\vec{g}_2 \dots d\vec{g}_N$$

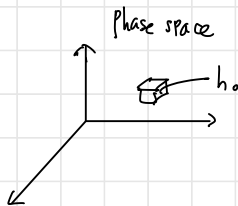
$$\Rightarrow S = K_B \cdot \ln \left[\frac{1}{h_0} \int d\vec{P}_1 \int d\vec{\theta}_1 \right]^N$$

$$= N K_B \cdot \ln \left[\int d\vec{P} \int d\vec{\theta} \right] - N \cdot K_B \ln h_0.$$

(cf) Simon's 3rd Law Statement

- The Contribution to the entropy of a system by each aspect of the system which is in (= different subsystem) the internal

thermodynamic equilibrium
tends to Zero as $T \rightarrow 0$



(*) Consequences

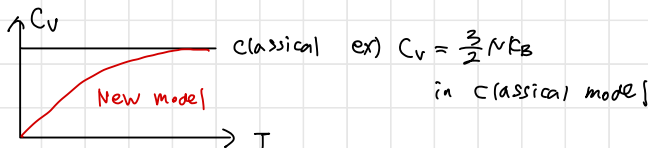
$$ii) S(T=0, X) \rightarrow 0 \quad \left(\frac{\partial S}{\partial X}\right)_T \rightarrow 0 \quad \text{as } T \rightarrow 0$$

$$g) C_x = T \cdot \left(\frac{\partial S}{\partial T} \right)_x = \left(\frac{\partial S}{\partial \ln T} \right)_x = 0$$

$$(\ln T \rightarrow -\infty \quad S \rightarrow 0.)$$

ii) $S(T, X) - S(T=0, X) = \int_0^T \frac{C_X(T')}{T'} dT'$ $T'=0$ and $\frac{1}{T'}$ diverges, so

$$\therefore \lim_{T \rightarrow 0} C_X(T) \rightarrow 0$$



$$\text{iii)} \left(\frac{\partial S}{\partial P} \right)_T = 0 \Leftrightarrow \alpha = \frac{1}{V} \cdot \left(\frac{\partial V}{\partial T} \right)_P = 0$$

at $T \rightarrow 0$.

Thermal expansion stops.

$$\text{iv)} S = C_v \ln T + R \ln V + \text{const}$$

$$C_p - C_v = R$$

No ideal gas at $T \rightarrow 0$

$$C_v \rightarrow 0, \ln T \rightarrow -\infty$$

$$\text{v)} \text{ Curie's Law } \left(\chi \propto \frac{1}{T} \right) \sim -\frac{c}{T^2}$$

$$\left(\frac{\partial S}{\partial H} \right)_T = \left(\frac{\partial M}{\partial T} \right)_H = V H \left(\frac{\partial \chi}{\partial T} \right)_H$$

$\rightarrow$ breaks down

$\downarrow$ by 3rd Law

0

$\Leftarrow T \rightarrow 0 \Rightarrow$ diverge

$\downarrow$

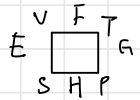
diverge

$T \rightarrow 0$,

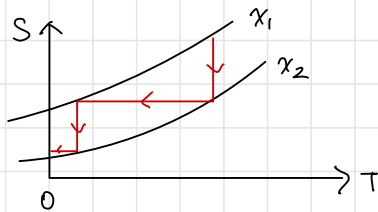
Interaction이 중요해지

기존의 유효했던 법칙/model이

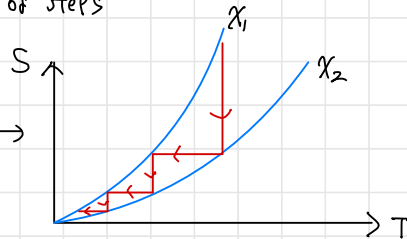
breaks down.



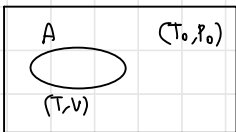
vi) Never reach $T=0$ in a finite numbers of steps



$\left(\begin{array}{l} \text{but } T=0 \\ \text{if } S \rightarrow 0 \end{array} \right)$
Third Law



4.8) Stability



N : fixed. (T, V) 변화 가능

$$\Rightarrow G = E - T_0 S + P_0 V$$

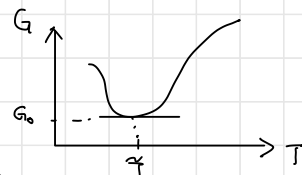
Q. Carnot engine with $T_L = 0$?

$$\epsilon = 1 - \frac{T_L}{T_H} = 1, \text{ Kelvin Violator?}$$

$\Rightarrow$ 3법칙은 2법칙과 다른, 독립적인 법칙.

i) $V \rightarrow$ fixed. $T \rightarrow$ Fluctuates around $\tilde{T}$

$$\Rightarrow G(T) = G_0(\tilde{T}) + \left(\frac{\partial G}{\partial T} \right)_V \Delta T + \frac{1}{2} \left(\frac{\partial^2 G}{\partial T^2} \right)_V (\Delta T)^2 + \dots$$



$$\Rightarrow \left(\frac{\partial G}{\partial T} \right)_{V, T=\tilde{T}} = 0 = \left(\frac{\partial E}{\partial T} \right)_V - T_0 \left(\frac{\partial S}{\partial T} \right)_V = \left(1 - \frac{T_0}{T} \right) \left(\frac{\partial E}{\partial T} \right)_V \Big|_{T=\tilde{T}}$$

$$\therefore \tilde{T} = T_0$$

평형온도

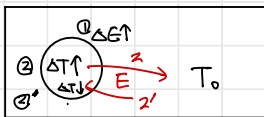
$$(T dS = dE + P dV)$$

↪ Either max / min 72. min = 2 평형 (which mean stability)

$$\left(\frac{\partial^2 G}{\partial T^2}\right)_V \geq 0 \Rightarrow \left[\frac{T_0}{T^2} \left(\frac{\partial E}{\partial T}\right)_V + \left(1 - \frac{T_0}{T}\right) \left(\frac{\partial E}{\partial T^2}\right)_V\right] \geq 0$$

$$\therefore \left(\frac{\partial E}{\partial T}\right)_V \geq 0 \quad \text{or} \quad C_V \geq 0$$

... Le Chatelier's principle.



ii) T fixed ($T = T_0$) V fluctuates around $\tilde{V}$

$$\Rightarrow G(V) = G_0(\tilde{V}) + \left(\frac{\partial G}{\partial V}\right)_T \Delta V + \frac{1}{2} \left(\frac{\partial^2 G}{\partial V^2}\right)_T (\Delta V)^2 + \dots$$

$$\Rightarrow \left(\frac{\partial G}{\partial V}\right)_T = 0 = \left(\frac{\partial E}{\partial V}\right)_T - T_0 \left(\frac{\partial S}{\partial V}\right)_T + P_0 \quad dE = TdS - PdV$$

$$= (T - T_0) \left(\frac{\partial S}{\partial V}\right)_T - (P - P_0)$$

$$\therefore P = P_0 \quad \text{평형조건}$$

$$\left(\frac{\partial^2 G}{\partial V^2}\right)_T \geq 0 \Rightarrow -\left(\frac{\partial P}{\partial V}\right)_T \geq 0 \quad \text{or} \quad K \geq 0. \quad (\text{Remind: } K = -\frac{1}{V} \cdot \left(\frac{\partial V}{\partial P}\right)_T)$$

iii) Density fluctuations. (?)

$$\text{Density } n = \frac{N}{V} \Rightarrow \text{mean value } \tilde{n} = \frac{N}{\tilde{V}}$$

$$\tilde{V} - V$$

$$\Delta n = n - \tilde{n} = N \cdot \left(\frac{1}{V} - \frac{1}{\tilde{V}}\right) = -\frac{\tilde{n} \Delta V}{\tilde{V}} \quad \left(= \frac{N}{\tilde{V}} \cdot \left(\frac{-\Delta V}{V}\right)\right)$$

$$\Rightarrow \langle (\Delta n)^2 \rangle = \left(\frac{\tilde{n}}{\tilde{V}}\right)^2 \langle (\Delta V)^2 \rangle$$

$$\Rightarrow p(V) dV \propto e^{-\beta G(V)} dV \quad \text{where} \quad G(V) = G_0(\tilde{V}) + \frac{1}{2} \left(\frac{\partial^2 G}{\partial V^2}\right)_T (\Delta V)^2$$

$$= \frac{1}{2} \frac{1}{\tilde{V} K} (\Delta V)^2$$

$$\Rightarrow p(V) dV = B \cdot \exp\left[-\frac{1}{2} \cdot \frac{(\Delta V)^2}{K_B T_0 \tilde{V} K}\right] dV$$

$$\langle (\Delta V)^2 \rangle = K_B T_0 \tilde{V} K.$$

$$\text{For critical point: } \left(\frac{\partial P}{\partial V}\right)_T = 0.$$

$$\therefore \langle (\Delta n)^2 \rangle \propto K.$$

$$\Rightarrow K \rightarrow \infty, \quad \langle (\Delta n)^2 \rangle \rightarrow \infty.$$

5. Phase Transitions

5.1) Phase equilibrium

- a single component system of two phases; 1 & 2 at constant T & P

⇒ Gibbs Potential

⇒ Can exist together (coexist or mixed)

$$G = E - TS + PV$$

$$\Rightarrow G = g_1 N_1 + g_2 N_2$$

g_i : i Phase's Gibbs energy per particle.

is minimized at equilibrium

N_i : numbers of particle in phase i

$$dG = VdP - SdT + \sum \mu_i dN_i = g_2$$

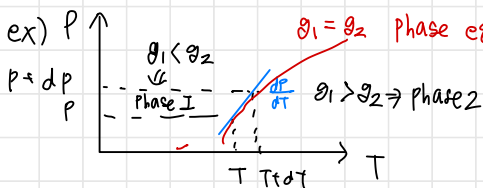
$$\langle \text{At equilibrium} \rangle dG = 0 \Rightarrow g_1 dN_1 + g_2 dN_2 = 0 \quad (N_1 + N_2 = N)$$

(Sec 22.5)

$$\Rightarrow (g_1 - g_2) dN_1 = 0$$

$$g_1(T, P) = g_2(T, P)$$

... Def of Coexistence of 2 Phases (Phase equilibrium)



⇒ Coexist at phase boundary ($g_1 = g_2$ for (T, P))

$$\Rightarrow g_1(T+dT, P+dP) = g_2(T+dT, P+dP)$$

$$\Rightarrow g_1(T, P) + \left(\frac{\partial g_1}{\partial T}\right) dT + \left(\frac{\partial g_1}{\partial P}\right) dP$$

$$= g_2(T, P) + \left(\frac{\partial g_2}{\partial T}\right) dT + \left(\frac{\partial g_2}{\partial P}\right) dP$$

$$(s_1 - s_2) dT + (v_2 - v_1) dP = 0$$

$$\Rightarrow dE = Tds - PdV \Rightarrow dg(T, P) = -s dT + v dP$$

$$\therefore \frac{dP}{dT} = \frac{s_2 - s_1}{v_2 - v_1} = \frac{\Delta S}{\Delta V}$$

small s → Entropy per particle → Volume per particle

Clausius - Clapeyron equation.

$$\text{Remind) } C_x = T \cdot \left(\frac{\partial S}{\partial T}\right)_x, \quad L \equiv \Delta Q_{\text{rev}} = T \Delta S \quad (\text{Latent heat}) \quad (x = P, V, H \dots)$$

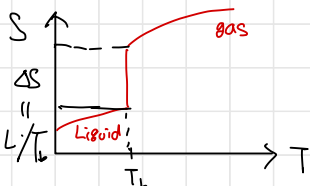
$$\frac{dP}{dT} = \frac{\Delta S}{\Delta V} = \frac{\Delta S \cdot N}{\Delta V} = \frac{L/N}{T \Delta V} = \frac{l}{T \cdot \Delta V} = \frac{L}{T \cdot \Delta V}$$

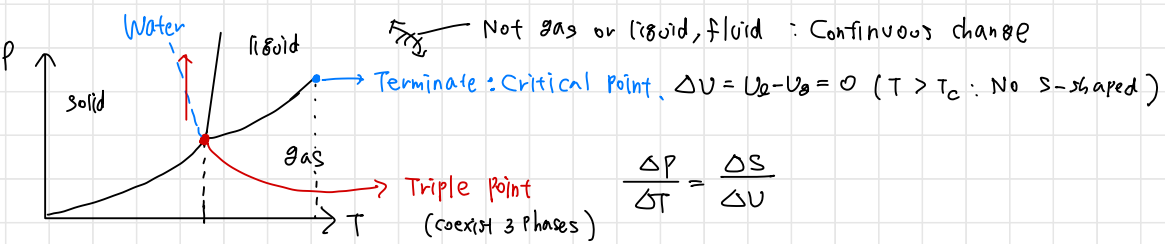
→ C_p at $T = T_c$ is spike.

$$(l \equiv T \Delta S = T \cdot \frac{\Delta S}{N} = \frac{L}{N})$$

$$(C) \quad dP = \frac{L}{T \Delta V} dT \Rightarrow \Delta P = \frac{L}{\Delta V} \cdot \ln\left(\frac{T}{T_0}\right) \quad (\because L, \Delta V \text{ T independent})$$

$$\therefore P = P_0 + \frac{L}{\Delta V} \ln\left(\frac{T}{T_0}\right) \rightarrow \frac{dP}{dT} \text{ is steep for Liquid-Solid phase boundary}$$





<Typical phase diagram>

ex) Vapor pressure: Determine phase boundary of liquid and gas (L = temperature independent) ^{NE}

gas
liquid

$$\frac{dP}{dT} = \frac{l}{T\Delta V} = \frac{l}{T V_2}$$

An ideal gas $\Rightarrow P V_2 = k_B T$. (양변 N 곱)

$$\int \frac{dP}{P} = \frac{l dT}{k_B T^2} \quad \left(\frac{dP}{dT} = \frac{l P}{k_B T^2} \right)$$

($\Delta U = U_2 - U_1 \approx U_2$ where $U_2 \gg U_1$)

$$\Rightarrow \ln P = -\frac{1}{k_B T} \therefore P = P_0 \exp\left(-\frac{l}{k_B T}\right)$$

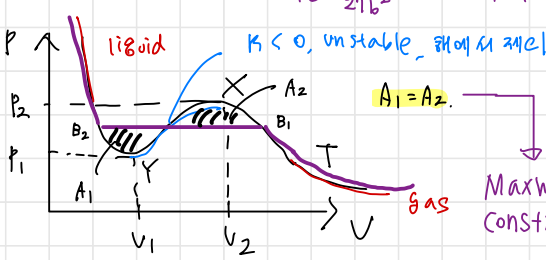
5.2. The van der Waals gas

이상기체 $\Rightarrow$ 무시한 interaction X. 다른 model 필요.

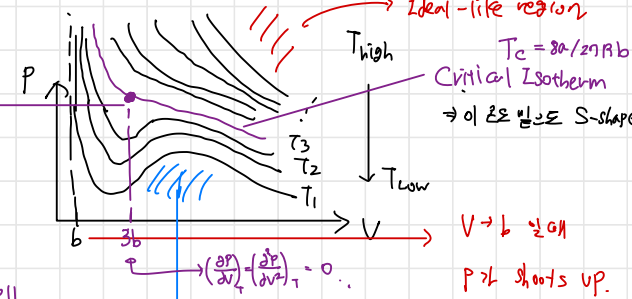
- The equation of state, for the vdw gas of one mole.

$$\left(P + \frac{a}{V^2}\right)(V - b) = \beta T. \quad \Leftrightarrow P V^3 - (P b + \beta T) V^2 + a V - a b = 0 \quad \Rightarrow P V = \beta T$$

intermolecular interaction excluded volume



$$P_c = \frac{a}{27b^2} \text{ Critical point}$$



For $P > P_2$, $\left(\frac{\partial P}{\partial V}\right)_T \leq 0 \rightarrow K = -\frac{1}{V} \left(\frac{\partial V}{\partial P}\right)_T \geq 0 \Rightarrow \text{stable}.$

Where $\left|\frac{\partial P}{\partial V}\right|_T$ is small $\Rightarrow K$ is large. $\Rightarrow$ gas

Where $\left|\frac{\partial P}{\partial V}\right|_T$ is large $\Rightarrow K$ is small $\Rightarrow$ liquid.

(Q) $K = -\frac{1}{V} \left(\frac{\partial V}{\partial P}\right)_T$

가 양/음에 따라 달라짐.

$\Rightarrow K < 0$ 은 불안정 (unstable)

P fluctuation에, $K < 0$ 이면 $P \uparrow \Rightarrow V \uparrow$.

Then, $\left(\frac{\partial V}{\partial P}\right)_T > 0$ $\Rightarrow$ 불안정성: P 대 T .

$dw = -P dV < 0$.

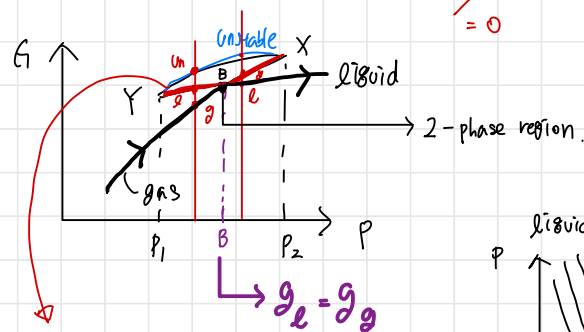
instability

For $P_1 < P < P_2$ $dG = -SdT + VdP \Rightarrow G(P_2, T) - G(P_1, T) = \int_{P_1}^{P_2} VdP$
 $= 0$

$= (\text{Area between } V(P) \text{ and } P \text{ axis})$

$(\because V = (\frac{\partial G}{\partial P})_T)$

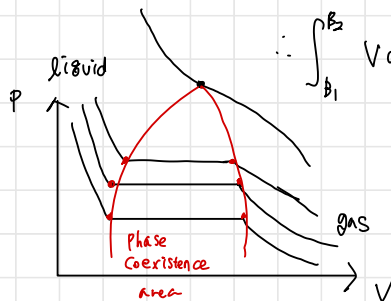
$\therefore \int_{P_1}^{P_2} VdP = 0$



metastable

superheated liquid

supercooled Vapor

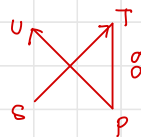
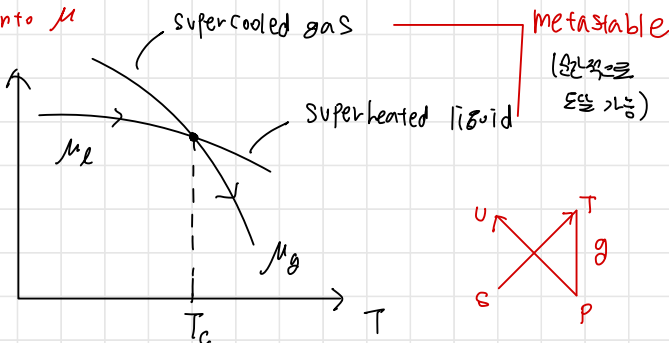
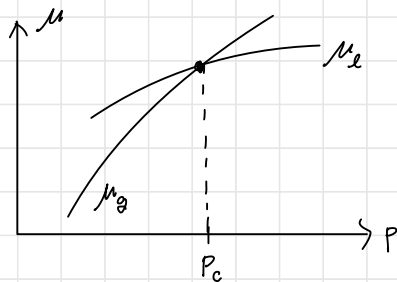


5.3. Nucleation

At constant T, P , $G = E - TS + PV$ ($dE = TdS - PdV + \sum \mu_i dN_i$)

$\Rightarrow dG = -SdT + VdP + \sum \mu_i dN_i = \mu_1 dN_1 + \mu_2 dN_2 = (\mu_1 - \mu_2) dN_1 = 0$
 $= 0$

$\therefore \mu_1 = \mu_2$... Rewriting μ into μ

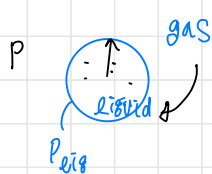


$\Rightarrow (\frac{\partial \mu}{\partial P})_T = v > 0$

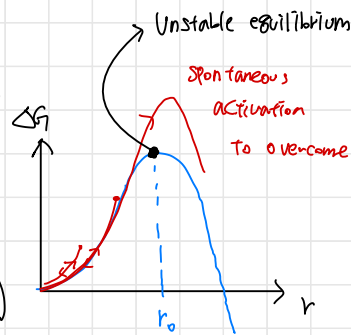
$\Rightarrow (\frac{\partial \mu}{\partial T})_P = -S < 0$

Q. Why the thermodynamically most stable state sometime doesn't form

$\Rightarrow$ Suppose a liquid droplet in equilibrium with vapor



$\Delta G = \gamma \cdot A + (\mu_l - \mu_g) \cdot V \cdot \frac{P_{\text{ext}}}{m}$
 $= 4\pi\gamma r^2 - (\Delta\mu) \cdot \frac{P_{\text{ext}}}{m} \cdot \frac{4\pi r^3}{3} \quad (\Delta\mu = \mu_g - \mu_l > 0)$



5.4. Gibbs Phase rule.

$$dG = \sum \mu_i dN_i + \sum \mu_j dV_j + \sum \mu_k dA_k$$

$$\left. \frac{dG}{dT} \right|_{P, N} = 0$$

Consider a multi component, multi phase system. $\left\{ \begin{array}{l} J = 1, 2, \dots, J \text{ Component} \\ K = 1, 2, \dots, K \text{ Phases} \end{array} \right\}$

↳ different substances

(solid, liquid, gas, ferro/paramagnetic, superconducting ...)

(T, P) is fixed (controlled)

$$\sum_{j=1}^J C_j = C \quad (\text{Total concentration}) \quad \theta_j = \frac{C_j}{C}$$

$$\left[(J-1) \times (K-1) \right] \times (K-1) \times J$$

$$\Rightarrow D = \left[2 + (J-1)K \right] - (K-1)J$$

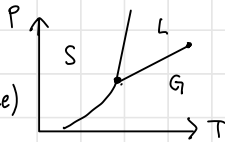
$$= 2 + J - K \quad \dots \text{Gibbs phase rule}$$

For J , Gibbs equilibrium $\mu_1 = \mu_2 = \dots = \mu_J$ $\rightarrow$ For J substances

a) $J=1, K=1$ (Water) $\Rightarrow D=2$.

$J=1, K=2$ (S&L, S&G, L&G) $\Rightarrow D=1$ (line)

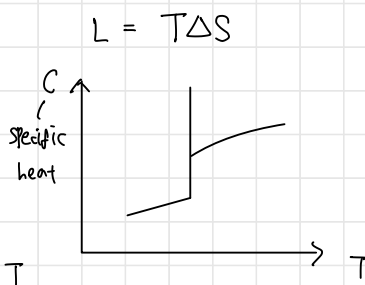
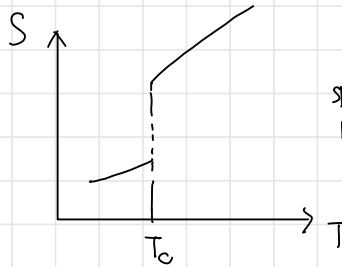
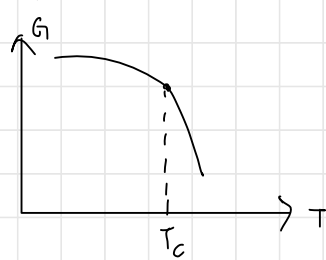
$J=1, K=3$ $\Rightarrow D=0$



5.5. Classification of Phase Transitions

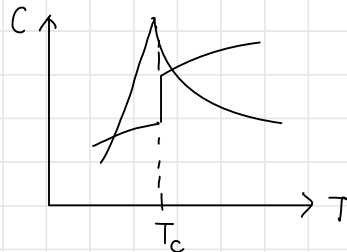
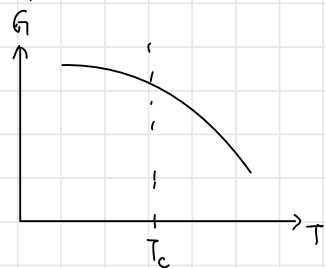
Ehrenfest's rule

i) 1st-order



$\Rightarrow$ Discontinuous phase

ii) 2nd-order (2nd and higher-order $\Rightarrow$ Continuous phase transition)



CH 5 & 6.

$$g(v_x) \sim e^{-\beta E} = e^{-\frac{1}{2} m v_x^2 / k_B T} (v_x, v_x + dv_x) \quad \left. \vphantom{g(v_x)} \right\} v_x : -\infty \text{ to } \infty$$

$$g(v_x) = \sqrt{\frac{m}{2\pi k_B T}} e^{-\frac{m v_x^2}{2 k_B T}}$$

Same to v_y, v_z

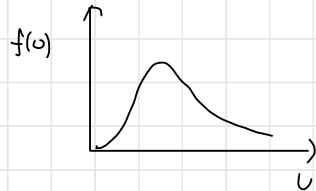
$$\Rightarrow g(\vec{v}) = g(v_x)g(v_y)g(v_z) dv_x dv_y dv_z \\ \sim \exp\left(\frac{1}{2} m v^2 / k_B T\right) dv_x dv_y dv_z$$

$$V = 4\pi v^2 dv. \quad f(v) dv \propto V \cdot g(\vec{v}) \\ = v^2 \cdot \exp\left(-\frac{m v^2}{2 k_B T}\right)$$

Normalize $\rightarrow f(v) dv = \frac{4}{\sqrt{\pi}} \cdot \left(\frac{m}{2 k_B T}\right)^{\frac{3}{2}} \cdot v^2 \cdot \exp\left(-\frac{m v^2}{2 k_B T}\right) dv. \quad \dots \text{M.B speed distribution}$

$v_{max} \langle v \rangle \{ v_{rms}$

$$\langle v \rangle = \sqrt{\frac{8 k_B T}{\pi m}} \quad \langle v^2 \rangle = \frac{3 k_B T}{m}$$



III. Kinetic Theory.

0. Brief Introduction

- Classical Mechanics : Newtonian, Hamiltonian. (결정론적)
- $(\vec{P}, \vec{Q}) = (p_1, \dots, p_{3N}, q_1, \dots, q_{3N}) \in \mathbb{R}^{6N}$ where $\dot{q}_i = \frac{\partial H}{\partial p_i}$ $\dot{p}_i = -\frac{\partial H}{\partial q_i}$ (1st, kinetic Theory)
- Thermodynamics : Carnot, Clausius, Maxwell, Gibbs...
- $(t \rightarrow -t, \text{same symmetry}) \Rightarrow \text{impossible}$
- $E, N, T, V, P, \dots \Rightarrow \text{Equation of states : Phenomenological Laws (Empirical)}$
- $\longrightarrow S, W, Q$
- Boltzmann

• Statistical Mechanics : ?

- Phase space (6N-D) collection of N -state point.
- $\Rightarrow \text{same } (E, V, N) \text{ macro state}$
- time evolution
- Phase trajectory
- Ensemble
- (E, V, N)
- different configuration
- (E, V, N)
- $\Rightarrow \text{Density function } \rho(\vec{P}, \vec{Q}, t) : \Omega \text{에 퍼져있는 Macrostate 복수개의 weight function (?) 집합 (but different microstate)}$
- $\rho \cdot d\Gamma = \lim_{N \rightarrow \infty} \frac{dN}{N}$

1. Liouville Theorem

- Consider a closed system of N classical particles
- A set of representative points $(\vec{P}, \vec{Q}) \Rightarrow \text{Gibbs (Statistical) Ensemble}$
- Phase space Probability density.

$\Rightarrow \int \frac{d\vec{P} \cdot d\vec{Q}}{N! h^{3N}} \rho(\vec{P}, \vec{Q}, t) : \text{Probability that your system is in the volume element around } (\vec{P}, \vec{Q})$

= 1 (Normalized)

(*) Time evolution of $\rho(\vec{P}, \vec{Q}, t)$

$$\frac{dn}{dt} = \frac{d}{dt} \int N \rho(\vec{P}, \vec{Q}, t) d\vec{P} d\vec{Q} = N \cdot \int_V \frac{\partial \rho}{\partial t} d\vec{P} d\vec{Q} = -N \cdot \int_{\partial V} (\rho \vec{u}) \cdot \hat{n} dS \quad (\vec{u} = (\dot{\vec{P}}, \dot{\vec{Q}}))$$

Phase velocity

$$= -N \cdot \int_V \nabla \cdot (\rho \vec{u}) d\vec{P} d\vec{Q}$$

$$(\nabla \equiv \sum_i \left(\frac{\partial}{\partial p_i} \hat{p}_i + \frac{\partial}{\partial q_i} \hat{q}_i \right)) \quad (*)$$

$$\therefore \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0$$

$$\Rightarrow \frac{\partial \rho}{\partial t} + \rho \cdot (\nabla \cdot \vec{u}) + \vec{u} \cdot (\nabla \rho) = 0$$

$$\Rightarrow \frac{\partial \rho}{\partial t} + \sum_{i=1}^3 \rho \cdot \left(\frac{\partial \dot{g}_i}{\partial g_i} + \frac{\partial \dot{p}_i}{\partial p_i} \right) + \sum_i \left(\frac{\partial \rho}{\partial g_i} \cdot \dot{g}_i + \frac{\partial \rho}{\partial p_i} \cdot \dot{p}_i \right) = 0$$

$$= \frac{\partial^2 H}{\partial p_i \partial g_i} - \frac{\partial^2 H}{\partial g_i \partial p_i} = 0 \quad = \frac{\partial \rho}{\partial g_i} \cdot \frac{\partial H}{\partial p_i} - \frac{\partial \rho}{\partial p_i} \cdot \frac{\partial H}{\partial g_i} \rightarrow \text{Koszul Bracket.}$$

$$\begin{cases} \dot{g}_i = \frac{\partial H}{\partial p_i} \\ \dot{p}_i = -\frac{\partial H}{\partial g_i} \end{cases}$$

$$\therefore \frac{\partial \rho}{\partial t} + \{ \rho, H \} = 0 \quad \dots \text{Liouville theorem } (\Leftrightarrow \frac{\partial \rho}{\partial t} = 0)$$

$$= i \hat{L} \rho \quad (L \equiv \text{Liouville Operator})$$

- Consider $A(\vec{p}, \vec{g}, t)$

$$\Rightarrow \frac{dA}{dt} = \frac{\partial A}{\partial t} + \sum_i \left(\frac{\partial A}{\partial g_i} \dot{g}_i + \frac{\partial A}{\partial p_i} \dot{p}_i \right) = \frac{\partial A}{\partial t} + \{A, H\} = \frac{\partial A}{\partial t} + i \hat{L} A$$

Liouville operator
(?)

$$\therefore \frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + i \hat{L} \rho = 0$$

ρ is constant along the trajectory in phase space. (맥스웰이)

$\therefore$ Phase space density ρ is time invariant. (Incompressible)

$$\Rightarrow \frac{\partial \rho}{\partial t} + i \hat{L} \rho = 0 \quad \Leftrightarrow \quad \rho(\vec{p}, \vec{g}, t) = e^{-i \hat{L} t} \cdot \rho(\vec{p}, \vec{g}, 0) \quad \text{where } \hat{L} \rho_\alpha = \lambda_\alpha \rho_\alpha$$

$$= \sum_\alpha c_\alpha \cdot e^{-i \lambda_\alpha t} \rho_\alpha \quad \text{Hermitian } \in \mathcal{B}$$

Poincaré recurrence theorem

$\Rightarrow$ Time - Reversal symmetry : Not consistent with daily life observation

(*) Average of $\langle A \rangle \quad A(\vec{p}, \vec{g})$

$$\langle A \rangle = \frac{1}{N! h^{3N}} \int A(\vec{p}, \vec{g}) \underbrace{\rho(\vec{p}, \vec{g}, t)}_{= e^{-i \hat{L} t} \rho(\vec{p}, \vec{g})} d\vec{p} d\vec{g} \quad \Rightarrow \quad \frac{d\langle A \rangle}{dt} = \frac{1}{N! h^{3N}} \cdot (-i) \cdot \int A i \hat{L} \rho d\vec{p} d\vec{g}$$

$$= [A, H] \dots 0$$

$$A(\vec{p}(t), \vec{g}(t)) \Rightarrow \langle A \rangle = \frac{1}{N! h^{3N}} \int \bar{A}(\vec{p}(t), \vec{g}(t)) \rho(\vec{p}, \vec{g}) d\vec{p} d\vec{g}$$

$$\Rightarrow \frac{dA(\vec{p}(t), \vec{g}(t))}{dt} = \frac{\partial A}{\partial t} + \sum_i \left(\frac{\partial A}{\partial p_i} \dot{p}_i + \frac{\partial A}{\partial g_i} \dot{g}_i \right) = \sum_i \left(\frac{\partial A}{\partial g_i} \frac{\partial H}{\partial p_i} - \frac{\partial A}{\partial p_i} \frac{\partial H}{\partial g_i} \right) = i \hat{L} A$$

= 0

(A의 시간 의존은 ρ, g 때문)

$$\therefore A = e^{i \hat{L} t} A(\vec{p}, \vec{g})$$

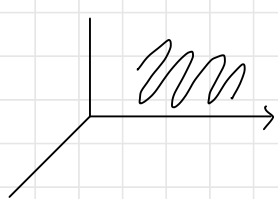
$$\Rightarrow \frac{d\langle A \rangle}{dt} = \frac{1}{N! h^{3N}} \int d\vec{p} d\vec{q} 2A\rho \dots (2)$$

From ①, ① $\Rightarrow - \sum_i \int A \left(\frac{\partial \rho}{\partial \vec{q}_i} \frac{\partial H}{\partial \vec{p}_i} - \frac{\partial H}{\partial \vec{q}_i} \frac{\partial \rho}{\partial \vec{p}_i} \right) d\vec{p} d\vec{q}$

$$= A \rho \frac{\partial H}{\partial \vec{p}_i} \Big|_S - \int d\vec{p} d\vec{q} \rho \{H, A\} = \langle \{A, H\} \rangle$$

$$\frac{d\langle A \rangle}{dt} = \langle \{A, H\} \rangle$$

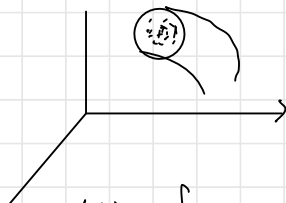
$\Rightarrow$ 수리양자 / 하이젠베르크 Approach identical result.



Time average

$$\bar{A} = \frac{1}{T} \int_0^T A(\vec{p}(t), \vec{q}(t)) d\vec{p} d\vec{q}$$

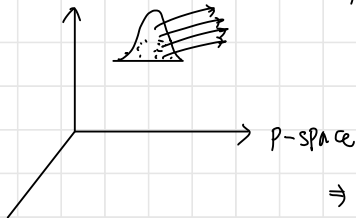
(Experiment)



Ensemble Average

$$\langle A \rangle = \int A \rho(t) d\vec{p} d\vec{q} \quad (\text{Theory})$$

$\equiv ?$ (Ergodic hypothesis, not been proved(?))



p-space

$$f_n(\vec{q}_1, \vec{q}_2, \dots, \vec{q}_N, \vec{p}_1, \vec{p}_2, \dots, \vec{p}_N; t)$$

$$\Rightarrow (\text{Number of particle}) \sim \int \frac{\partial f_N}{\partial t} d\vec{p} \cdot d\vec{q} = - \int_{\partial V} (\vec{f}_N \cdot \hat{n}) dS$$

$$= - \int \nabla \cdot (\vec{u} f_N) d\vec{p} d\vec{q}$$

Hamiltonian, Poisson bracket, Liouville operator

$$\Rightarrow \frac{df}{dt} = \frac{\partial f}{\partial t} + \{H, f\} = 0.$$

$\Rightarrow$ Precise, but cannot explain time-irreversibility, too many equations, difficult to solve.

Non-interacting 일 때만 풀이 가능 (?)

$\Rightarrow$ Exact, but useless

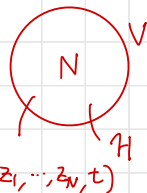
2. BBGKY Hierarchy

- Consider a classical system of identical N particles

$$\mathbf{z}_i = (\vec{p}_i, \vec{q}_i)$$

f_N : Probability finding N particles having specified $\mathbf{p}, \mathbf{q}$

$$\begin{aligned} ① \langle A_1(t) \rangle &= \int \left[\sum_{i=1}^N A_1(\mathbf{z}_i) \right] f_N(\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_N, t) d\mathbf{z}_1 \dots d\mathbf{z}_N \\ &= A_1(\mathbf{z}_1) + A_1(\mathbf{z}_2) + \dots + A_1(\mathbf{z}_N) \\ &\quad \text{dummy index 3회 가능} \\ &= \int d\mathbf{z}_1 A_1(\mathbf{z}_1) \cdot N \int d\mathbf{z}_2 \dots d\mathbf{z}_N f_N = \int d\mathbf{z}_1 A_1(\mathbf{z}_1) f_1(\mathbf{z}_1, t) \quad N44. \\ &\quad \text{N44.} \\ &\quad \text{=} \boxed{f_1(\mathbf{z}_1, t)} \rightarrow N \text{ 개 중 1개만 taken } \vec{p}_1, \vec{q}_1 \text{ 해 볼 수 있음.} \end{aligned}$$



$$P(\mathbf{z}_1, \dots, \mathbf{z}_N, t)$$

$$\begin{aligned} ② \langle A_2(t) \rangle &= \int \left[\sum_{i \neq j} A_2(\mathbf{z}_i, \mathbf{z}_j) \right] f_N(\mathbf{z}_1, \dots, \mathbf{z}_N, t) d\mathbf{z}_1 \dots d\mathbf{z}_N \quad (\text{Interaction}) \\ &= \int d\mathbf{z}_1 d\mathbf{z}_2 A_2(\mathbf{z}_1, \mathbf{z}_2) N(N-1) \int d\mathbf{z}_3 \dots d\mathbf{z}_N f_N = \int d\mathbf{z}_1 d\mathbf{z}_2 A_2(\mathbf{z}_1, \mathbf{z}_2) f_2(\mathbf{z}_1, \mathbf{z}_2, t) \\ &\quad \text{=} \boxed{f_2(\mathbf{z}_1, \mathbf{z}_2, t)} \dots S \text{ particle reduced distribution function} \end{aligned}$$

$$\therefore f_S(\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_S, t) = \frac{N!}{(N-S)!} \int d\mathbf{z}_{S+1} \dots d\mathbf{z}_N f_N(\mathbf{z}_1, \dots, \mathbf{z}_N, t)$$

(Ex) For kinetic energy, $A_i = \frac{p_i^2}{2m}$, $\langle K \rangle = \int d\mathbf{z}_1 \frac{p_1^2}{2m} \cdot f_1(\mathbf{z}_1, t)$

For potential energy, $U_{ij} \Rightarrow \langle U \rangle = \frac{1}{2} \int d\mathbf{z}_1 d\mathbf{z}_2 U(\mathbf{q}_1, \mathbf{q}_2) f_2(\mathbf{z}_1, \mathbf{z}_2, t)$

($\because U(\mathbf{q}_1, \mathbf{q}_2) = U(\mathbf{q}_2, \mathbf{q}_1) = \frac{1}{2}$ 보, 따라서 $\frac{1}{2}$ 배 해줘야 함.)

$\Rightarrow$ Single or 2-particle distribution $\Rightarrow$ average value 계산 가능.

(*) Some Properties

$$\int d\mathbf{z}_1 f_1(\mathbf{z}_1, t) = N$$

$$\int d\mathbf{p}_1 f_1(\mathbf{z}_1, t) = n(\mathbf{q}_1, t) \rightarrow \text{Particle number density, function of position}$$

$$\int d\mathbf{p}_1 \left(\frac{p_1^2}{2m} \right) f_1(\mathbf{z}_1, t) \equiv \frac{3}{2} n(\mathbf{q}, t) \cdot T(\mathbf{q}, t)$$

$$\int d\mathbf{p}_1 \cdot \vec{p} f_1(\mathbf{z}_1, t) \equiv \underline{m} \cdot n(\mathbf{q}, t) \underline{u(\mathbf{q}, t)} \quad \text{Continuum Temperature}$$

Momentum

(*) BBGKY 8도.

• Suppose $\mathcal{H} = \left[\sum_{i=1}^N \frac{p_i^2}{2m} + \sum_{i < j} U_{ij}(\mathbf{q}_i, \mathbf{q}_j) \right] + \sum_{i < j} U_{ij}(\mathbf{q}_i - \mathbf{q}_j)$ for N particles

$$\Rightarrow \mathcal{L}_N = \sum_{i=1}^N \left(\frac{\partial \mathcal{H}}{\partial \mathbf{p}_i} \frac{\partial}{\partial \mathbf{q}_i} - \frac{\partial \mathcal{H}}{\partial \mathbf{q}_i} \frac{\partial}{\partial \mathbf{p}_i} \right) \quad (\text{편미분 } \mathbf{p}_i = \vec{p}_i, \mathbf{q}_i = \vec{q}_i \text{ 의미})$$

$$= \sum_i \frac{p_i^2}{m} \delta_{i2} = \sum_i \frac{\partial u_{ij}}{\partial \mathbf{q}_i} \delta_{i2} + \sum_{i < j} \left(\frac{\partial u_{ij}}{\partial \mathbf{q}_i} \delta_{i2} + \frac{\partial u_{ij}}{\partial \mathbf{q}_j} \delta_{j2} \right)$$

$$= \sum_i \frac{P_i}{m} \frac{\partial}{\partial g_i} - \sum_i \frac{\partial u_i}{\partial g_i} \frac{\partial}{\partial P_i} - \sum_{i < j} \left(\frac{\partial u_{ij}}{\partial g_i} \frac{\partial}{\partial P_i} + \frac{\partial u_{ij}}{\partial g_j} \frac{\partial}{\partial P_j} \right) \Leftarrow u_{ij}(g_i - g_j)$$

$$= \sum_{i=1}^N \left(\frac{P_i}{m} \frac{\partial}{\partial g_i} + F_i^{\text{ext}} \frac{\partial}{\partial P_i} \right) + \sum_{i < j} F_{ij} \left(\frac{\partial}{\partial P_i} - \frac{\partial}{\partial P_j} \right)$$

$F_{ij} = -\frac{\partial u_{ij}}{\partial g_i}$

(1...S) $\equiv S_i$ (S+1...N) $\equiv P_j$ (Interaction) (이제 decompose 하라)

(S particle $\equiv$)

$$\Rightarrow \mathcal{L}_N = \underbrace{\sum_{i=1}^S S_i}_{\mathcal{L}_S} + \underbrace{\sum_{\substack{i < j \\ i=1 \dots S}} P_{ij}}_{\mathcal{L}_{N-S}} + \sum_{i=S+1}^N S_i + \sum_{\substack{i, j=S+1 \dots N \\ (i < j)}} P_{ij} + \sum_{i=1}^S \sum_{j=S+1}^N P_{ij}$$

From Liouville, $\frac{\partial f_N}{\partial t} + \mathcal{L}_N f_N = 0$. and we defined f_S before.

(LHS) $\Rightarrow \mathcal{L}_N f_N = -\frac{\partial f_N}{\partial t}$ 양변을 $\frac{N!}{(N-S)!} \int dz_{S+1} dz_{S+2} \dots dz_N$ 적분하면, $f_N \rightarrow f_S$ 이다.

(LHS) $= -\frac{\partial}{\partial t} f_S$ $\overset{\text{similarly}}{=} \mathcal{L}_S f_S$ [No integration by part, 그대로 적분함수=] $f_N|_S = 0$.
 파생변은 S+1 ~ N까지 다 다

② $= \frac{N!}{(N-S)!} \int dz_{S+1} \dots dz_N \mathcal{L}_{N-S} f_N = \frac{N!}{(N-S)!} \int dz_{S+1} \dots dz_N \left[\sum_{i=S+1}^N \left(\frac{P_i}{m} \frac{\partial f_N}{\partial g_i} + F_i^{\text{ext}} \frac{\partial f_N}{\partial P_i} \right) \right]$

$= 0$. ($\because i=S+1 \sim N$ 뿐이 뿐지, $\int \frac{\partial f_N}{\partial g_i} dg_i = f_N|_S = 0$ for surface S) + $\sum_{i,j=S+1}^N \left(\frac{\partial f_N}{\partial P_i} - \frac{\partial f_N}{\partial P_j} \right)$

$\Rightarrow$ ② term vanishes. (Other 'S+1 ~ N'의 evolution은 생략하지 않아도 되게 된다)

③ $= \frac{N!}{(N-S)!} \int dz_{S+1} \dots dz_N \sum_{i=1}^S \sum_{j=S+1}^N F_{ij} \left(\frac{\partial f_N}{\partial P_i} - \frac{\partial f_N}{\partial P_j} \right)$ $\rightarrow j=S+1 \sim N$, ②에서 같이, $f_N|_S = 0$

$= \sum_{i=1}^S \frac{N!}{(N-S)!} \int dz_{S+1} \dots dz_N \sum_{j=S+1}^N F_{ij} \frac{\partial f_N}{\partial P_i} = \sum_{i=1}^S \frac{N! (N-S-1+1)}{(N-S)!} \int dz_{S+1} \dots dz_N F_{i, S+1} \frac{\partial f_N}{\partial P_i}$

$= \left[\sum_{i=1}^S \int dz_{S+1} F_{i, S+1} \frac{\partial}{\partial P_i} \right] \left[\frac{N!}{(N-S-1)!} \int dz_{S+2} \dots dz_N f_N \right]$ (이제 j=S+1 지움)

$= f_{S+1}$

Now, 위 결과를 합하면, $-\frac{\partial}{\partial t} f_S = \mathcal{L}_S f_S + \text{③}$, $[\mathcal{L}_S + \frac{\partial}{\partial t}] f_S = -\text{③}$.

$$\Rightarrow \left[\frac{\partial}{\partial t} + \mathcal{L}_S \right] \cdot f_S(z_1, z_2, \dots, z_S, t) = - \sum_{i=1}^S \int dz_{S+1} F_{i, S+1} \frac{\partial}{\partial P_i} f_{S+1}(z_1, \dots, z_{S+1}, t)$$

$\frac{df_S}{dt} \neq 0$

... Bogoliubov-Born-Green-Kirkwood-Yvon hierarchy (BBGKY)

$$S=1: \left(\frac{\partial}{\partial t} + \frac{p_1}{m} \frac{\partial}{\partial x_1} + F_1 \frac{\partial}{\partial p_1} \right) f_1(x_1, p_1, t) = - \int dx_2 F_{1,2} \frac{\partial}{\partial p_1} f_2(x_1, p_1, x_2, p_2, t)$$

$$S=2: \left(\frac{\partial}{\partial t} + \frac{p_1}{m} \frac{\partial}{\partial x_1} + \frac{p_2}{m} \frac{\partial}{\partial x_2} + F_1 \frac{\partial}{\partial p_1} + F_2 \frac{\partial}{\partial p_2} + F_{12} \left(\frac{\partial}{\partial p_1} - \frac{\partial}{\partial p_2} \right) \right) f_2$$

$$= - \int dx_3 \left(F_{12} \frac{\partial}{\partial p_1} + F_{23} \frac{\partial}{\partial p_2} \right) f_3(x_1, p_1, x_2, p_2, x_3, p_3, t)$$

$S=3 \dots \rightsquigarrow$ 계속해서 반복되는데 '계승' 계승. How to terminate?

$\Rightarrow$ 물리적 직관을 동원한 approximation,

3. Vlasov Equation

$$\left(\frac{\partial}{\partial t} + \frac{\vec{p}}{m} \frac{\partial}{\partial \vec{x}} + \vec{F} \frac{\partial}{\partial \vec{p}} \right) f_1(\vec{x}, \vec{p}, t) = \int d\vec{x}' d\vec{p}' \frac{\partial u(\vec{x}, \vec{x}')}{\partial \vec{x}} \frac{\partial}{\partial \vec{p}} f_2(\vec{x}, \vec{p}, \vec{x}', \vec{p}', t)$$

$$= f_1(\vec{x}, \vec{p}, t) \cdot f_2(\vec{x}', \vec{p}', t)$$

(Vector notation 생략, Drop off | subscript)

... Vlasov Equation

$$(RHS) = \int dx' dp' \frac{\partial u}{\partial x} \cdot f(x', p', t) \cdot \frac{\partial f}{\partial p} = - \bar{F}(x, t) \frac{\partial f(x, p, t)}{\partial p}$$

$$= \int dx' \frac{\partial u}{\partial x} \cdot n(x', t) = \frac{\partial}{\partial x} \int dx' u(x, x') n(x', t)$$

$\rightarrow$ Interaction with others in system

$$\frac{df}{dt} = - \bar{F}(x, t) \rightarrow \text{Mean field force}$$

$$\Rightarrow \left[\frac{\partial}{\partial t} + \frac{p}{m} \frac{\partial}{\partial x} + \left(\cancel{F^{ext}} + \bar{F} \right) \frac{\partial}{\partial p} \right] f(x, p, t) = 0$$

Let 0

$\rightarrow$ Time-reversible Invariant (Symmetry)

(*) Let's see what happening in the plasma,

Plasma Parameter $\rho_p = \frac{e^2/d}{k_B T}$ (d = average distance)

$$\approx \frac{e^2 n^{-1/3}}{k_B T}$$

$$= \frac{1}{4\pi} \frac{d^2}{\lambda_D^2} \ll 1$$

$$\nabla^2 u = -4\pi e^2 S(r)$$

$$\frac{1}{\lambda_D^2} \sim \frac{4\pi e^2 n}{k_B T} \quad (\lambda_D: \text{Debye length})$$

$\rightarrow$ Electric potential은 parameter 조 건적 가능. : weakly coupled plasma.

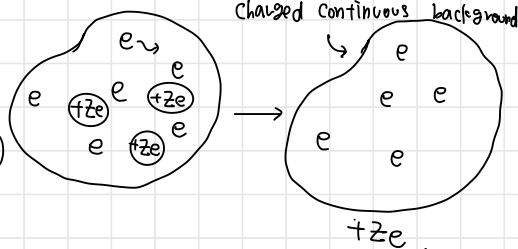
(perturbation)

now, by Vlasov Eq,

$$\frac{\partial f}{\partial t} + \frac{\vec{p}}{m} \frac{\partial f}{\partial \vec{r}} + e \left(\vec{E} + \frac{1}{c} \vec{v} \times \vec{H} \right) \frac{\partial f}{\partial \vec{p}} = 0$$

$\rightarrow$ nonlinear equation

where $\bar{F} = e \vec{E}_{(r,t)} - \frac{\partial}{\partial r} \int dr' u(r-r') n(r', t)$ $\int dp = n$ $\Rightarrow$ perturbative approach



E field에 f에 의존

Let $f(\vec{r}, \vec{p}, t) = f_0(\vec{p}) + \delta f(\vec{r}, \vec{p}, t)$ ($f_0(p) = n \cdot \left(\frac{\beta}{2\pi m}\right)^{\frac{3}{2}} \cdot e^{-\frac{\beta p^2}{2m}}$)
 Vlasov equation 대입. weak Coulomb interaction에 따른 term

$$\Rightarrow \frac{\partial}{\partial t} (f_0 + \delta f) + \frac{p}{m} \frac{\partial}{\partial r} (f_0 + \delta f) = -e \vec{E} \cdot \frac{\partial}{\partial p} (f_0 + \delta f) \quad n(r, t) = \cancel{n_0} + \delta n(r, t)$$

Then, (BHS): $\frac{\partial f_0}{\partial t} + \frac{p}{m} \frac{\partial f_0}{\partial r} = 0$, $\frac{\partial}{\partial t} \delta f + \frac{p}{m} \frac{\partial}{\partial r} \delta f = -e \vec{E} \cdot \frac{\partial f_0}{\partial p}$ ($= \int (f_0 + \delta f) dp'$)
 (trivial) $\frac{\partial}{\partial t} \delta f + \frac{p}{m} \frac{\partial}{\partial r} \delta f = -e \vec{E} \cdot \frac{\partial f_0}{\partial p}$

이제, wave-like solution idea를 이용하자. P 는 vel 비례하는 물리량임, ... Linearized Vlasov equation.

구독작으로 다음과 같이 푸리에 변환이 가능하다.

$$\begin{aligned} \delta f(\vec{r}, \vec{p}, t) &= \delta f(\vec{r}, \vec{p}, \omega) \cdot e^{i(\vec{K} \cdot \vec{r} - \omega t)} \\ \delta n(\vec{r}, t) &= \delta n(\vec{K}, \omega) e^{i(\vec{K} \cdot \vec{r} - \omega t)} \end{aligned}$$

이들 식에 대입하여 정리하면,

$$\Rightarrow -i\omega \delta f(\vec{r}, \vec{p}, \omega) + i\vec{K} \cdot \vec{v} \delta f(\vec{r}, \vec{p}, \omega) = -e \vec{E}(\vec{K}, \omega) \frac{\partial f_0}{\partial p} \quad \left[e \vec{E} = -\vec{J} \right]$$

Where $e \vec{E} = -\frac{\partial}{\partial r} \int dr' u(r-r') \delta n(r', t) = -i\vec{K} \cdot u(\vec{K}) \delta n(\vec{K}, \omega)$.

$$\Rightarrow (\text{RHS}) = +i u(\vec{K}) \delta n(\vec{K}, \omega) \cdot \vec{K} \frac{\partial f_0}{\partial p} = i(\vec{K} \cdot \vec{v} - \omega) \delta f(\vec{r}, \vec{p}, \omega)$$

$$\therefore \delta f = -\frac{u(\vec{K}) \delta n(\vec{K}, \omega)}{\omega - \vec{K} \cdot \vec{v}} \cdot \vec{K} \cdot \frac{\partial f_0}{\partial p}$$

이제, δf 를 구했으니, 다음 식을 이용하자. $\int d\vec{p} \delta f(\vec{r}, \vec{p}, \omega) = \delta n(\vec{K}, \omega)$.

$$\Rightarrow \cancel{\delta n} = -\int \frac{u(\vec{K}) \cancel{\delta n(\vec{K}, \omega)}}{\omega - \vec{K} \cdot \vec{v}} \cdot \vec{K} \cdot \frac{\partial f_0}{\partial p} \cdot d\vec{p} \Rightarrow \text{Dispersion relation을 구할 수 있다.}$$

이때, $u(\vec{K})$ 는 electric potential 이고, $\nabla^2 u(\vec{r}) = -4\pi e^2 \delta(\vec{r})$ 푸리에
 $-k^2 u(\vec{K}) = -4\pi e^2$

$$\Rightarrow -\frac{4\pi e^2}{k^2} \int d\vec{p} \frac{1}{\omega - \vec{K} \cdot \vec{v}} \left(\vec{K} \cdot \frac{\partial f_0}{\partial p} \right) = 1 \quad \therefore u(r) = \frac{4\pi e^2}{k^2}$$

이때, f_0 가 Gaussian 플인 경우를 이용하면, $\frac{\partial f_0}{\partial p} = -\frac{2\beta \vec{p}}{2m} f_0 = -\beta \cdot \vec{v} f_0$.

$$\begin{aligned} \therefore 1 &= \frac{4\pi e^2}{k^2} \int d\vec{p} \cdot \frac{\vec{K} \cdot \vec{v}}{\omega - \vec{K} \cdot \vec{v}} \beta f_0 \quad \left(\frac{\partial f_0}{\partial E} \cdot \frac{\partial E}{\partial p}, f_0 \sim d \cdot e^{-\beta E} \right) \\ &= \frac{\vec{K} \cdot \vec{v}}{\omega} \cdot \left(\frac{1}{1 - \frac{\vec{K} \cdot \vec{v}}{\omega}} \right) = \frac{\vec{K} \cdot \vec{v}}{\omega} \left(1 + \frac{\vec{K} \cdot \vec{v}}{\omega} + \left(\frac{\vec{K} \cdot \vec{v}}{\omega} \right)^2 + \dots \right) \end{aligned}$$

$$\Rightarrow 1 \approx \frac{4\pi e^2}{k^2} \int d\vec{p} \cdot \left[\cancel{\frac{\vec{K} \cdot \vec{v}}{\omega}} + \left(\frac{\vec{K} \cdot \vec{v}}{\omega} \right)^2 + \left(\cancel{\frac{\vec{K} \cdot \vec{v}}{\omega}} \right)^3 + \dots \right] \beta f_0 \quad (\text{Small region에 } k \text{에서 } \cancel{\text{값}} \text{만 2차})$$

0, odd function 0

non zero

$$= \frac{4\pi e^2}{k^2} \cdot 2\pi \int d(\cos\theta) \cdot \int_0^\infty dp \cdot p^2 \cdot \frac{k^2 p^2 \cos^2\theta}{m^2 \omega^2} p \cdot n \cdot \left[\frac{p}{2\pi m} \right]^{\frac{3}{2}} e^{-\frac{p^2}{2m}}$$

$$= \frac{4\pi e^2 n}{m^2 \omega^2} \equiv \frac{\omega_p^2}{\omega^2} \quad \boxed{\omega_p^2 = \frac{4\pi e^2 n}{m^2}} \quad \text{plasma frequency.}$$

So, $\omega_p = \omega$ 이고, Plasma frequency가 e, n, m 의 함수인 상수이며,
 System의 wave frequency가 잘 정의된 ω_p 를 진행한다. } Oscillation
 $\omega > 0$. no imaginary, no damping

$\Rightarrow$ 근사항을 고려하면, 위 식은식이 $1 = \frac{\omega_p^2}{\omega^2} \cdot \left[1 + \frac{k^2}{\omega^2} \langle v^2 \rangle \right]$ ← Equilibrium behavior $E = \frac{m \langle v^2 \rangle}{2} = \frac{3k_B T}{2}$

$\Rightarrow \omega^2 \cong \omega_p^2 + k^2 \langle v^2 \rangle$



$$\delta f = - \frac{\overbrace{-ie\vec{E}}^{\text{'' } -ie\vec{E} \text{ ''}} \cdot \frac{\vec{k} \cdot \vec{u}(\vec{k}) \delta n(\vec{k}, \omega)}{\omega - \vec{k} \cdot \vec{v}} \cdot \left(\frac{\partial f_0}{\partial p} \right)}$$

(*) Response function.

$$\delta n(\vec{k}, \omega) = \int \delta f(\vec{k}, \vec{p}, \omega) d\vec{p}$$

$$= \frac{-i \cdot e \cdot \vec{E} \cdot \int d\vec{p} \cdot \frac{1}{\omega - \vec{k} \cdot \vec{v}} \left(\frac{\partial f_0}{\partial p} \right)}{= \delta n(\vec{k}, \omega)}$$

and, we know $\left\{ \begin{array}{l} \nabla \cdot \vec{P} = -4\pi \rho_b = -4\pi e \cdot \delta n(\vec{r}, t) \\ i\vec{k} \cdot \vec{P} = -4\pi e \delta n(\vec{k}, \omega) \end{array} \right.$

$$\therefore \vec{P}(\vec{k}, \omega) = \frac{4\pi e^2}{k^2} \cdot \int d\vec{p} \cdot \frac{1}{\omega - \vec{k} \cdot \vec{v}} \left(\frac{\partial f_0}{\partial p} \cdot \vec{k} \right) \vec{E}$$

$= \chi_e$

we know $\vec{P}(\vec{r}, t) = \int d\vec{r}' dt' \chi(\vec{r} - \vec{r}', t - t') \vec{E}(\vec{r}', t')$

Green function, susceptibility

$\vec{P}(\vec{k}, \omega) = \chi(\vec{k}, \omega) \vec{E}(\vec{k}, \omega)$ Let $\vec{P}, \vec{E}$ 가 특정 방향 (평행)

$\Rightarrow P(k, \omega) = \chi_e(k, \omega) E(k, \omega)$

(cf) $\vec{E} = \vec{I} + \vec{\chi}$

$\therefore \chi_e = - \frac{\omega_p^2}{\omega^2} \cdot \left[1 + \frac{k^2}{\omega^2} \langle v^2 \rangle + \dots \right]$

$$\Rightarrow \epsilon_L = 1 + \chi_L = 1 - V(k) \cdot \int \frac{d^3 \vec{p}}{k \cdot \vec{v} - \omega} \cdot \left(\frac{\partial f_0}{\partial \vec{p}} \right) = 1 - \frac{4\pi e^2}{k^2} \int \frac{d^3 p}{k \cdot \vec{v} - \omega - i\eta} \frac{\partial f_x}{\partial p_x}$$

Perturbation $\rightarrow$ (S) $\rightarrow$ response.

where $\lim_{\eta \rightarrow 0} \int \frac{f(z)}{z - i\eta} dz = P \int \frac{f(z)}{z} dz + i\pi f(0)$

$\hookrightarrow$ Cauchy principle value

$\omega \rightarrow \omega + i\eta$
 $\hat{k} // \hat{x}$
 $= \epsilon_L' + i \cdot \epsilon_L''$

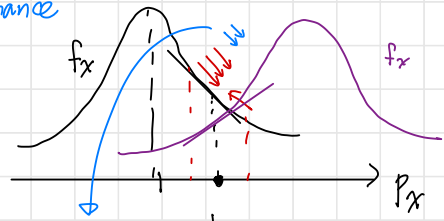
... Sokhotski-Plemelj theorem

$$\Rightarrow \epsilon_L'' = - \frac{4\pi e^2}{k^2} \int \frac{dp_x}{m} \cdot k \cdot \frac{df_x}{dp_x} \cdot \delta(kv_x - \omega) = - \frac{4\pi e^2 m}{k^2} \cdot k \cdot \left(\frac{\partial f_x}{\partial p_x} \right)_{v_x = \frac{\omega}{k}}$$

System에 에너지 Loss/Absorption에 대한 지표

($\because$ Wave & Particle 간에 에너지 전달)

$$\epsilon_L'' = \begin{cases} + & : \text{Damping (Wave lost energy)} \\ - & : \text{Growing (Wave gain energy)} \end{cases}$$



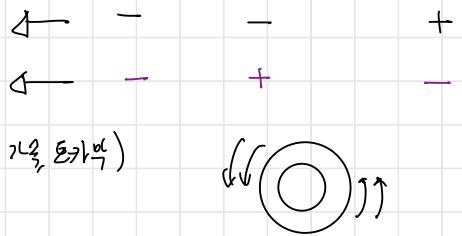
$\Delta v_x > 0$
Particle gain energy $\Leftrightarrow$ wave losing energy
 $m v_x = m \frac{\omega}{k}$
 $\epsilon_L'' = (-) \times \left(\frac{\partial f_x}{\partial p_x} \right)$

입자간 충돌이 없어도 (2) 조건에 에너지 잃음.

... Landau damping

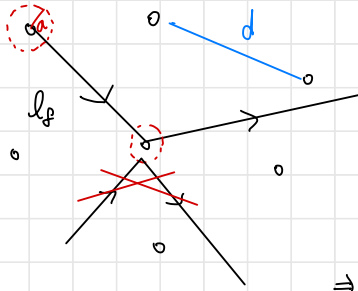
System gaining energy.

($\because f_x$ 가 우편향, 전체 입자에 가중, 좌우)



4. Boltzmann Equation : Time irreversibility

- Consider a dilute classical gas undergoing binary collisions.



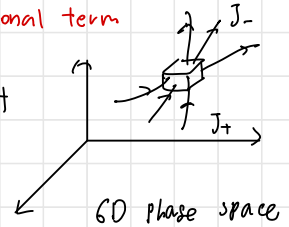
d = Average distance, a = Interaction range.
 l_f = Mean free path.

- (*) 74% i) $l_f > d$, Collision event rare
 ii) No three particle collision event.

⇒ Using Vlasov equation, one notices

$$\left[\begin{aligned} \frac{Df_1}{Dt} &= J[f_2] \\ \frac{Df_2}{Dt} &= J[f_1] \end{aligned} \right] \quad \frac{Df_1}{Dt} = \left(\frac{\partial}{\partial t} + \frac{\vec{p}}{m} \cdot \frac{\partial}{\partial \vec{r}} + \vec{F} \cdot \frac{\partial}{\partial \vec{p}} \right) f = \underbrace{J[f_2]}_{\text{Collisional term}} = \overset{\text{Influx}}{J_+} - \overset{\text{Outflux}}{J_-}$$

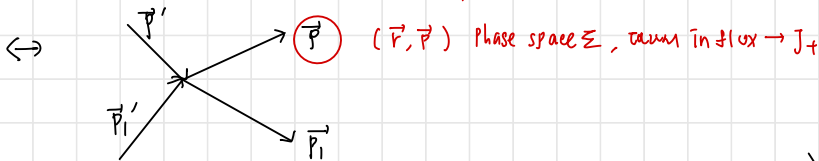
⇒ $J_{\pm}(\vec{r}, \vec{p}, t) = (\text{Outgoing flux}) \text{ influx of } f \text{ into the volume element } d\vec{r} d\vec{p} \text{ around } (\vec{r}, \vec{p}) \text{ during } dt.$



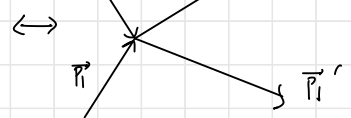
- One notices that;

$$J_+ = \int d\vec{p}_1 \cdot d\vec{p}' \cdot d\vec{p}_1' \cdot \underbrace{W(\vec{p}, \vec{p}_1 | \vec{p}', \vec{p}_1')}_{\text{Initial Condition}} f_2(\vec{r}, \vec{p}, \vec{r}, \vec{p}_1', t)$$

transmission probability

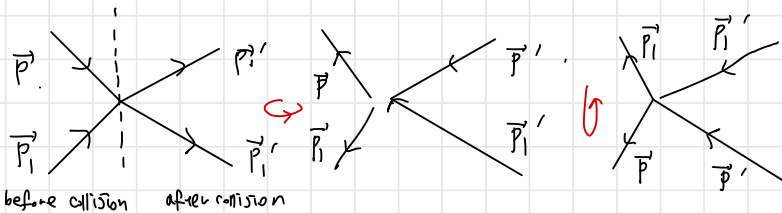


$$J_- = \int d\vec{p}_1' \cdot d\vec{p}' \cdot d\vec{p}_1 \cdot W(\vec{p}', \vec{p}_1' | \vec{p}, \vec{p}_1) f_2(\vec{r}, \vec{p}, \vec{r}, \vec{p}_1, t)$$



- (*) Symmetric Property of Probability.

$$W(\vec{p}', \vec{p}_1' | \vec{p}, \vec{p}_1) = W(\vec{p}, \vec{p}_1 | \vec{p}', \vec{p}_1')$$



And, Boltzmann assumed Stoßzahlansatz
= Collision number hypothesis

$$\Rightarrow f(v_1, v_2) = f(v_1) f(v_2)$$

$$\Rightarrow \text{Uncorrelated before the collision.}$$

$$\left. \begin{aligned} f_2(\vec{r}, \vec{p}, \vec{r}, \vec{p}_1, t) &= f(\vec{r}, \vec{p}, t) \cdot f(\vec{r}, \vec{p}_1, t) \end{aligned} \right\}$$

Therefore, we can make above equation as; $\rightarrow$ Not Time-Reversal Invariant.

$$\frac{Df}{Dt} = \frac{\partial f}{\partial t} + \left[\frac{\vec{p}}{m} \cdot \frac{\partial}{\partial \vec{r}} + \vec{F} \cdot \frac{\partial}{\partial \vec{p}} \right] f = J_+ - J_- = \int d\vec{p}' d\vec{p}_1' d\vec{p}_1 \cdot W(\vec{p}', \vec{p}_1' | \vec{p}, \vec{p}_1) [f f_1' - f f_1]$$

$$t \rightarrow -t : \vec{p} \rightarrow -\vec{p} \quad (f' = f(\vec{r}, \vec{p}', t), f_1' = f(\vec{r}, \vec{p}_1', t))$$

(*) H-Theorem

Let's define $H = \int d\vec{r} d\vec{p} f(\vec{r}, \vec{p}, t) \cdot \ln f(\vec{r}, \vec{p}, t)$

$$S(\vec{r}, t) = -k_B \cdot \int d\vec{p} \cdot f \ln f. \rightarrow \text{Localized entropy density}$$

$$\Rightarrow \frac{\partial S}{\partial t} = -k_B \int d\vec{p} \cdot \frac{\partial}{\partial t} [f \ln f] = -k_B \int d\vec{p} \cdot [1 + \ln f] \left(\frac{df}{dt} \right)$$

$$= -k_B \int d\vec{p} \cdot (1 + \ln f) \left[\underbrace{-\frac{\vec{p}}{m} \cdot \frac{df}{d\vec{r}}}_{\textcircled{1}} - \underbrace{\vec{F} \cdot \frac{df}{d\vec{p}}}_{\textcircled{2}} + \underbrace{J[f_2]}_{\textcircled{3}} \right]$$

$\left. \begin{aligned} \textcircled{1} \quad \textcircled{2} \quad \textcircled{3} \end{aligned} \right\} \text{BBGKY hierarchy}$

$$\textcircled{1} = +k_B \int d\vec{p} \cdot \frac{\vec{p}}{m} \cdot (1 + \ln f) \frac{df}{d\vec{r}} = k_B \int d\vec{p} \cdot \frac{\vec{p}}{m} \cdot \frac{d}{d\vec{r}} (f \ln f) = \frac{\partial}{\partial r} \underbrace{k_B \int d\vec{p} \cdot \frac{\vec{p}}{m} f \ln f}_{= -\vec{J}_S}$$

$$\textcircled{2} = k_B \cdot \int d\vec{p} (1 + \ln f) \vec{F} \cdot \frac{df}{d\vec{p}} = k_B \cdot \vec{F} \int d\vec{p} \frac{d}{d\vec{p}} (f \ln f) \propto (f \ln f) \Big|_S = 0. \quad \text{Entropy Current}$$

$$\textcircled{3} = -k_B \cdot \int d\vec{p} \cdot (1 + \ln f) J[f_2]$$

$\Rightarrow$ 대칭성과 이항하여 정리하면, $J = J_+ - J_-$ 이므로

$$\frac{\partial S}{\partial t} + \vec{\nabla}_{\vec{r}} \cdot \vec{J}_S = -k_B \int d\vec{p} \cdot d\vec{p}_1' d\vec{p}' d\vec{p}_1 \cdot W(p' p_1' | p p_1) (f' f_1' - f f_1) (1 + \ln f) \dots (i)$$

by $p \leftrightarrow p_1$ Symmetry,

$$\left(\dots \right) = -k_B \int d\vec{p} d\vec{p}_1' d\vec{p}' d\vec{p}_1 \cdot W(p' p_1' | p p_1) (f' f_1' - f f_1) (1 + \ln f) \dots (i)'$$

$\rightarrow$ Half Sum (i) and (i)', we get

$$\left(\frac{\partial S}{\partial t} + \vec{\nabla}_{\vec{r}} \cdot \vec{J}_S \right) = -\frac{k_B}{2} \int d\vec{r} d\vec{r}_1 d\vec{r}' d\vec{r}'_1 W(f'f'_1 - ff_1) (2 + \ln ff_1) \quad \dots (ii)$$

→ Same way, (ii) or 11 $(P, P_1) \leftrightarrow (P', P'_1)$ symmetry of W .

$$\left(\frac{\partial S}{\partial t} + \vec{\nabla}_{\vec{r}} \cdot \vec{J}_S \right) = -\frac{k_B}{2} \int d\vec{r} d\vec{r}_1 d\vec{r}' d\vec{r}'_1 W(ff_1 - f'f'_1) (2 + \ln f'f'_1) \quad \dots (ii)'$$

→ Again, half sum

$$\left(\frac{\partial S}{\partial t} + \vec{\nabla}_{\vec{r}} \cdot \vec{J}_S \right) = +\frac{k_B}{4} \int d\vec{r} d\vec{r}_1 d\vec{r}' d\vec{r}'_1 W(f'f'_1 - ff_1) \ln \frac{f'f'_1}{ff_1} \geq 0.$$

$$= \frac{dS(\vec{r}, t)}{dt}$$

→ Total entropy of the system

$$S(t) = \int d\vec{r} S(\vec{r}, t) = -k_B \int d\vec{r} \int d\vec{r}' f \ln f = -k_B \cdot H(t).$$

$$\therefore, \frac{dS}{dt} \geq 0 \Leftrightarrow \frac{dH}{dt} \leq 0 \quad \text{이다.}$$

$$(x-y) \ln \left(\frac{x}{y} \right) \geq 0 \quad \leftarrow \begin{cases} x > y \\ y > x \\ x = y \end{cases}$$

(*) Equilibrium Distribution.

• At equilibrium, as required property, $ff_1 = f'f'_1$ ($dH = 0$)

• $\lim_{t \rightarrow \infty} f(\vec{r}, \vec{p}, t) = f_0(\vec{p})$ ($\because \vec{r}$ symmetry) ($\delta f_0(\vec{r}, \vec{p}, t) \rightarrow 0$)

$$\Rightarrow f_0(\vec{p}) f_0(\vec{p}_1) = f_0(\vec{p}') f_0(\vec{p}'_1)$$

$$\Rightarrow \ln f_0(\vec{p}) + \ln f_0(\vec{p}_1) = \ln f_0(\vec{p}') + \ln f_0(\vec{p}'_1)$$

= Conserved quantity처럼 보인다. (콜리전 불변량)

$$\rightarrow \chi(\vec{p}') + \chi(\vec{p}'_1) = \chi(\vec{p}) + \chi(\vec{p}_1) \quad (\chi = \text{collision invariant})$$

$$\Rightarrow \ln f_0(\vec{p}) = a + \vec{b} \cdot \vec{p} + c \cdot \frac{p^2}{2m} \quad (\text{conserved quantity})$$

$$\int d\vec{p} \cdot f(\vec{r}, \vec{p}, t) = \underline{n(\vec{r}, t)} \quad \text{local density}$$

$$\int d\vec{p} \cdot \vec{p} f(\vec{r}, \vec{p}, t) = n(\vec{r}, t) \cdot \underline{\vec{u}(\vec{r}, t)} \quad \text{local field velocity}$$

$$\int d\vec{p} \cdot \frac{(\vec{p} - m\vec{u})^2}{2m} \cdot f = \frac{3}{2} k_B T(\vec{r}, t) n(\vec{r}, t) \quad \text{local temperature}$$

#5 equations. $\rightarrow a, \vec{b}, c$

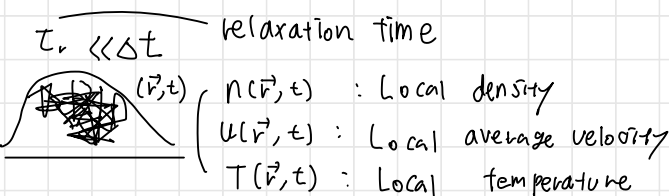
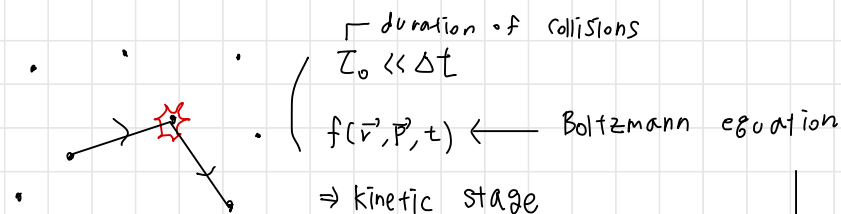
Generalized Boltzmann distribution
... Spatial Variance of T, n exist.

$$f_0(\vec{r}, \vec{p}, t) = \frac{n(\vec{r}, t)}{[2\pi m k_B T(\vec{r}, t)]^{\frac{3}{2}}} \exp \left(-\frac{[\vec{p} - m\vec{u}(\vec{r}, t)]^2}{2m k_B T(\vec{r}, t)} \right)$$

(f = 1 particle distribution function = prob of finding 1 particle in $\vec{r}, \vec{p}$ at t)

5. Hydrodynamic equations

→ a dilute classical gas undergoing binary collisions



→ Hydrodynamic equation

(Hydrodynamic stage)

$$\frac{Df}{Dt} = \frac{\partial f}{\partial t} + \frac{\vec{p}}{m} \cdot \frac{\partial f}{\partial \vec{r}} + \vec{F} \cdot \frac{\partial f}{\partial \vec{p}} = \left(\frac{Df}{Dt} \right)_{\text{coll}}$$

(*) Conservation Laws

Let χ be a collisional invariant quantity. $\chi = \chi(\vec{r}, \vec{p}, t)$

$$\int d\vec{p} \cdot \chi(\vec{r}, \vec{p}, t) \left(\frac{\partial f}{\partial t} \right)_{\text{coll}} = 0 \quad \text{일지 모름. By Boltzmann equation, (LHS) become:}$$

$$\Rightarrow \int d\vec{p} \int d\vec{p}_1 \int d\vec{p}' \int d\vec{p}_1' W(\vec{p}', \vec{p}_1' | \vec{p}, \vec{p}_1) [f' f_1' - f f_1] \chi \quad \chi_1 = \chi(\vec{r}, \vec{p}_1, t) \text{ 볼 때, by symmetry,}$$

$$= \frac{1}{2} \int d\vec{p} \int d\vec{p}_1 \int d\vec{p}' \int d\vec{p}_1' W(\vec{p}', \vec{p}_1' | \vec{p}, \vec{p}_1) [f' f_1' - f f_1] (\chi_1 + \chi) \quad (\text{half sum})$$

$\Rightarrow$ By $(p, p_1) \leftrightarrow (p', p_1')$ symmetry and half sum,

$$= \frac{1}{4} \int d\vec{p} \int d\vec{p}_1 \int d\vec{p}' \int d\vec{p}_1' W(\vec{p}', \vec{p}_1' | \vec{p}, \vec{p}_1) [f' f_1' - f f_1] (\chi + \chi_1 - \chi' - \chi_1') \quad (\because \text{Collisional invariant, } \chi = \chi_1 = \chi' = \chi_1')$$

$$\Rightarrow \text{By Boltzmann equation, Let's rewrite this: } \int d\vec{p} \chi(\vec{r}, \vec{p}, t) \left(\frac{\partial f}{\partial t} + \frac{\vec{p}}{m} \cdot \frac{\partial f}{\partial \vec{r}} + \vec{F} \cdot \frac{\partial f}{\partial \vec{p}} \right) = 0.$$

$\Rightarrow$ By expanding this equation;

$$\left[\frac{\partial}{\partial t} \int d\vec{p} \cdot (\chi f) - \int d\vec{p} \cdot f \left(\frac{\partial \chi}{\partial t} \right) + \left[\frac{\partial}{\partial \vec{r}} \cdot \int d\vec{p} \cdot (\chi \cdot \vec{u} \cdot f) - \int d\vec{p} \cdot \left(\frac{\partial \chi}{\partial \vec{r}} \right) \cdot \vec{u} f \right] + \left[\int d\vec{p} \cdot \frac{\partial}{\partial \vec{p}} (\chi F f) - \int d\vec{p} \left(\frac{\partial \chi}{\partial \vec{p}} \right) \vec{F} f \right] \right] = 0.$$

($\because$ Surface integral 0이므로 제외함)

6/13(목) 시험일정

1.p.m ~ 4.p.m.

중간 이후 ~

하지만 전체 이해해야

Now, Let's define kinetic average of $A \Rightarrow \langle A \rangle = \frac{\int d\vec{p} \cdot (A f)}{\int d\vec{p} \cdot f} = \frac{\int d\vec{p} (A f)}{n(\vec{r}, t)}$

$\Rightarrow$ Then, we can get the final equation:

$$\frac{d}{dt} n \langle \chi \rangle - n \cdot \left\langle \frac{\partial \chi}{\partial t} \right\rangle + \vec{\nabla} \cdot n \langle \chi \vec{v} \rangle - n \cdot \langle (\vec{\nabla} \chi) \cdot \vec{v} \rangle - n \langle (\vec{\nabla}_{\vec{r}} \chi) \cdot \vec{F} \rangle = 0$$

... Conservation Laws

$\Rightarrow$ Now, Let's see what happen if we substitute χ in invariant quantity.

i) Let $\chi = m$. and, we know by definition, $\langle \vec{v} \rangle = \vec{u}(\vec{r}, t)$

$$\Rightarrow \frac{d}{dt} (n m) - n \cdot 0 + \vec{\nabla} \cdot n m \vec{u} = 0 \quad (\nabla m = \nabla_p m = 0) \quad \text{Let } \rho(\vec{r}, t) = m n(\vec{r}, t)$$

$$\Rightarrow \frac{\partial \rho(\vec{r}, t)}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

ii) Let $\chi = m v_i$ ($i = x, y, z$) similarly,

$$\frac{d}{dt} m n \langle v_i \rangle + \vec{\nabla} \cdot m n \langle v_i \vec{v} \rangle - n \left\langle \left(\frac{\partial}{\partial t} \cdot \hat{i} \right) \cdot \vec{F} \right\rangle = 0$$

$$\Rightarrow \frac{\partial}{\partial t} \cdot m n u_i(\vec{r}, t) + \vec{\nabla} \cdot (m n \langle v_i v_j \rangle) - \frac{\rho}{m} F_i = 0 \quad (j = 1, 2, 3)$$

$$\Rightarrow \langle v_i v_j \rangle = \langle (v_i - u_i)(v_j - u_j) \rangle + \underbrace{\left(\frac{\langle v_i \rangle u_j + u_i \langle v_j \rangle}{= u_i u_j} - u_i u_j \right)}_{= u_i u_j}$$

이것 대입하면 정리 가능.

$$\vec{\nabla} \cdot (\rho \langle v_i v_j \rangle) = \vec{\nabla} \cdot \left\{ \rho \langle (v_i - u_i)(v_j - u_j) \rangle + u_i u_j \rho \right\} = u_i u_j$$

$\equiv P_{ij}$ (Pressure tensor)

now, f.v. $v_i = x, y, z$, 이 식을 Vector form으로 정리하면

$$\frac{d}{dt} (\rho \vec{u}) + \vec{\nabla} \cdot \vec{P}_{ij} + \vec{\nabla} \cdot (\rho \vec{u} \vec{u}) = \frac{\rho}{m} \vec{F}$$

$$= \vec{u} (\nabla \rho) \cdot \vec{u} + \rho (\vec{u} \cdot \vec{\nabla}) \vec{u} + \rho (\vec{\nabla} \cdot \vec{u}) \vec{u}$$

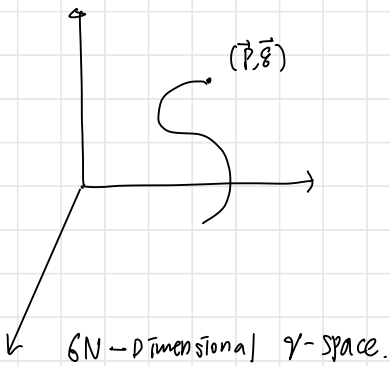
$$\vec{u} \cdot \left(\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0 \right)$$

$$\therefore \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = \frac{\vec{F}}{m} - \frac{\vec{\nabla} \cdot \vec{P}_{ij}}{\rho}$$

... Euler equation

$\Rightarrow$ 아직은 특별한 결과 χ 결국 f 를 알아야 한다... (perturbative method, hard to deal)

(*) Summary N particle system



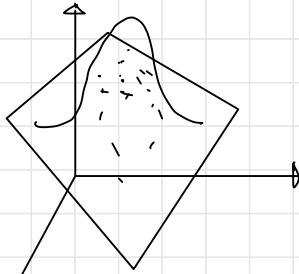
$$\Rightarrow \dot{q}_i = \frac{\partial H}{\partial p_i}, \quad \dot{p}_i = - \frac{\partial H}{\partial q_i}$$

Relation: "Kinetic Theory"
in 19th.

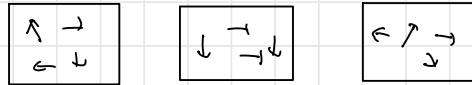
A Few thermodynamic variables ($E, T, N, V, P, \dots$)
via S, W, Q .

IV. Foundation of 'Equilibrium' Statistical Mechanics

1. Statistical Ensemble



• System Macrostate $M(E, V, N)$



3-6N mapping.

Different microstate configuration, same M-State.

• Statistical (Gibbs) Ensemble

⇒ A collection of a large number of copies of identical systems (Each constructed to have the given M-State)

• $\rho(\vec{p}, \vec{q}, t)$: phase space density.

⇒ $d\vec{p} d\vec{q} \rho$ = number of representative points in the volume elements (μ -states)

Remind) $\frac{d\rho}{dt} + \nabla \cdot (\rho \vec{v}) = 0$. (∇ = phase space operator)

$$\left[\frac{d\rho}{dt} + \sum_i \left(\frac{\partial \rho}{\partial g_i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial \rho}{\partial p_i} \frac{\partial \mathcal{H}}{\partial g_i} \right) \right] = \frac{d\rho}{dt} + \{ \rho, \mathcal{H} \} = 0 \quad \dots \text{Liouville thm.}$$

($\because \dot{p}_i = -\frac{\partial \mathcal{H}}{\partial g_i}, \dot{g}_i = +\frac{\partial \mathcal{H}}{\partial p_i}$)

$$= \frac{d\rho}{dt}$$

2. Statistical Postulate

• Consider a physical quantity $\mathcal{O}(\vec{p}, \vec{q}) \rightarrow$ physical meaningful : average.

$$\langle \mathcal{O} \rangle = \int d\vec{p} d\vec{q} \rho(\vec{p}, \vec{q}, t) \mathcal{O}(\vec{p}, \vec{q}), \quad \frac{d\langle \mathcal{O} \rangle}{dt} = \int d\vec{p} d\vec{q} \left(\frac{d\rho}{dt} \right) \mathcal{O}(\vec{p}, \vec{q}) = - \{ \rho, \mathcal{H} \}$$

$$\frac{d\langle \mathcal{O} \rangle}{dt} = - \int d\vec{p} d\vec{q} \mathcal{O} \cdot \sum_{i=1} \left(\frac{\partial \rho}{\partial g_i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial \rho}{\partial p_i} \frac{\partial \mathcal{H}}{\partial g_i} \right)$$

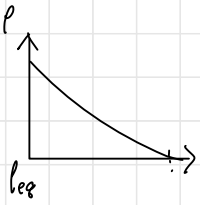
부호반전
omit Σ .

$$\begin{aligned} & \rightarrow - \mathcal{O} \cdot \rho \cdot \frac{\partial \mathcal{H}}{\partial p_i} \Big|_S + \int d\vec{p} d\vec{q} \cdot \rho \cdot \frac{\partial \mathcal{O}}{\partial g_i} \frac{\partial \mathcal{H}}{\partial p_i} + \int d\vec{p} d\vec{q} \cdot \rho \cdot \mathcal{O} \cdot \frac{\partial^2 \mathcal{H}}{\partial g_i \partial p_i} \\ & + \mathcal{O} \cdot \rho \cdot \frac{\partial \mathcal{H}}{\partial g_i} \Big|_S - \int d\vec{p} d\vec{q} \cdot \rho \cdot \frac{\partial \mathcal{O}}{\partial p_i} \frac{\partial \mathcal{H}}{\partial g_i} - \int d\vec{p} d\vec{q} \cdot \rho \cdot \mathcal{O} \cdot \frac{\partial^2 \mathcal{H}}{\partial p_i \partial g_i} \end{aligned}$$

$\xrightarrow{S \rightarrow \infty} 0$

$$\therefore \frac{d\langle \mathcal{O} \rangle}{dt} = \langle \{ \mathcal{O}, \mathcal{H} \} \rangle \quad \dots \text{time dependence of } \langle \mathcal{O} \rangle = \int d\vec{p} d\vec{q} \cdot \rho \cdot \{ \mathcal{O}, \mathcal{H} \}$$

• Now, for equilibrium condition. $\Rightarrow \frac{d\langle \theta \rangle}{dt} = 0$.



(*) Equilibrium (Stationary) Ensemble.

$$\frac{d\langle \theta \rangle}{dt} = 0 \rightarrow \left(\frac{dP}{dt} \right) = 0 \quad \left(\text{not } \frac{dP}{dt}, \text{ this is always 0 for incompressible } P \right)$$

$$\xrightarrow{\text{Liouville}} \{P, H\} = 0$$

→ These are not rigorous, but physically acceptable.

→ One possible way of satisfying this: To assume $P = P_{eg}(H(\vec{p}, \vec{q}))$

The fundamental assumption of statistical mechanics (Postulate of a equal priori probability)

In thermodynamic equilibrium, an isolated system is equally likely to be any state

satisfying the given macroscopic conditions $\rightarrow$ $\vec{p}$ 및 $\vec{q}$ X, E (or H) invariant

$\Rightarrow P_{eg}$ is fixed

$\Rightarrow P_{eg}$ is constant on
constant energy (M state)
surface

3. Ergodic Hypothesis (Not yet proved rigorously still now)

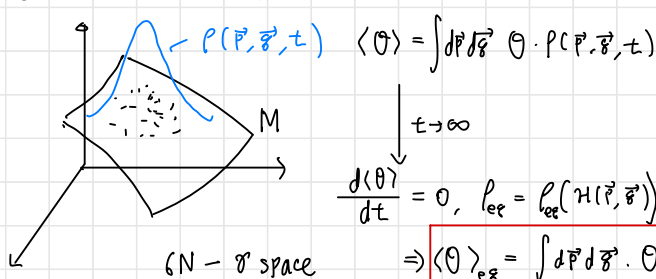
• In statistic, average value (for physical quantity) is meaningful, important.

$\Rightarrow$ 이 값은, 정역대르리엔 수 많은 sample 중비, 특정해야 얻을 수 있다. (Ensemble average)

$\Rightarrow$ but, 실제 실험에서는 Temporal average를 특정. 이를 사용. 태알까?

• Two different averages

① Ensemble average



② Temporal average

$$\bar{\theta} = \frac{1}{T} \int_0^T dt \cdot \theta(\vec{p}, \vec{q}, t)$$

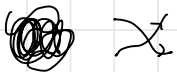
$$\downarrow T \rightarrow \infty$$

$$\bar{\theta} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T dt \cdot \theta(\vec{p}, \vec{q}, t)$$

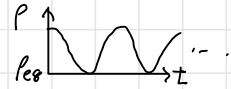
??

• Ergodic hypothesis

after a sufficiently long time, Γ -trajectory passes through every point in the allowed Γ -space with equal number of time.

cf)  quasi-ergodic

Spanning time $\ll$ relaxation time scale. is it ok?

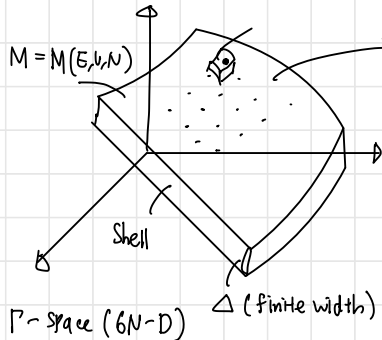


4. Microcanonical Ensemble.

$$M = (E, V, N)$$

- Consider an isolated system (No exchange of Q, W, ...) Based on fundamental assumption

→ Energy Conservation: $P = P_{\text{eq}} = \text{const.}$ → equally ~~likely~~ representative points on M . (equally likely)



$$P(\vec{p}, \vec{q}) = \frac{1}{\Omega(E)} \delta[H(\vec{p}, \vec{q}) - E]$$

($\Omega(E)$ = Surface area of hypersurface)

→ hard to evaluate Ω ?

⇒ Allow uncertainty Δ in energy.

$$\rho = \begin{cases} \frac{1}{\Omega(E)} \cdot (E \leq H \leq E + \Delta) \\ 0 & \text{otherwise.} \end{cases}$$

• Let's define $\begin{cases} \Gamma \equiv \text{Volume of the shell} \\ \Sigma \equiv \text{Volume of the enclosed volume} \end{cases}$

$$\text{then, } \Gamma = \Sigma(E + \Delta) - \Sigma(E) \cong \frac{\partial \Sigma}{\partial E} \cdot \Delta = \Omega(E).$$

$$= \int_{E \leq H \leq E + \Delta} d\vec{p} d\vec{q} = \int_{E < H} d\vec{p} d\vec{q}$$



(Quantum Mechanical) $\Delta p \Delta q \gtrsim \hbar$. $(\Delta p \Delta q)^{3N} \gtrsim \hbar^{3N}$

$$\Rightarrow P(\vec{\mu}) = \begin{cases} \frac{1}{\Omega(E)} & \text{if } E \leq H \leq E + \Delta \\ 0 & \text{otherwise} \end{cases}$$

$$(P(\vec{p}, \vec{q}) = P(\vec{\mu}))$$

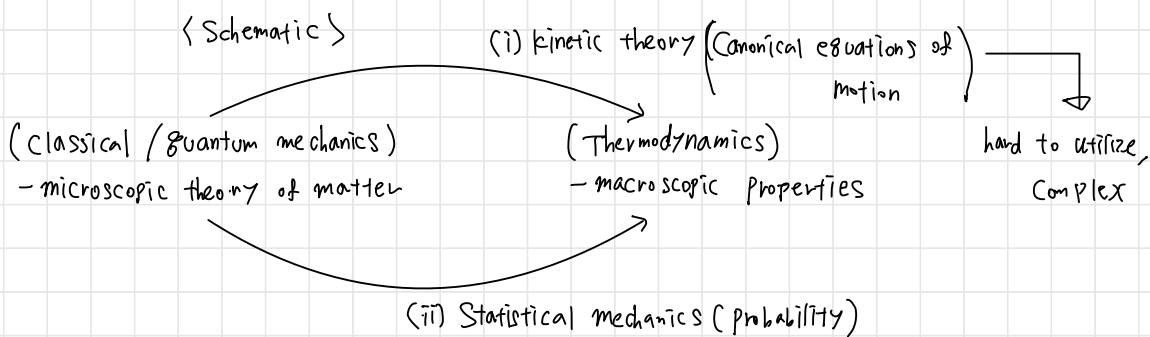
$$\therefore \Omega(E, V, N) \equiv \frac{\Gamma(E, V, N)}{\Gamma_0} \rightarrow \text{unit volume}$$

⇒ number of different microscopic states (that we can distinguish)

$$\left(\int d\vec{p} d\vec{q} P(\vec{p}, \vec{q}) = 1 \right)$$

5. Entropy

- Statistical Mechanics: A Probabilistic Approach to equilibrium



(*) Entropy

$$\begin{aligned}
 S(E, V, N) &= -k_B \cdot \langle \ln P(\vec{\mu}) \rangle = -k_B \cdot \sum_{\vec{\mu}} P(\vec{\mu}) \cdot \ln P(\vec{\mu}) \quad \left(P(\vec{\mu}) = \frac{1}{\Omega(E)} \right) \\
 &= +k_B \cdot \sum \frac{1}{\Omega} \cdot \ln \Omega \\
 &= k_B \cdot \ln \Omega(E, V, N)
 \end{aligned}$$

$\therefore S(E, V, N) = k_B \cdot \ln \Omega(E, V, N)$

(*) Zeroth Law (Power of Entropy)

- When two systems are in thermal equilibrium, the temperatures of the two systems are **the same**.

$(V, N) \rightarrow \text{fixed. only allowed to exchange } E.$

$$\begin{cases} \vec{\mu} = \vec{\mu}_1 \otimes \vec{\mu}_2 \\ E = E_1 + E_2 \end{cases}$$

$$P(E) = \begin{cases} \frac{1}{\Omega(E)} \\ 0 \end{cases}$$

$H_1 + H_2 = E \dots$
otherwise

$$\begin{aligned}
 \Rightarrow \Omega(E) &= \int dE_1 dE_2 \cdot \Omega_1(E_1) \Omega_2(E_2) \delta(E - E_1 - E_2) \\
 &= \int dE_1 \cdot \Omega_1(E_1) \Omega_2(E - E_1) = \int dE_1 \cdot \exp \left[\frac{1}{k_B} \cdot \left(S_1(E_1) + S_2(E - E_1) \right) \right]
 \end{aligned}$$

(Approx) $F = \sum_{i=1}^M F_i$, $F_i \sim O(e^{N^p})$, $M \sim N^p$, $F_{\max} = \max(F_i)$

$$F_{\max} \leq F \leq M \cdot F_{\max}$$

$$\lim_{N \rightarrow \infty} \left(\frac{1}{N} \ln F_{\max} \leq \frac{1}{N} \ln F \leq \frac{1}{N} \ln F_{\max} + \frac{1}{N} \ln M \right) \rightarrow F \rightarrow F_{\max}$$

$$\Omega(E) \simeq e^{\frac{1}{k_B} (S_1(E_1^*) + S_2(E_2^*))} \quad S(E) = k_B \ln \Omega = S_1(E_1^*) + S_2(E_2^*)$$

$$\delta(\Omega_1(E_1) \Omega_2(E_2)) = 0.$$

$$\Omega_2 \cdot \frac{\partial \Omega_1}{\partial E_1} + \Omega_1 \cdot \frac{\partial \Omega_2}{\partial E_1} = 0. \quad \frac{1}{\Omega_1} \frac{\partial \Omega_1}{\partial E_1} + \frac{1}{\Omega_2} \frac{\partial \Omega_2}{\partial E_1} = 0.$$

$$\Rightarrow \left. \frac{\partial}{\partial E_1} \ln \Omega_1 \right|_{E_1^*} = \left. \frac{\partial}{\partial E_2} \ln \Omega_2 \right|_{E_2^*}$$

$$\left. \frac{\partial S_1}{\partial E_1} \right|_{E_1^*} + \left. \frac{\partial S_2}{\partial E_1} \right|_{E_1^*} = 0.$$

$$\therefore \left. \frac{\partial S_1}{\partial E_1} \right|_{E_1^*} = \left. \frac{\partial S_2}{\partial E_2} \right|_{E_2^*} \longrightarrow \frac{1}{T_1} = \frac{1}{T_2}.$$

$$\uparrow$$

$$\left(\frac{\partial S}{\partial E} \right) = \frac{1}{T}$$